

Euclidean QuasiConvexity

Hrant Hakobyn¹ David A Herron²

¹SUNY at Stony Brook

²University of Cincinnati

9:00AM

16 March 2007

AMS Special Session

Complex Dynamics and Complex Function Theory



- 1 Introduction
 - Definitions & Examples
 - Euclidean Domains

- 2 Plane Domains
 - Necessary Conditions
 - Sufficient Conditions
 - Finitely Connected Domains

- 3 General Sufficient Conditions

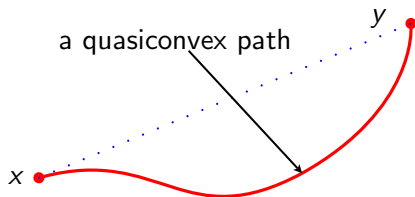
- 4 The Main Example
 - The Result
 - Picture Proof

Outline

- 1 Introduction
 - Definitions & Examples
 - Euclidean Domains
- 2 Plane Domains
 - Necessary Conditions
 - Sufficient Conditions
 - Finitely Connected Domains
- 3 General Sufficient Conditions
- 4 The Main Example
 - The Result
 - Picture Proof

Definition of QuasiConvexity

A metric space is quasiconvex iff it is bilipschitz equivalent to some length space; each pair of points can be joined by a rectifiable path whose length is comparable to the distance between its endpoints.



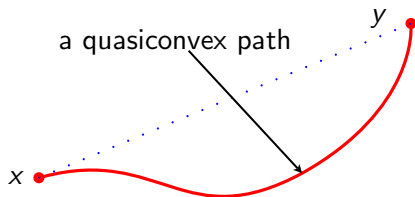
Definition of QuasiConvexity

A metric space is quasiconvex iff it is bilipschitz equivalent to some length space; each pair of points can be joined by a rectifiable path whose length is comparable to the distance between its endpoints.

Definition

A metric space is c -*quasiconvex* if each pair of points x, y can be joined by a rectifiable path γ satisfying

$$l(\gamma) \leq c |x - y|.$$



Examples of QuasiConvex Spaces

- upper regular Loewner spaces (this includes Carnot groups & certain Riemannian manifolds with non-negative Ricci curvature)

Examples of QuasiConvex Spaces

- upper regular Loewner spaces (this includes Carnot groups & certain Riemannian manifolds with non-negative Ricci curvature)
- doubling metric measure spaces supporting a Poincaré inequality

Examples of QuasiConvex Spaces

- upper regular Loewner spaces (this includes Carnot groups & certain Riemannian manifolds with non-negative Ricci curvature)
- doubling metric measure spaces supporting a Poincaré inequality
- Sobolev extension domains in Euclidean space

Examples of QuasiConvex Spaces

- upper regular Loewner spaces (this includes Carnot groups & certain Riemannian manifolds with non-negative Ricci curvature)
- doubling metric measure spaces supporting a Poincaré inequality
- Sobolev extension domains in Euclidean space
- a John disk is a quasidisk if and only if it is quasiconvex

Main Questions & Outline of Talk

- Which domains in \mathbb{R}^n are quasiconvex?

Main Questions & Outline of Talk

- Which domains in \mathbb{R}^n are quasiconvex?
- What do quasiconvexity obstacles look like?

Main Questions & Outline of Talk

- Which domains in \mathbb{R}^n are quasiconvex?
- What do quasiconvexity obstacles look like?
- If $A \subset \mathbb{R}^n$ is closed and totally disconnected, is $A^c := \mathbb{R}^n \setminus A$ quasiconvex? (A^c is connected, hence rectifiably connected)

Main Questions & Outline of Talk

- Which domains in \mathbb{R}^n are quasiconvex?
- What do quasiconvexity obstacles look like?
- If $A \subset \mathbb{R}^n$ is closed and totally disconnected, is $A^c := \mathbb{R}^n \setminus A$ quasiconvex? (A^c is connected, hence rectifiably connected)
- First, examine plane domains. Can characterize finitely connected quasiconvex plane domains.

Main Questions & Outline of Talk

- Which domains in \mathbb{R}^n are quasiconvex?
- What do quasiconvexity obstacles look like?
- If $A \subset \mathbb{R}^n$ is closed and totally disconnected, is $A^c := \mathbb{R}^n \setminus A$ quasiconvex? (A^c is connected, hence rectifiably connected)
- First, examine plane domains. Can characterize finitely connected quasiconvex plane domains.
- Next, exhibit sufficient conditions for quasiconvexity of domains in \mathbb{R}^n .

Main Questions & Outline of Talk

- Which domains in \mathbb{R}^n are quasiconvex?
- What do quasiconvexity obstacles look like?
- If $A \subset \mathbb{R}^n$ is closed and totally disconnected, is $A^c := \mathbb{R}^n \setminus A$ quasiconvex? (A^c is connected, hence rectifiably connected)
- First, examine plane domains. Can characterize finitely connected quasiconvex plane domains.
- Next, exhibit sufficient conditions for quasiconvexity of domains in \mathbb{R}^n .
- Last, present some especially relevant examples.

Outline

- 1 Introduction
 - Definitions & Examples
 - Euclidean Domains
- 2 Plane Domains
 - Necessary Conditions
 - Sufficient Conditions
 - Finitely Connected Domains
- 3 General Sufficient Conditions
- 4 The Main Example
 - The Result
 - Picture Proof

Notation

Call $C \subset \mathbb{R}^2$ a *Jordan curve* if it is a Jordan loop or a Jordan line:

a *Jordan loop* is homeomorphic image of a round circle,

so always compact;

a *Jordan line* is image of injective path $\mathbb{R} \xrightarrow{\lambda} \mathbb{R}^2$ with

$\lambda(t) \rightarrow \infty$ (in $\hat{\mathbb{R}}^2$) as $t \rightarrow \pm\infty$.

Notation

Call $C \subset \mathbb{R}^2$ a *Jordan curve* if it is a Jordan loop or a Jordan line:

a *Jordan loop* is homeomorphic image of a round circle,

so always compact;

a *Jordan line* is image of injective path $\mathbb{R} \xrightarrow{\lambda} \mathbb{R}^2$ with

$$\lambda(t) \rightarrow \infty \text{ (in } \hat{\mathbb{R}}^2 \text{) as } t \rightarrow \pm\infty.$$

Every Jordan line in \mathbb{R}^2 corresponds to a Jordan loop in $\hat{\mathbb{R}}^2$.

