

# Quasiconvex Plane Domains

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9:00AM

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AMS Special Session

*Analysis and Potential Theory on Metric Spaces*



## 1 Introduction

- Definitions & Examples
- Complements of Sectors
- Euclidean Domains

## 2 Plane Domains

- Necessary Conditions
- Sufficient Conditions
- Finitely Connected Domains

## 3 The Main Example

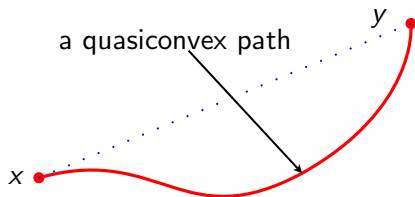
- The Result
- A Picture Proof

# Outline

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# Definition of QuasiConvexity

A metric space is quasiconvex iff it is bilipschitz equivalent to some length space; each pair of points can be joined by a rectifiable path whose length is comparable to the distance between its endpoints.



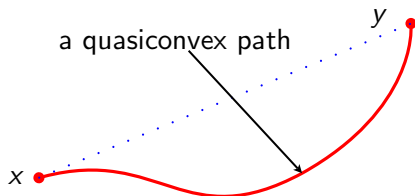
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### Definition

A metric space is  $c$ -*quasiconvex* if each pair of points  $x, y$  can be joined by a rectifiable path  $\gamma$  satisfying

$$l(\gamma) \leq c |x - y|.$$



# Examples of QuasiConvex Spaces

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- doubling metric measure spaces supporting  $(1, p)$ -Poincaré inequality
- Sobolev extension domains in Euclidean space
- a John disk is a quasidisk if and only if it is quasiconvex

# Basic Example

Given  $0 < \theta \leq \pi/2$ ,  $C_\theta = \{z \in \mathbb{C} : |\text{Arg}(z)| \leq \theta\}$  is closed convex sector and the concave sector  $D_\theta = \mathbb{R}^2 \setminus C_\theta$  is  $\text{csc } \theta$ -quasiconvex.

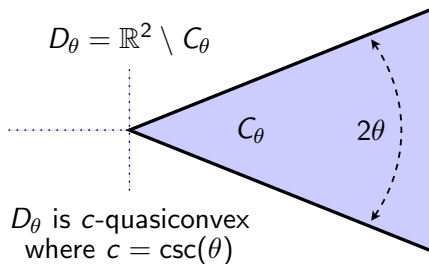


Figure: A concave sector is quasiconvex.

## Extremal Examples

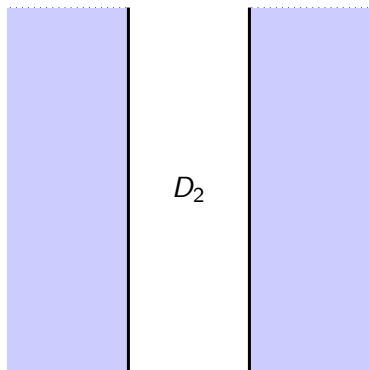
$\theta = \pi/n$ ,  $\zeta_k = e^{2ki\theta}$  ( $1 \leq k \leq n$ ),  $C_k = \zeta_k C_\theta + \zeta_k$  (closed convex sectors obtained by rotating  $C_\theta$  and then translating)  $\implies$

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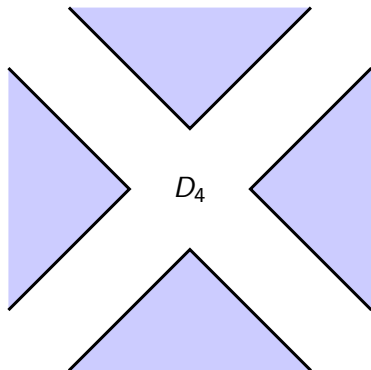
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A convex domain



