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# Compatibility of change of measures

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## (Joint work with Yi Shen, Bin Wang and Ruodu Wang)

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- 2 Necessary condition
- 3 Sufficient condition
- 4 Stochastic processes

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- Change of measure: distribution  $\Rightarrow$  another one
- *How much* would the distribution change?

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- Change of measure: distribution  $\Rightarrow$  another one
- *How much* would the distribution change?
- Given several probability measures Q<sub>1</sub>,..., Q<sub>n</sub> and distribution measures F<sub>1</sub>,..., F<sub>n</sub>, does there exist a random variable X : Ω → ℝ such that X has distribution F<sub>i</sub> under Q<sub>i</sub> for i = 1,...,n?

- $(\Omega, \mathcal{A})$ : measurable space
- $\mathcal{F}$ : the set of distributions on  $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ ,
- $\mathcal{P}$ : the set of probability measures on  $(\Omega, \mathcal{A})$
- $D_{\mathrm{KL}}(\cdot || \cdot)$ : Kullback-Leibler divergence between probability measures

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# Definition (Compatibility)

 $(F_1, \ldots, F_n) \in \mathcal{F}^n$  and  $(Q_1, \ldots, Q_n) \in \mathcal{P}^n$  are *compatible* if there exists a random variable X in  $(\Omega, \mathcal{A})$  such that for each  $i = 1, \ldots, n$ , the distribution of X under  $Q_i$  is  $F_i$ .

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## Definition (Almost compatibility)

 $(F_1, \ldots, F_n) \in \mathcal{F}^n$  and  $(Q_1, \ldots, Q_n) \in \mathcal{P}^n$  are *almost compatible*, if for any  $\epsilon > 0$ , there exists a random variable  $X_{\epsilon}$  in  $(\Omega, \mathcal{A})$  such that for each  $i = 1, \ldots, n$ , the distribution of  $X_{\epsilon}$  under  $Q_i$ , denoted by  $F_{i,\epsilon}$ , is absolutely continuous with respect to  $F_i$ , and satisfies  $D_{\mathrm{KL}}(F_{i,\epsilon}||F_i) < \epsilon$ .

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## Definition (Convex order)

Let  $(\Omega_1, \mathcal{A}_1, P_1)$  and  $(\Omega_2, \mathcal{A}_2, P_2)$  be two probability spaces. For  $\mathbf{X} \in L_1^n(\Omega_1, \mathcal{A}_1, P_1)$  and  $\mathbf{Y} \in L_1^n(\Omega_2, \mathcal{A}_2, P_2)$ , we write  $\mathbf{X}|_{P_1} \prec_{\mathrm{cx}} \mathbf{Y}|_{P_2}$ , if  $\mathbb{E}^{P_1}[f(\mathbf{X})] \leq \mathbb{E}^{P_2}[f(\mathbf{Y})]$  for all convex functions  $f : \mathbb{R}^n \to \mathbb{R}$ , provided that both expectations exist.

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## Lemma ()

For  $\mathbf{X} \in L_1^n(\Omega_1, \mathcal{A}_1, P_1)$  and  $\mathbf{Y} \in L_1^n(\Omega_2, \mathcal{A}_2, P_2)$ ,  $\mathbf{X}|_{P_1} \prec_{cx} \mathbf{Y}|_{P_2}$  if and only if there exist a probability space  $(\Omega_3, \mathcal{A}_3, P_3)$  and  $\mathbf{X}', \mathbf{Y}' \in L_1^n(\Omega_3, \mathcal{A}_3, P_3)$  such that  $\mathbf{X}'|_{P_3} \stackrel{d}{=} \mathbf{X}|_{P_1}, \mathbf{Y}'|_{P_3} \stackrel{d}{=} \mathbf{Y}|_{P_2}$ , and  $\mathbb{E}^{P_3}[\mathbf{Y}'|\mathbf{X}'] = \mathbf{X}'$ .

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# • $Q_1, \ldots, Q_n$ identical $\Rightarrow F_1, \ldots, F_n$ identical

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- $Q_1, \ldots, Q_n$  identical  $\Rightarrow F_1, \ldots, F_n$  identical
- $Q_1, \ldots, Q_n$  mutually singular  $\Rightarrow F_1, \ldots, F_n$  arbitrary.