Notation

Call $C \subset \mathbb{R}^2$ a *Jordan curve* if it is a Jordan loop or a Jordan line:

a *Jordan loop* is homeomorphic image of a round circle,

so always compact;

a *Jordan line* is image of injective path $\mathbb{R} \xrightarrow{\lambda} \mathbb{R}^2$ with

$$\lambda(t) \rightarrow \infty \text{ (in } \hat{\mathbb{R}}^2 \text{) as } t \rightarrow \pm\infty.$$

Every Jordan line in \mathbb{R}^2 corresponds to a Jordan loop in $\hat{\mathbb{R}}^2$.

All topology with respect to \mathbb{R}^2 .

Notation

Call $C \subset \mathbb{R}^2$ a *Jordan curve* if it is a Jordan loop or a Jordan line:

a *Jordan loop* is homeomorphic image of a round circle,

so always compact;

a *Jordan line* is image of injective path $\mathbb{R} \xrightarrow{\lambda} \mathbb{R}^2$ with

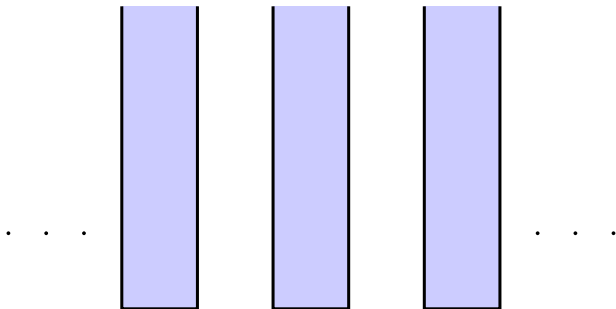
$$\lambda(t) \rightarrow \infty \text{ (in } \hat{\mathbb{R}}^2) \text{ as } t \rightarrow \pm\infty.$$

Every Jordan line in \mathbb{R}^2 corresponds to a Jordan loop in $\hat{\mathbb{R}}^2$.

All topology with respect to \mathbb{R}^2 .

A *Jordan curve domain* is an open connected plane region each of whose boundary components is either a single point or a Jordan curve.

A Simply Connected Jordan Curve Domain



A simply connected Jordan curve domain

Figure: Infinitely many unbounded boundary components

Necessary Conditions for QuasiConvexity

Theorem

Suppose $D \subsetneq \mathbb{R}^2$ is a c -quasiconvex domain. Then:

(i) D is a Jordan curve domain,

▶ Proof of (i)

Necessary Conditions for QuasiConvexity

Theorem

Suppose $D \subsetneq \mathbb{R}^2$ is a c -quasiconvex domain. Then:

- (i) D is a Jordan curve domain,
- (ii) ∂D has at most $\pi / \arcsin(1/c)$ unbounded components, and

▶ Proof of (ii)

Necessary Conditions for QuasiConvexity

Theorem

Suppose $D \subsetneq \mathbb{R}^2$ is a c -quasiconvex domain. Then:

- (i) D is a Jordan curve domain,
- (ii) ∂D has at most $\pi / \arcsin(1/c)$ unbounded components, and
- (iii) for any $b > c$, all pts $\xi, \eta \in \bar{D}$ joinable by b -quasiconvex path in $D \cup \{\xi, \eta\}$; \therefore all pts of ∂D rectifiably accessible.

Necessary Conditions for QuasiConvexity

Theorem

Suppose $D \subsetneq \mathbb{R}^2$ is a c -quasiconvex domain. Then:

- (i) D is a Jordan curve domain,
- (ii) ∂D has at most $\pi / \arcsin(1/c)$ unbounded components, and
- (iii) for any $b > c$, all pts $\xi, \eta \in \bar{D}$ joinable by b -quasiconvex path in $D \cup \{\xi, \eta\}$; \therefore all pts of ∂D rectifiably accessible.

(iii) is best possible: may be bdry pts not joinable by c -quasiconvex paths

Necessary Conditions for QuasiConvexity

Theorem

Suppose $D \subsetneq \mathbb{R}^2$ is a c -quasiconvex domain. Then:

- (i) D is a Jordan curve domain,
- (ii) ∂D has at most $\pi / \arcsin(1/c)$ unbounded components, and
- (iii) for any $b > c$, all pts $\xi, \eta \in \bar{D}$ joinable by b -quasiconvex path in $D \cup \{\xi, \eta\}$; \therefore all pts of ∂D rectifiably accessible.

(iii) is best possible: may be bdry pts not joinable by c -quasiconvex paths
 (ii) & $c = 1$ says a convex domain has at most two unbdd bdry cmpnts

Necessary Conditions for QuasiConvexity

Theorem

Suppose $D \subsetneq \mathbb{R}^2$ is a c -quasiconvex domain. Then:

- (i) D is a Jordan curve domain,
- (ii) ∂D has at most $\pi / \arcsin(1/c)$ unbounded components, and
- (iii) for any $b > c$, all pts $\xi, \eta \in \bar{D}$ joinable by b -quasiconvex path in $D \cup \{\xi, \eta\}$; \therefore all pts of ∂D rectifiably accessible.

(iii) is best possible: may be bdry pts not joinable by c -quasiconvex paths

(ii) & $c = 1$ says a convex domain has at most two unbdd bdry cmpnts

$\forall n \geq 1, \exists$ simply conn c -quasiconvex domain with $c = 1/\sin(\pi/n)$ and n unbdd bdry components

Necessary Conditions for QuasiConvexity

Theorem

Suppose $D \subsetneq \mathbb{R}^2$ is a c -quasiconvex domain. Then:

- (i) D is a Jordan curve domain,
- (ii) ∂D has at most $\pi / \arcsin(1/c)$ unbounded components, and
- (iii) for any $b > c$, all pts $\xi, \eta \in \bar{D}$ joinable by b -quasiconvex path in $D \cup \{\xi, \eta\}$; \therefore all pts of ∂D rectifiably accessible.