A  $\sqrt{2}$ -quasiconvex domain

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## Fact

*Suppose  $A \subset \mathbb{R}^n$  is closed and each projection onto a coordinate  $(n - 1)$ -plane has  $(n - 1)$ -measure zero. Then  $A^c$  is quasiconvex.*

▶ See Proof

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Thus  $A^c$  is quasiconvex if

- $\dim_{\mathcal{H}} A < n - 1$ , or  $A$  itself has  $(n - 1)$ -measure zero, or
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# Notation

Call  $C \subset \mathbb{R}^2$  a *Jordan curve* if it is a Jordan loop or a Jordan line:

a *Jordan loop* is homeomorphic image of a round circle,

so always compact;

a *Jordan line* is image of injective path  $\mathbb{R} \xrightarrow{\lambda} \mathbb{R}^2$  with

$\lambda(t) \rightarrow \infty$  (in  $\hat{\mathbb{R}}^2$ ) as  $t \rightarrow \pm\infty$ .

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A *Jordan curve domain* is an open connected plane region each of whose boundary components is either a single point or a Jordan curve.

# Examples of Jordan Curve Domains

- Every Jordan disk (simply connected plane domain bounded by a single Jordan curve) is a Jordan curve domain.

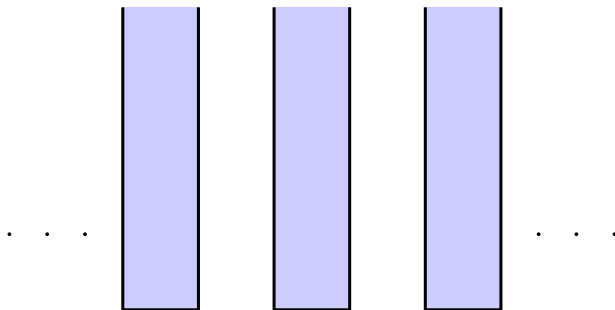
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- There are simply connected Jordan curve domains having infinitely many boundary components.

# Examples of Jordan Curve Domains



A simply connected Jordan curve domain

Figure: Infinitely many unbounded boundary components

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Can weaken hypothesis *finitely many boundary components* if instead require that all boundary points be joinable by quasiconvex paths.

# QuasiConvexity Characterization

## Corollary

A finitely connected  $D \subsetneq \mathbb{R}^2$  is  $c$ -quasiconvex iff

- (i)  $D$  is a Jordan curve domain, and
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$\forall M > 0, \exists$  closed totally disconn  $A \subset \mathbb{R}^2$  with  $-1, 1 \in A^c$  and st each rectifiable path  $\gamma$  joining  $-1, 1$  in  $A^c$  has  $\ell(\gamma) \geq M$ .

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Construct  $A := \bigcap_i E_i$  where  $E_1 \supset E_2 \supset \dots$  closed,  $E_i = \bigcup_j F_{ij}$ , with  $F_{ij}$  nested compact sets satisfying

$$\lim_{i \rightarrow \infty} \sup_j \text{diam } F_{ij} = 0.$$

Thus  $A$  closed and totally disconnected.