Introduction	Necessary condition	Sufficient condition	Stochastic processes	

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Conclution:  $Q_1, \ldots, Q_n$  are more *variabile* than  $F_1, \ldots, F_n$ 





3 Sufficient condition



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# Necessary condition for compatibility

### Lemma

Let 
$$(F_1, ..., F_n) \in \mathcal{F}^n$$
 and  $(Q_1, ..., Q_n) \in \mathcal{P}^n$ . If  $(F_1, ..., F_n)$  and  $(Q_1, ..., Q_n)$  are compatible, then  
(i) For any  $F \in \mathcal{F}$ ,  $F_i \ll F$  for  $i = 1, ..., n$ , there exists  $Q \in \mathcal{P}$ ,  $Q_i \ll Q$  for  $i = 1, ..., n$ , such that

$$\left. \left( \frac{\mathrm{d}F_1}{\mathrm{d}F}, \dots, \frac{\mathrm{d}F_n}{\mathrm{d}F} \right) \right|_F \prec_{\mathrm{cx}} \left( \frac{\mathrm{d}Q_1}{\mathrm{d}Q}, \dots, \frac{\mathrm{d}Q_n}{\mathrm{d}Q} \right) \right|_Q.$$
(1)

(ii) For any  $Q \in \mathcal{P}$ ,  $Q_i \ll Q$  for i = 1, ..., n, there exists  $F \in \mathcal{F}$ ,  $F_i \ll F$  for i = 1, ..., n, such that (1) holds.

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- $(\Omega, \mathcal{A}) = ([0, 1], \mathcal{B}([0, 1]))$
- *Q*<sub>1</sub>: probability point mass at 0
- *Q*<sub>2</sub>: probability point mass at 1
- $F_1$  and  $F_2$ : uniform distribution on [0, 1]

There exists  $Q = \frac{1}{2}(Q_1 + Q_2)$  and  $F = F_1$  such that

$$\left(\frac{\mathrm{d}F_1}{\mathrm{d}F},\frac{\mathrm{d}F_2}{\mathrm{d}F}\right)\Big|_F \prec_{\mathrm{cx}} \left(\frac{\mathrm{d}Q_1}{\mathrm{d}Q},\frac{\mathrm{d}Q_2}{\mathrm{d}Q}\right)\Big|_Q,$$

but  $(Q_1, Q_2)$  and  $(F_1, F_2)$  are not compatible.

#### Theorem

Suppose that  $(Q_1, \ldots, Q_n) \in \mathcal{P}^n$ ,  $(F_1, \ldots, F_n) \in \mathcal{F}^n$  and  $(\Omega, \mathcal{A}, Q_i)$ is atomless for each  $i = 1, \ldots, n$ .  $(Q_1, \ldots, Q_n)$  and  $(F_1, \ldots, F_n)$  are almost compatible if and only if there exist  $F \in \mathcal{F}$  and  $Q \in \mathcal{P}$ , such that  $F_i \ll F$ ,  $Q_i \ll Q$  for i = 1, ..., n, and

$$\left(\frac{\mathrm{d}F_1}{\mathrm{d}F},\ldots,\frac{\mathrm{d}F_n}{\mathrm{d}F}\right)\Big|_F \prec_{\mathrm{cx}} \left(\frac{\mathrm{d}Q_1}{\mathrm{d}Q},\ldots,\frac{\mathrm{d}Q_n}{\mathrm{d}Q}\right)\Big|_Q.$$
 (2)

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Introduction







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 $(1), ([0, 1], \mathcal{D}(\mathbb{T}))$ 

• 
$$(\Omega, \mathcal{A})$$
:  $([0, 1], \mathcal{B}(\mathbb{R}))$   
•  $Q_2 = \lambda, \frac{dQ_1}{dQ_2}(t) = 2t, t \in [0, 1]$   
•  $F_2 = \lambda$  on  $[0, 1], \frac{dF_1}{dF_2}(x) = |4x - 2|, x \in [0, 1]$   
 $\Rightarrow$   
•  $\frac{dQ_1}{dQ_2}$  uniform on  $[0, 2]$  under  $Q_2$   
•  $\frac{dF_1}{dF_2}$  uniform on  $[0, 2]$  under  $F_2$   
Taking  $Q = Q_2$  and  $F = F_2$ ,

$$\left(\frac{\mathrm{d}F_1}{\mathrm{d}F},\frac{\mathrm{d}F_2}{\mathrm{d}F}\right)\Big|_F \stackrel{\mathrm{d}}{=} \left(\frac{\mathrm{d}Q_1}{\mathrm{d}Q},\frac{\mathrm{d}Q_2}{\mathrm{d}Q}\right)\Big|_Q.$$

However,  $(Q_1, Q_2)$  and  $(F_1, F_2)$  are not compatible.