(iii) is best possible: may be bdry pts not joinable by c -quasiconvex paths

(ii) & $c = 1$ says a convex domain has at most two unbdd bdry cmpnts

$\forall n \geq 1$, \exists simply conn c -quasiconvex domain with $c = 1/\sin(\pi/n)$ and n unbdd bdry components—namely, the domains D_n [▶ See \$D_n\$ pix](#)

Necessary Conditions for QuasiConvexity

Theorem

Suppose $D \subsetneq \mathbb{R}^2$ is a c -quasiconvex domain. Then:

- (i) D is a Jordan curve domain,
- (ii) ∂D has at most $\pi / \arcsin(1/c)$ unbounded components, and
- (iii) for any $b > c$, all pts $\xi, \eta \in \bar{D}$ joinable by b -quasiconvex path in $D \cup \{\xi, \eta\}$; \therefore all pts of ∂D rectifiably accessible.

(iii) is best possible: may be bdry pts not joinable by c -quasiconvex paths

(ii) & $c = 1$ says a convex domain has at most two unbdd bdry cmpnts

$\forall n \geq 1$, \exists simply conn c -quasiconvex domain with $c = 1/\sin(\pi/n)$ and n unbdd bdry components—namely, the domains D_n

Sufficient Conditions for QuasiConvexity

Theorem

$D \subsetneq \mathbb{R}^2$ a Jordan curve domain with finitely many boundary components

Sufficient Conditions for QuasiConvexity

Theorem

*$D \subsetneq \mathbb{R}^2$ a Jordan curve domain with finitely many boundary components
Suppose $c > 1$ and all rectifiably accessible pts $\xi, \eta \in \partial D$ joinable by c -quasiconvex path in $D \cup \{\xi, \eta\}$.*

Sufficient Conditions for QuasiConvexity

Theorem

$D \subsetneq \mathbb{R}^2$ a Jordan curve domain with finitely many boundary components
Suppose $c > 1$ and all rectifiably accessible pts $\xi, \eta \in \partial D$ joinable by c -quasiconvex path in $D \cup \{\xi, \eta\}$. Then D is c -quasiconvex.

▶ Proof

Sufficient Conditions for QuasiConvexity

Theorem

*$D \subsetneq \mathbb{R}^2$ a Jordan curve domain with finitely many boundary components
Suppose $c > 1$ and all rectifiably accessible pts $\xi, \eta \in \partial D$ joinable by
 c -quasiconvex path in $D \cup \{\xi, \eta\}$. Then D is c -quasiconvex.*

Sufficient Conditions for QuasiConvexity

Theorem

$D \subsetneq \mathbb{R}^2$ a Jordan curve domain with finitely many boundary components
Suppose $c > 1$ and all rectifiably accessible pts $\xi, \eta \in \partial D$ joinable by c -quasiconvex path in $D \cup \{\xi, \eta\}$. Then D is c -quasiconvex.

$E \neq \emptyset$ closed totally disconn set of pts lying on some strictly convex curve
 $\implies E^c$ satisfies all above hypotheses with $c = 1$, but is not convex.

Sufficient Conditions for QuasiConvexity

Theorem

$D \subsetneq \mathbb{R}^2$ a Jordan curve domain with *finitely many boundary components*
 Suppose $c > 1$ and all rectifiably accessible pts $\xi, \eta \in \partial D$ joinable by c -quasiconvex path in $D \cup \{\xi, \eta\}$. Then D is c -quasiconvex.

$E \neq \emptyset$ closed totally disconn set of pts lying on some strictly convex curve
 $\implies E^c$ satisfies all above hypotheses with $c = 1$, but is not convex.

Can weaken hypothesis *finitely many boundary components* if instead require that all boundary points be joinable by quasiconvex paths.

QuasiConvexity Characterization

Corollary

A finitely connected $D \subsetneq \mathbb{R}^2$ is c -quasiconvex iff

- (i) D is a Jordan curve domain, and
- (ii) all pts $\xi, \eta \in \partial D$ joinable by b -quasiconvex path in $D \cup \{\xi, \eta\}$.

For necessity, can take any $b > c$; for sufficiency, $c = b$ works.

QuasiConvexity Characterization

Corollary

A *finitely connected* $D \subsetneq \mathbb{R}^2$ is c -quasiconvex iff

- (i) D is a Jordan curve domain, and
- (ii) all pts $\xi, \eta \in \partial D$ joinable by b -quasiconvex path in $D \cup \{\xi, \eta\}$.

For necessity, can take any $b > c$; for sufficiency, $c = b$ works.

Recall that there exist simply connected Jordan curve domains with infinitely many boundary components.

▶ See lotsa pix

QuasiConvexity Characterization

Corollary

A finitely connected $D \subsetneq \mathbb{R}^2$ is c -quasiconvex iff

- (i) D is a Jordan curve domain, and
- (ii) all pts $\xi, \eta \in \partial D$ joinable by b -quasiconvex path in $D \cup \{\xi, \eta\}$.

For necessity, can take any $b > c$; for sufficiency, $c = b$ works.

Recall that there exist simply connected Jordan curve domains with infinitely many boundary components.

Outline

- 1 Introduction
 - Definitions & Examples
 - Euclidean Domains
- 2 Plane Domains
 - Necessary Conditions
 - Sufficient Conditions
 - Finitely Connected Domains
- 3 General Sufficient Conditions
- 4 The Main Example
 - The Result
 - Picture Proof

General Sufficient Conditions

Fact

Suppose $A \subset \mathbb{R}^n$ is closed and each projection onto a coordinate $(n - 1)$ -plane has $(n - 1)$ -measure zero. Then A^c is quasiconvex.

▶ See Proof

General Sufficient Conditions

Theorem

Suppose $A \subset \mathbb{R}^n$ is closed and each projection onto a coordinate $(n - 1)$ -plane has $(n - 1)$ -measure zero *or is nowhere dense*.

Then A^c is quasiconvex.

General Sufficient Conditions

Theorem

Suppose $A \subset \mathbb{R}^n$ is closed and each projection onto a coordinate $(n-1)$ -plane has $(n-1)$ -measure zero or is nowhere dense.

Then A^c is quasiconvex.