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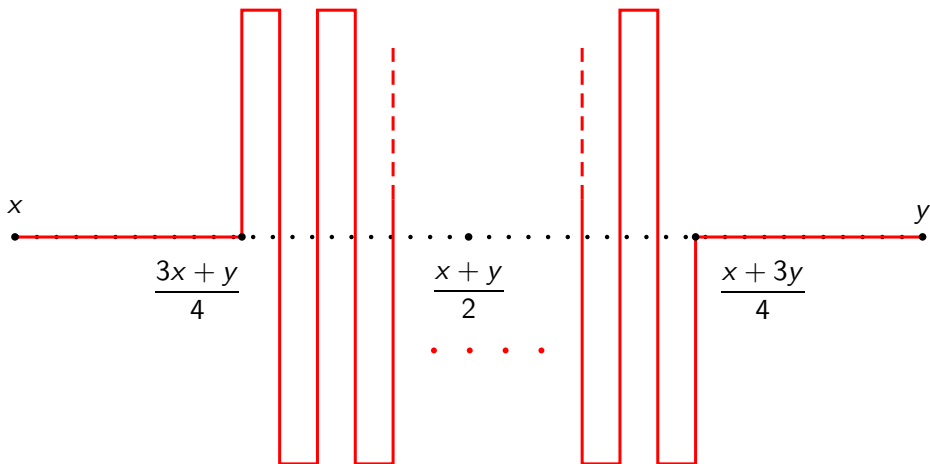
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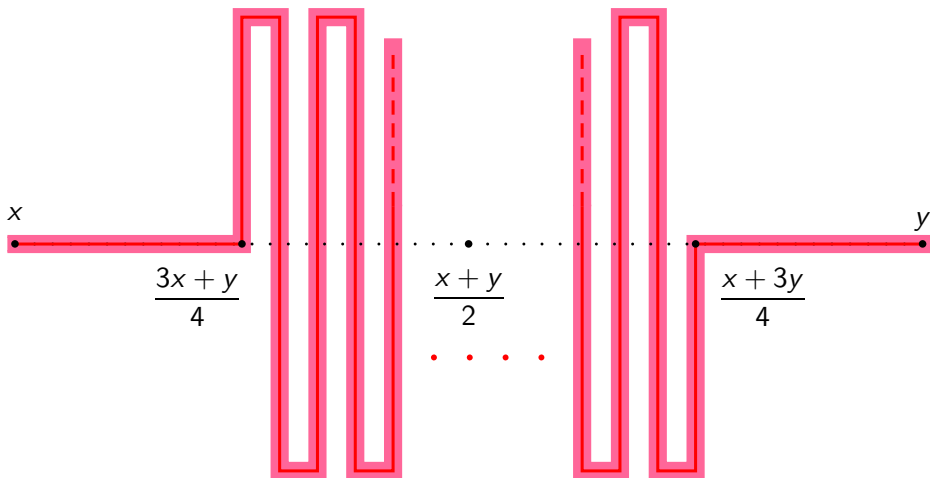
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Gotta describe sets  $F_{ij}$ .

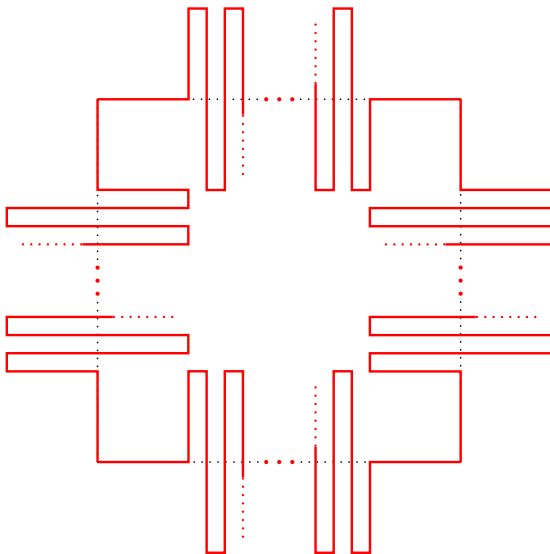
# $[x, y] \rightsquigarrow$ Long Broken Line Segment