Introduction	Necessary condition	Sufficient condition	Stochastic processes
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#### Theorem

Let  $(F_1, \ldots, F_n) \in \mathcal{F}^n$  and  $(Q_1, \ldots, Q_n) \in \mathcal{P}^n$ . If  $(F_1, \ldots, F_n)$  and  $(Q_1, \ldots, Q_n)$  are compatible, then there exist  $F \in \mathcal{F}$  and  $Q \in \mathcal{P}$  such that  $F_i \ll F$ ,  $Q_i \ll Q$  for i = 1, ..., n, and

$$\left(\frac{\mathrm{d}F_1}{\mathrm{d}F},\ldots,\frac{\mathrm{d}F_n}{\mathrm{d}F}\right)\Big|_F \prec_{\mathrm{cx}} \left(\frac{\mathrm{d}Q_1}{\mathrm{d}Q},\ldots,\frac{\mathrm{d}Q_n}{\mathrm{d}Q}\right)\Big|_Q.$$
 (3)

Conversely, assume there exist  $F \in \mathcal{F}$  and  $Q \in \mathcal{P}$  such that  $F_i \ll F$ ,  $Q_i \ll Q$  for i = 1, ..., n, and (3) holds. If in addition, there exists a continuous random variable defined on  $(\Omega, \mathcal{A}, Q)$ , independent of  $\left(\frac{dQ_1}{dQ}, \ldots, \frac{dQ_n}{dQ}\right)$ , then  $(F_1, \ldots, F_n)$  and  $(Q_1, \ldots, Q_n)$  are compatible.



- 2 Necessary condition
- 3 Sufficient condition



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- *I*: a closed interval
- C(I): the space of all continuous functions defined on I
- $C_I$ : the cylindrical  $\sigma$ -field
- $G_I$ : the set of probability measures on  $(C(I), C_I)$

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## Definition

For a closed interval  $I \subset \mathbb{R}$ ,  $(G_1, \ldots, G_n) \in \mathcal{G}_I^n$  and  $(Q_1, \ldots, Q_n) \in \mathcal{P}^n$  are *compatible* if there exists a continuous stochastic process  $X = \{X(t)\}_{t \in I}$  defined on  $(\Omega, \mathcal{A})$  such that for each  $i = 1, \ldots, n$ , the distribution of X under  $Q_i$  is  $G_i$ .

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#### Theorem

Assume there exist  $G \in \mathcal{G}_I$  and  $Q \in \mathcal{P}$  such that  $G_i \ll G$ ,  $Q_i \ll Q$  for i = 1, ..., n, and

$$\left(\frac{\mathrm{d}G_1}{\mathrm{d}G},\ldots,\frac{\mathrm{d}G_n}{\mathrm{d}G}\right)\Big|_F\prec_{\mathrm{cx}} \left(\frac{\mathrm{d}Q_1}{\mathrm{d}Q},\ldots,\frac{\mathrm{d}Q_n}{\mathrm{d}Q}\right)\Big|_Q$$

holds. If in addition, there exists a continuous random variable defined on  $(\Omega, \mathcal{A}, Q)$  independent of  $\left(\frac{dQ_1}{dQ}, \ldots, \frac{dQ_n}{dQ}\right)$ , then  $(G_1, \ldots, G_n)$  and  $(Q_1, \ldots, Q_n)$  are compatible.

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Q : How much can the drift of a Brownian motion change by a change of measure in the classic Girsanov Theorem.

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- *P*: a probability measure
- $B = \{B_t\}_{t \in [0,T]}$ : *P*-standard Brownian motion

The Girsanov Theorem says that, by defining  $Q_{\theta}$  via

$$\frac{\mathrm{d}Q_{\theta}}{\mathrm{d}P} = e^{\theta B_T - \frac{\theta^2}{2}T},\tag{4}$$

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 $\tilde{B}(t) = B(t) - \theta t$  is a Brownian motion under  $Q_{\theta}$ .

# Q1 : Does there exist a *P*-standard Brownian motion which has a fixed drift term $\mu \in \mathbb{R}$ under $Q_{\theta}$ ?



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- Q1 : Does there exist a *P*-standard Brownian motion which has a fixed drift term  $\mu \in \mathbb{R}$  under  $Q_{\theta}$  ?
  - G<sub>μ</sub> ∈ G<sub>[0,T]</sub>: distribution measure of a BM on [0, T] with a constant drift term μ ∈ ℝ and volatility 1
  - $(G_0, G_\mu)$  and  $(P, Q_\theta)$  are compatible ?

ntroduction	Necessary condition	Sufficient condition	Stochastic processes

- Q1 : Does there exist a *P*-standard Brownian motion which has a fixed drift term  $\mu \in \mathbb{R}$  under  $Q_{\theta}$  ?
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  - $(G_0, G_\mu)$  and  $(P, Q_\theta)$  are compatible ?

## Proposition

Let  $P \in \mathcal{P}$  and  $B = \{B_t\}_{t \in [0,T]}$  be a P-standard Brownian motion. Using the above notation, for  $\mu, \theta \in \mathbb{R}$ ,  $(P, Q_{\theta})$  and  $(G_0, G_{\mu})$  are compatible if and only if  $|\mu| \leq |\theta|$ .