Thus A^c is quasiconvex if

- $\dim_{\mathcal{H}} A < n - 1$, or $\mathcal{H}^{n-1}(A) = 0$, or
- A is n -fold product of a positive measure nowhere dense subset of \mathbb{R} .

General Sufficient Conditions

Theorem

Suppose $A \subset \mathbb{R}^n$ is closed and each projection onto a coordinate $(n-1)$ -plane has $(n-1)$ -measure zero or is nowhere dense.

Then A^c is quasiconvex.

Thus A^c is quasiconvex if

- $\dim_{\mathcal{H}} A < n - 1$, or $\mathcal{H}^{n-1}(A) = 0$, or
- A is n -fold product of a **positive measure** nowhere dense subset of \mathbb{R} .

So, there exists quasiconvex $D \subset \mathbb{R}^n$ with $\mathcal{H}^n(\partial D) > 0$.

Outline

- 1 Introduction
 - Definitions & Examples
 - Euclidean Domains
- 2 Plane Domains
 - Necessary Conditions
 - Sufficient Conditions
 - Finitely Connected Domains
- 3 General Sufficient Conditions
- 4 The Main Example
 - The Result
 - Picture Proof

Statements

Theorem

*There exists a compact **totally disconnected** set $A \subset \mathbb{R}^n$ with Hausdorff dimension $\dim_{\mathcal{H}} A = n - 1$ and A^c non-quasiconvex.*

Statements

Theorem

There exists a compact totally disconnected set $A \subset \mathbb{R}^n$ with Hausdorff dimension $\dim_{\mathcal{H}} A = n - 1$ and A^c non-quasiconvex.

Corollary

For closed $A \subset \mathbb{R}^n$, $\mathcal{H}^{n-1}(A) = 0 \implies A^c$ quasiconvex. OTOH,

Statements

Theorem

There exists a compact totally disconnected set $A \subset \mathbb{R}^n$ with Hausdorff dimension $\dim_{\mathcal{H}} A = n - 1$ and A^c non-quasiconvex.

Corollary

For closed $A \subset \mathbb{R}^n$, $\mathcal{H}^{n-1}(A) = 0 \implies A^c$ quasiconvex. OTOH, $\forall \alpha \in (n - 1, n]$, \exists compact totally disconn A, B with positive finite α -measure and such that A^c is not quasiconvex while B^c is quasiconvex.

Statements

Theorem

There exists a compact totally disconnected set $A \subset \mathbb{R}^n$ with Hausdorff dimension $\dim_{\mathcal{H}} A = n - 1$ and A^c non-quasiconvex.

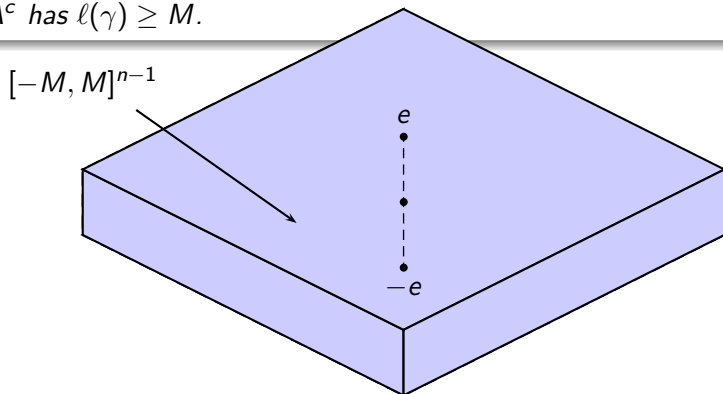
Corollary

For closed $A \subset \mathbb{R}^n$, $\mathcal{H}^{n-1}(A) = 0 \implies A^c$ quasiconvex. OTOH, $\forall \alpha \in (n - 1, n]$, \exists compact totally disconn A, B with positive finite α -measure and such that A^c is not quasiconvex while B^c is quasiconvex. When $\alpha = n - 1$, still get such A, B but only know A has non-zero $(n - 1)$ -measure.

Key Tool

Proposition

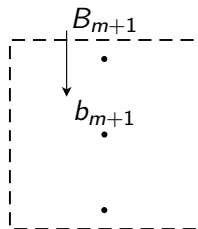
$\forall M > 0, \exists$ compact totally disconn $A \subset [-M, M]^{n-1} \times [-1/2, 1/2]$ with $\pm e \in A^c$, $e = (0, \dots, 0, 1)$, $\dim_{\mathcal{H}} A \leq n - 1$, and st each rectifiable path γ joining $\pm e$ in A^c has $\ell(\gamma) \geq M$.



Proposition \implies Theorem

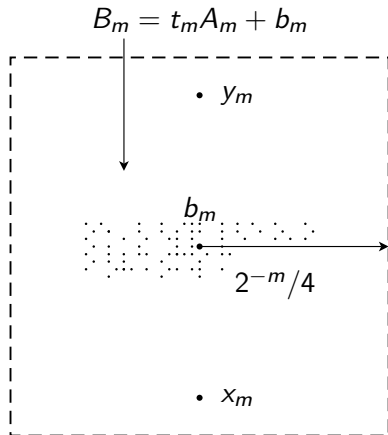
$$t_m = (2^{m+2} \operatorname{diam} A_m)^{-1}$$

$$b_m = (1/2^m, 0, \dots, 0)$$



$$\begin{array}{cccc} \bullet & \bullet & \bullet & \bullet \\ (0, \dots, 0) & & & \end{array}$$

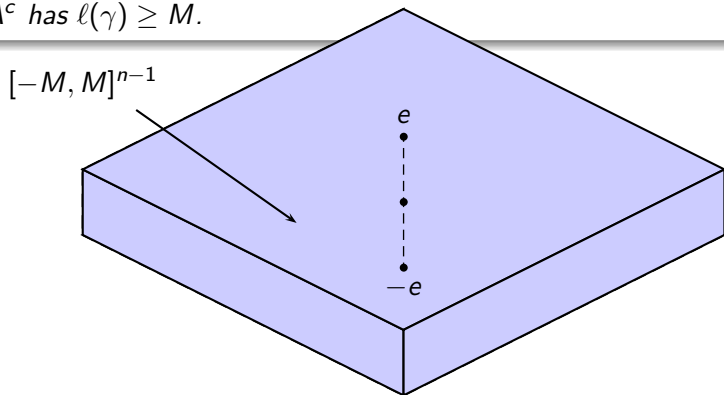
$$A = \{0\} \cup \bigcup_1^\infty B_m$$



Key Tool

Proposition

$\forall M > 0, \exists$ compact totally disconn $A \subset [-M, M]^{n-1} \times [-1/2, 1/2]$ with $\pm e \in A^c$, $e = (0, \dots, 0, 1)$, $\dim_{\mathcal{H}} A \leq n - 1$, and st each rectifiable path γ joining $\pm e$ in A^c has $\ell(\gamma) \geq M$.