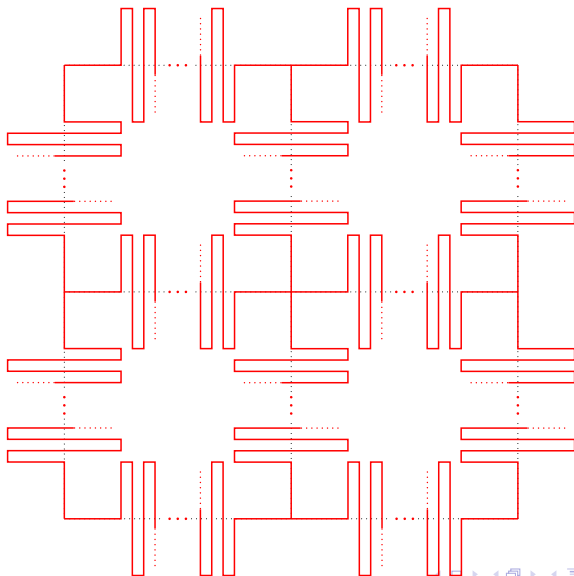
# An Irrigation Canal Based on $[x, y]$

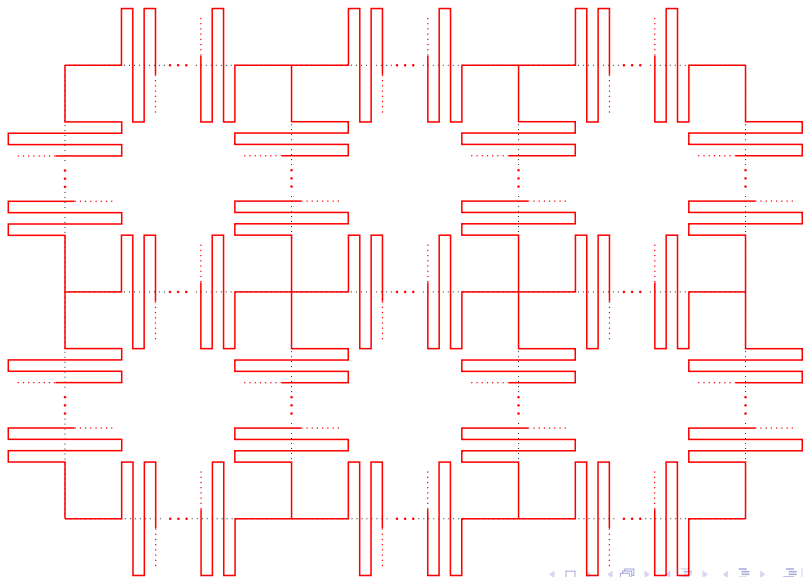


# Irrigating a Square

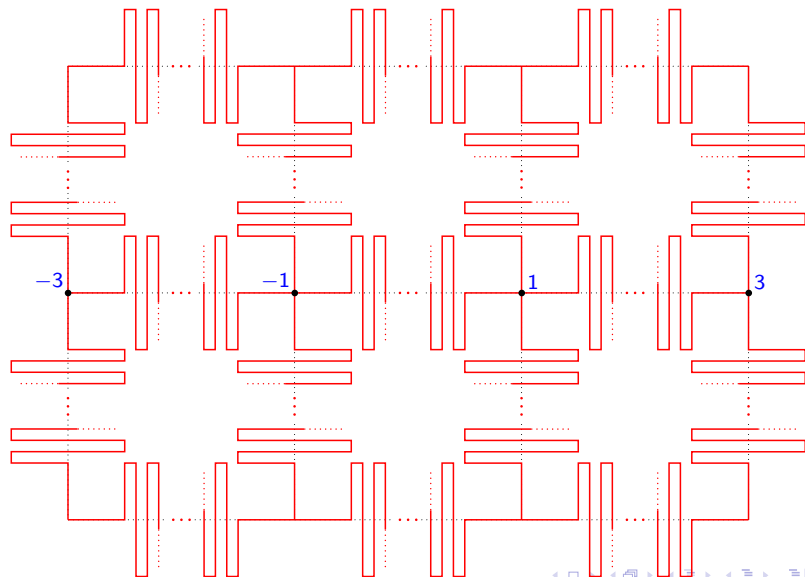


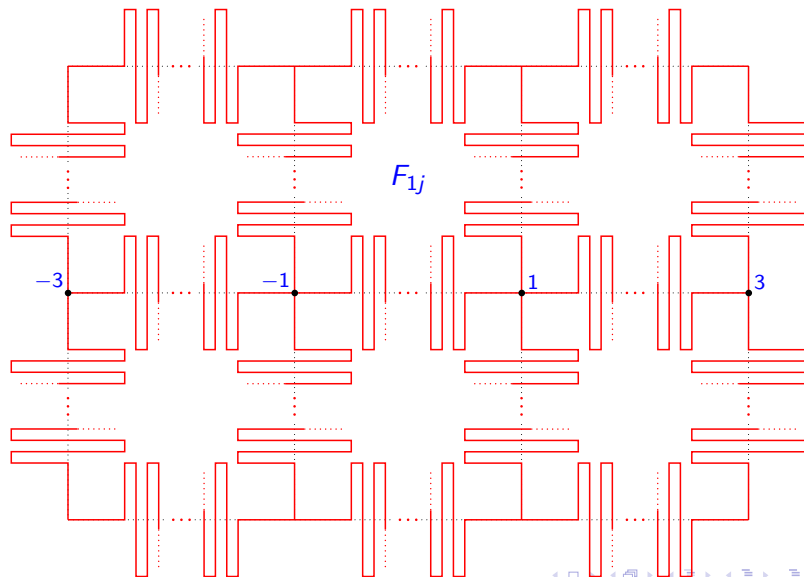
# Irrigating a Bunch of Squares



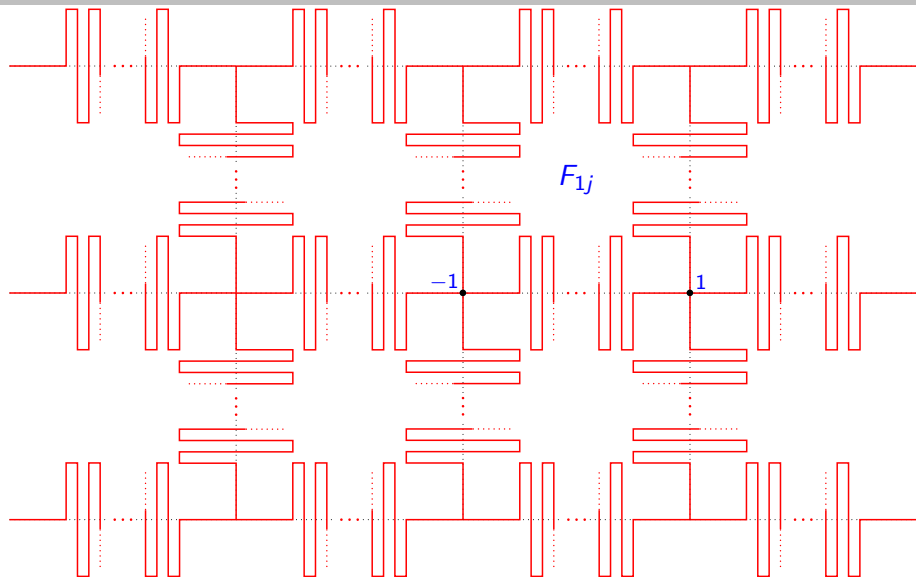
Irrigating Squares and The First Generation of  $F_{ij}$ 



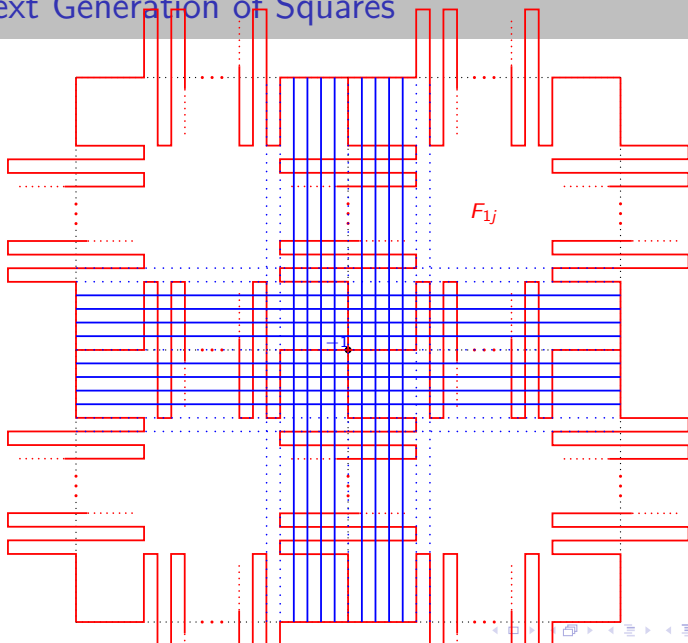
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## Taking a Closer Look