Idea for Proof of Proposition

Use Cantor type construction:

get $A := \bigcap_i E_i$ where $E_1 \supset E_2 \supset \dots$, $E_i = \bigcup_j B_{ij}$ compact, with B_{ij} nested closed rectangular boxes satisfying

$$\lim_{i \rightarrow \infty} \sup_j \text{diam } B_{ij} = 0.$$

Thus A closed and totally disconnected.

Idea for Proof of Proposition

Use Cantor type construction:

get $A := \bigcap_i E_i$ where $E_1 \supset E_2 \supset \dots$, $E_i = \bigcup_j B_{ij}$ compact, with B_{ij} nested closed rectangular boxes satisfying

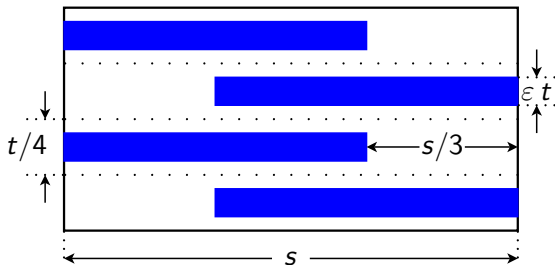
$$\lim_{i \rightarrow \infty} \sup_j \text{diam } B_{ij} = 0.$$

Thus A closed and totally disconnected.

Gotta describe sets B_{ij} .

Construction in \mathbb{R}^2

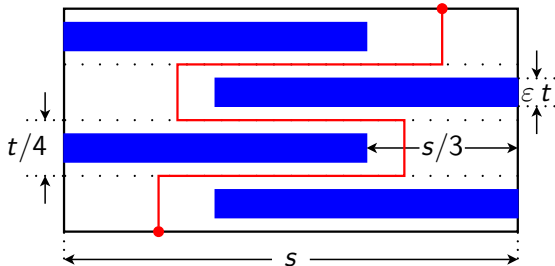
Start with thin flat $[0, s] \times [0, t]$ rectangle. Divide into four horizontal corridors ($[0, s] \times [0, t/4]$, etc.). Place $(2s/3) \times (\varepsilon t)$ barriers into vertical middles of each of these corridors. Alternate horizontal placement of barriers.



Construction in \mathbb{R}^2

Start with thin flat $[0, s] \times [0, t]$ rectangle. Divide into four horizontal corridors ($[0, s] \times [0, t/4]$, etc.). Place $(2s/3) \times (\varepsilon t)$ barriers into vertical middles of each of these corridors. Alternate horizontal placement of barriers. Path in original rectangle joining horizontal edges and avoiding barriers has 'horizontal length' at least s .

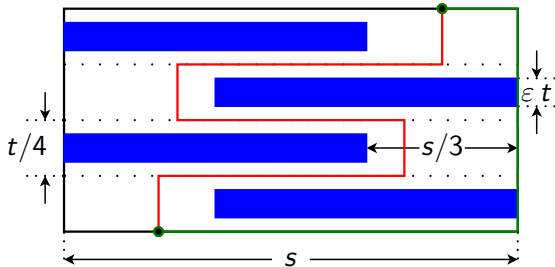
a 'penetrating path' traversing a plane maze



Construction in \mathbb{R}^2

Start with thin flat $[0, s] \times [0, t]$ rectangle. Divide into four horizontal corridors ($[0, s] \times [0, t/4]$, etc.). Place $(2s/3) \times (\varepsilon t)$ barriers into vertical middles of each of these corridors. Alternate horizontal placement of barriers. Path in original rectangle joining horizontal edges and avoiding barriers has 'horizontal length' at least s . Such a 'penetrating path' can be replaced—without increasing 'horizontal length'—by 'avoiding path'.

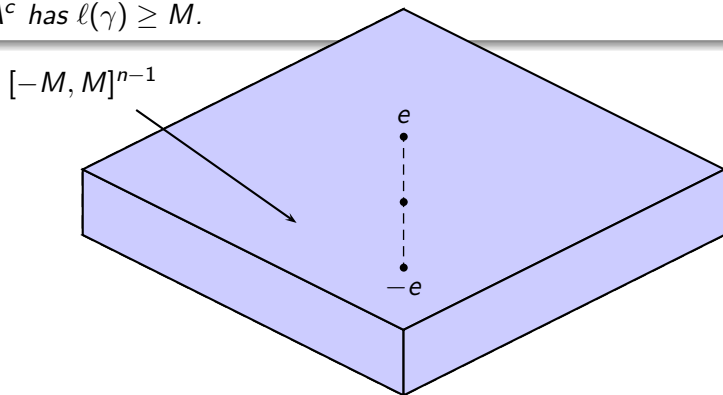
an 'avoiding path' traversing the boundary
a 'penetrating path' traversing a plane maze