# The Next Generation of Squares





# Summary

- Compact totally disconnected sets need not have quasiconvex complements.

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- Although OK in many cases (sets with small dimension or nowhere dense projections).
- Are there similar examples in  $\mathbb{R}^3$ ? In  $\mathbb{R}^n$ ? (I guess so)
- Is there an example with Hausdorff dimension strictly less than  $n$ ?

# The End



## 4 Appendix

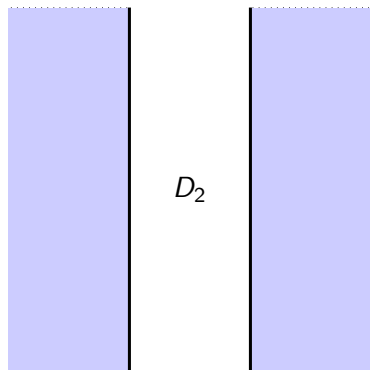
- Extremal Examples
- Proof of Theorem

# Outline

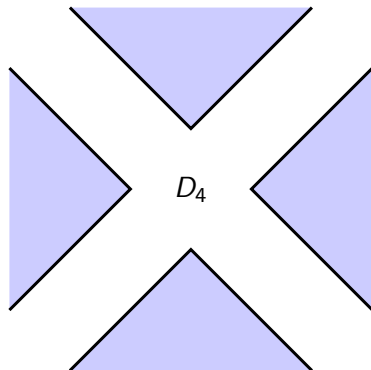
- 4 Appendix
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# Complements of Sectors

$\theta = \pi/n$ ,  $\zeta_k = e^{2ki\theta}$  ( $1 \leq k \leq n$ ),  $C_k = \zeta_k C_\theta + \zeta_k$  (closed convex sectors obtained by rotating  $C_\theta$  and then translating)  $\implies D_n = \mathbb{R}^2 \setminus \bigcup_{k=1}^n C_k$  is simply conn csc  $\theta$ -quasiconvex domain with  $n$  unbdd bdy cmpnts [Go Back](#)



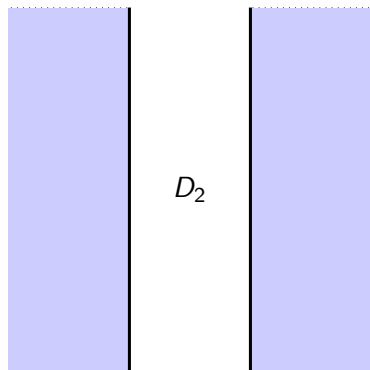
A convex domain



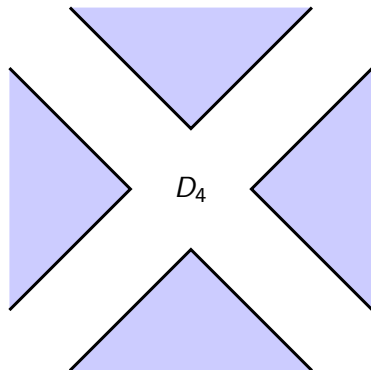
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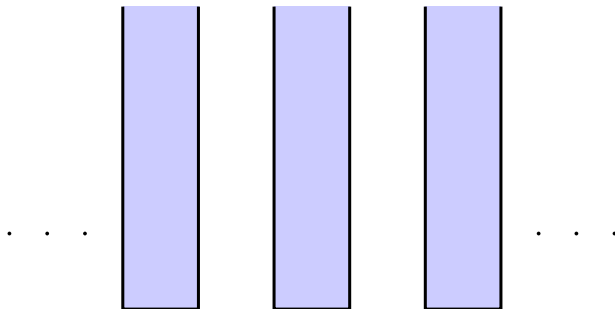