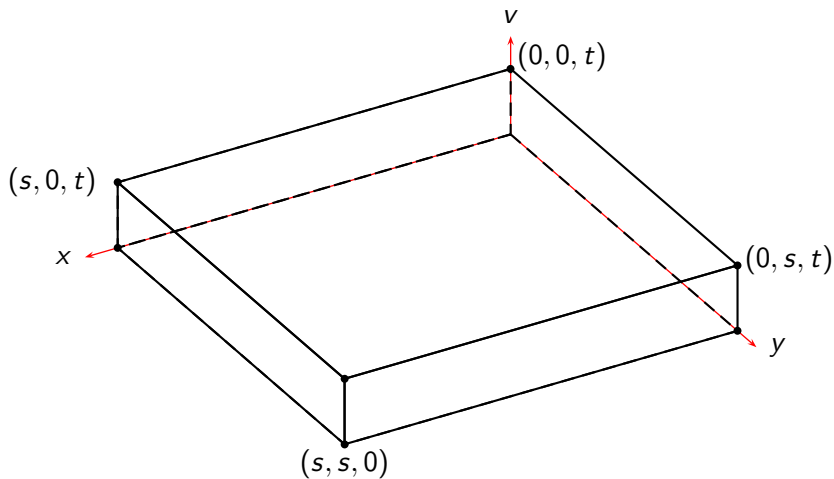
Key Tool

Proposition

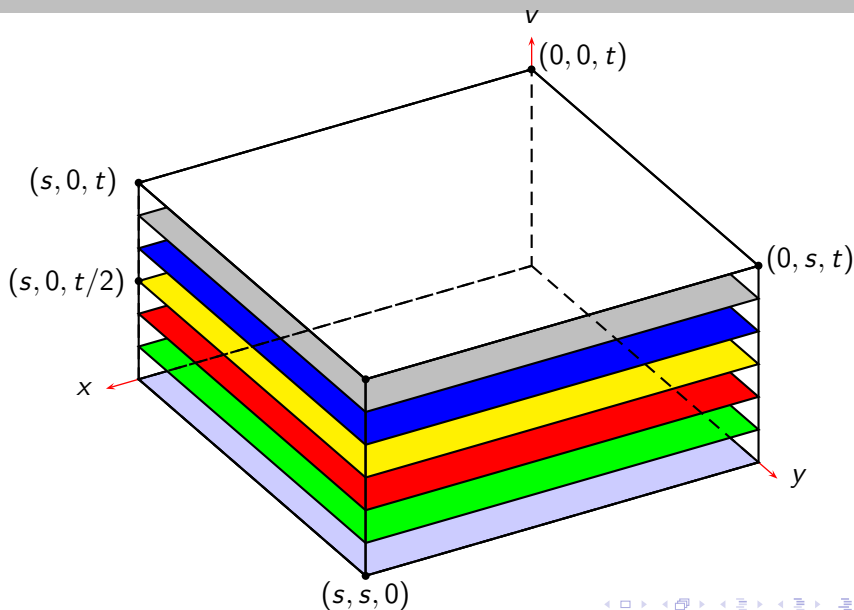
$\forall M > 0, \exists$ compact totally disconn $A \subset [-M, M]^{n-1} \times [-1/2, 1/2]$ with $\pm e \in A^c$, $e = (0, \dots, 0, 1)$, $\dim_{\mathcal{H}} A \leq n - 1$, and st each rectifiable path γ joining $\pm e$ in A^c has $\ell(\gamma) \geq M$.



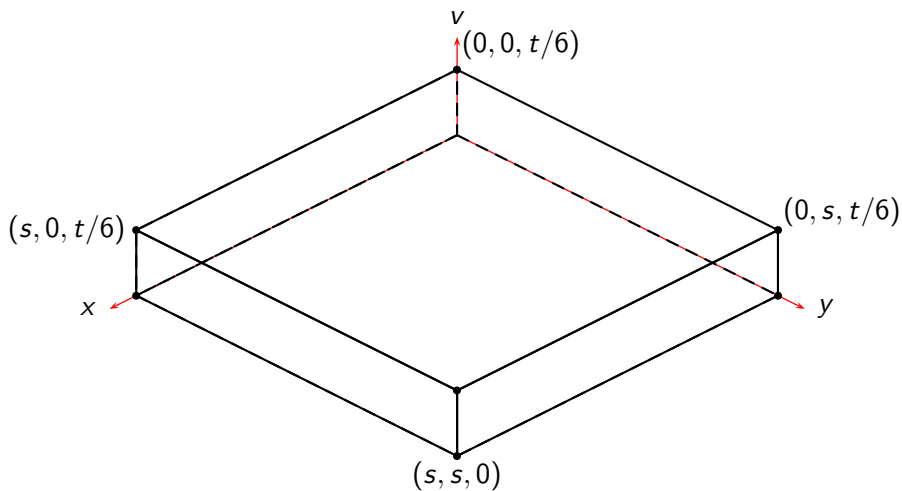
B – a Thin Flat $s \times s \times t$ Rectangular Box in \mathbb{R}^3



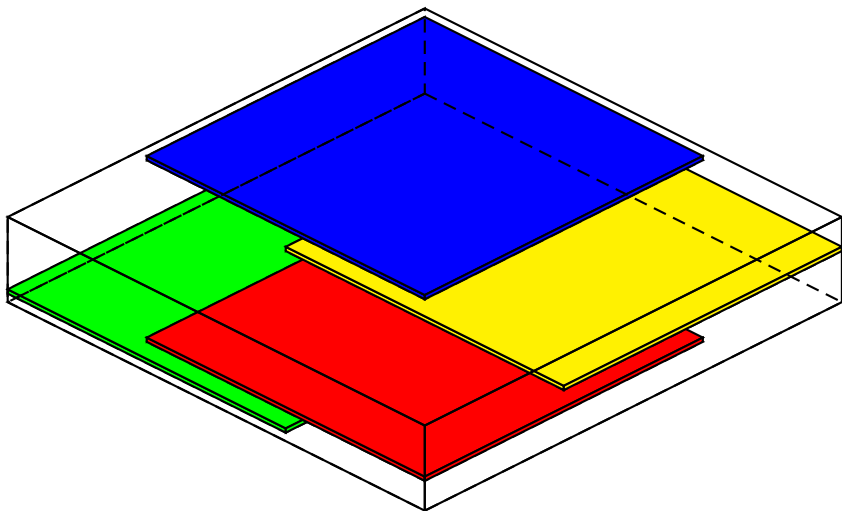
The Rectangular Box B Divided into 6 Layers