A convex domain



A  $\sqrt{2}$ -quasicvex domain

# Lots of Unbdd Boundary Components

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A simply connected Jordan curve domain

Figure: Infinitely many unbounded boundary components

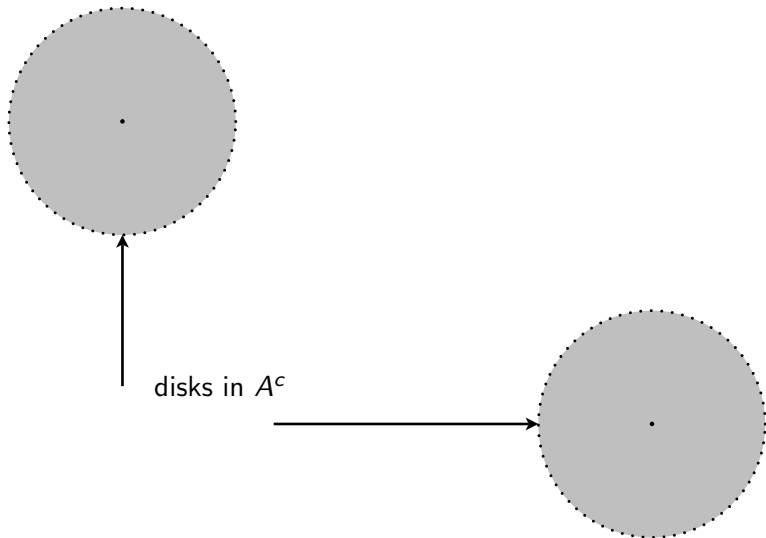
# Complement of Plane Set with Zero Measure Projections

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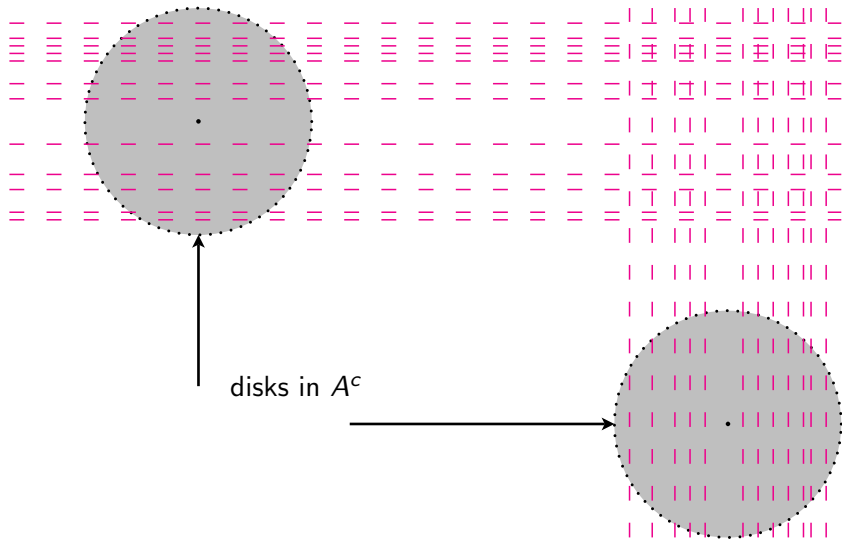
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# Complement of Plane Set with Zero Measure Projections



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# Complement of Plane Set with Zero Measure Projections

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