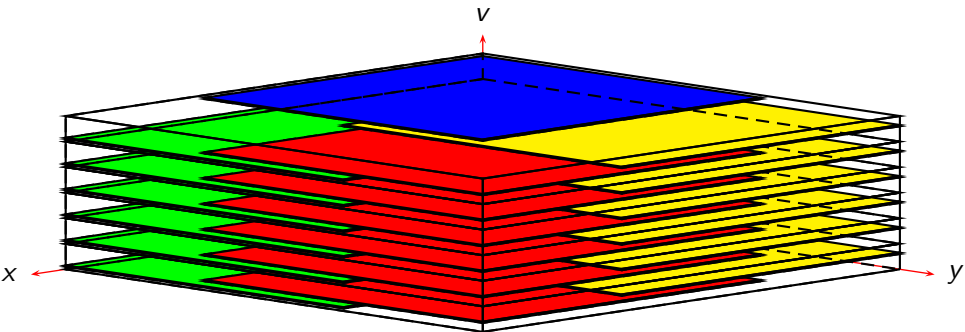
C – a Thin Flat $s \times s \times (t/6)$ Layer of B



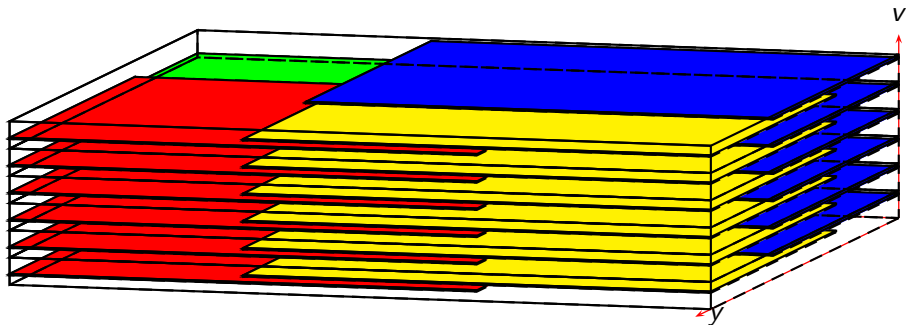
A SubMaze in C with $(2s/3) \times (2s/3) \times (\varepsilon t)$ Barriers



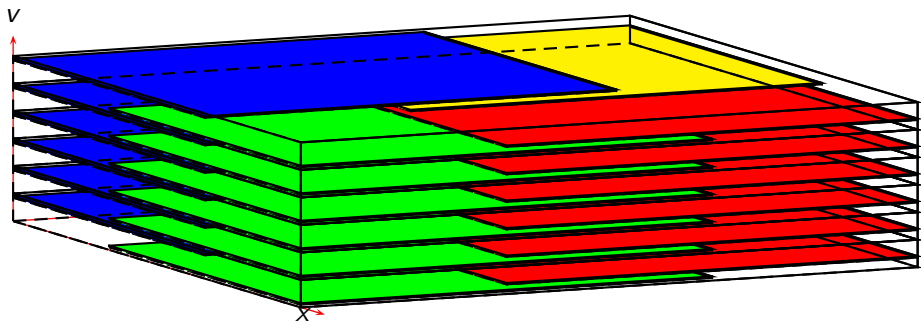
A Box Maze in B Built with 6 Stacked SubMazes



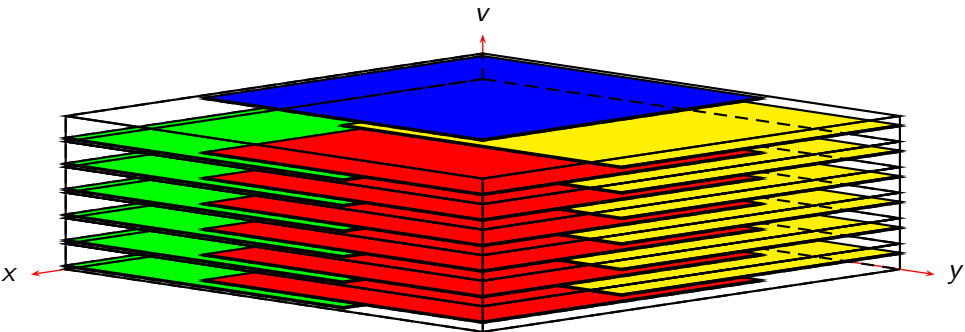
A Box Maze in B Built with 6 Stacked SubMazes



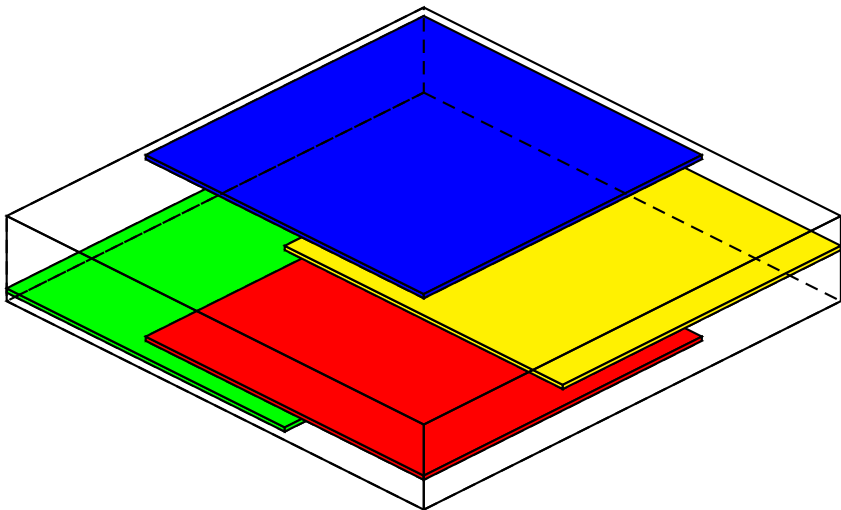
A Box Maze in B Built with 6 Stacked SubMazes



A Box Maze in B Built with 6 Stacked SubMazes



A SubMaze in C with $(2s/3) \times (2s/3) \times (\varepsilon t)$ Barriers



Summary

- Compact totally disconnected sets may not have quasiconvex complements.

Summary

- Compact totally disconnected sets may not have quasiconvex complements.
- Altho true for 'small' sets (Hausdorff dimension below $n - 1$, or zero-measure projections, or nowhere dense projections).

Summary

- Compact totally disconnected sets may not have quasiconvex complements.
- Altho true for 'small' sets (Hausdorff dimension below $n - 1$, or zero-measure projections, or nowhere dense projections).
- Is there an example with positive finite $(n - 1)$ -measure?

Summary

- Compact totally disconnected sets may not have quasiconvex complements.
- Altho true for 'small' sets (Hausdorff dimension below $n - 1$, or zero-measure projections, or nowhere dense projections).
- Is there an example with positive **finite** $(n - 1)$ -measure? (I guess no)

The End



5 Appendix

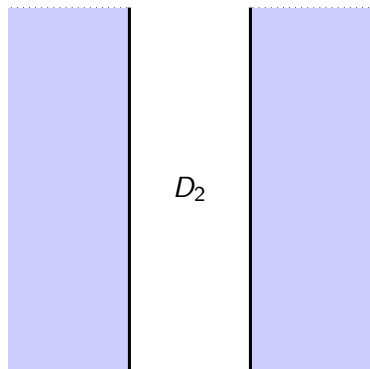
- Extremal Examples
- Proof of Theorem A(i)
- Proof of Theorem A(ii)
- Proof of Theorem B
- Proof of Theorem

Outline

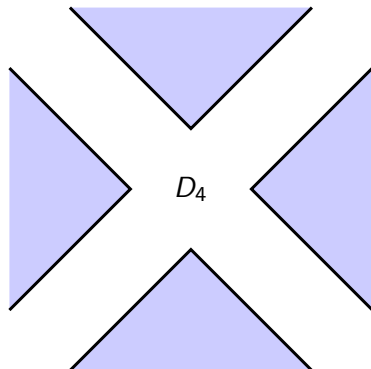
- 5 Appendix
 - Extremal Examples
 - Proof of Theorem A(i)
 - Proof of Theorem A(ii)
 - Proof of Theorem B
 - Proof of Theorem

Complements of Sectors

$\theta = \pi/n$, $\zeta_k = e^{2ki\theta}$ ($1 \leq k \leq n$), $C_k = \zeta_k C_\theta + \zeta_k$ (closed convex sectors obtained by rotating C_θ and then translating) $\implies D_n = \mathbb{R}^2 \setminus \bigcup_{k=1}^n C_k$ is simply conn csc θ -quasicvx domain with n unbdd bdry cmpnts [◀ Go Back](#)



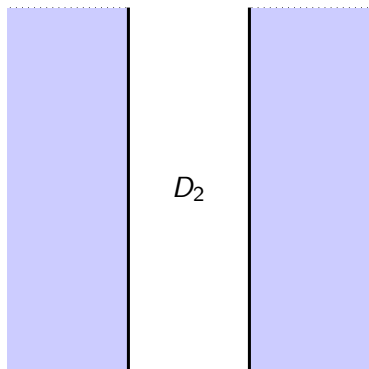
A convex domain



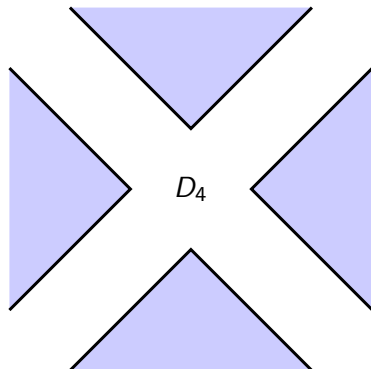
A $\sqrt{2}$ -quasiconvex domain

Complements of Sectors

$\theta = \pi/n$, $\zeta_k = e^{2ki\theta}$ ($1 \leq k \leq n$), $C_k = \zeta_k C_\theta + \zeta_k$ (closed convex sectors obtained by rotating C_θ and then translating) $\implies D_n = \mathbb{R}^2 \setminus \bigcup_{k=1}^n C_k$ is simply conn csc θ -quasiconv domain with n unbdd bdry cmpnts [Go Back](#)

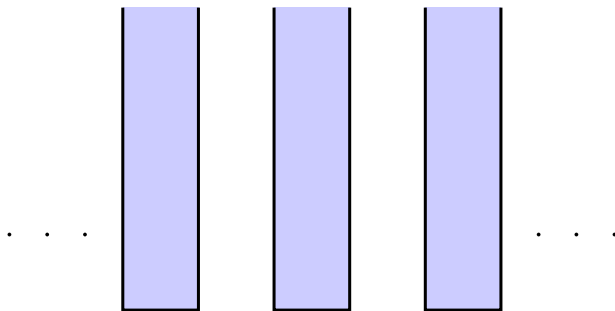


A convex domain



A $\sqrt{2}$ -quasiconvex domain

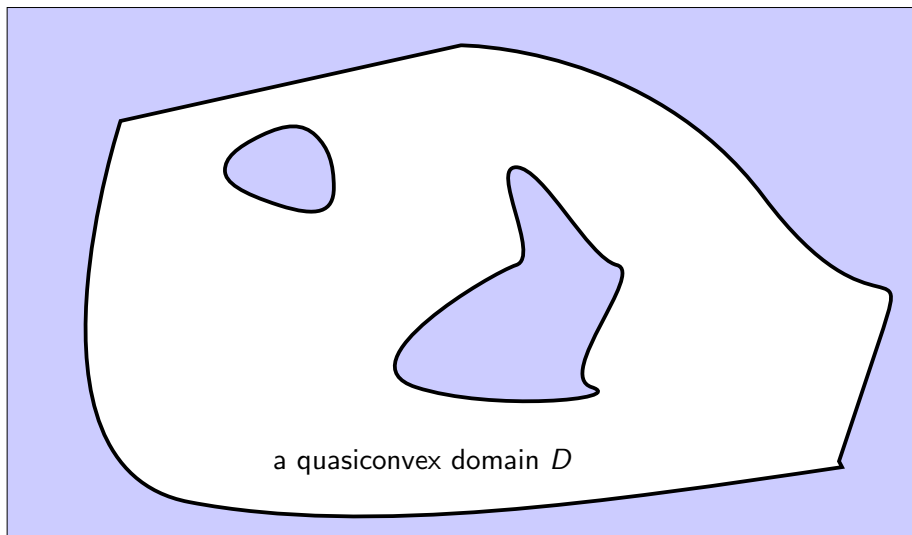
Lots of Unbdd Boundary Components

[◀ Go Back](#)

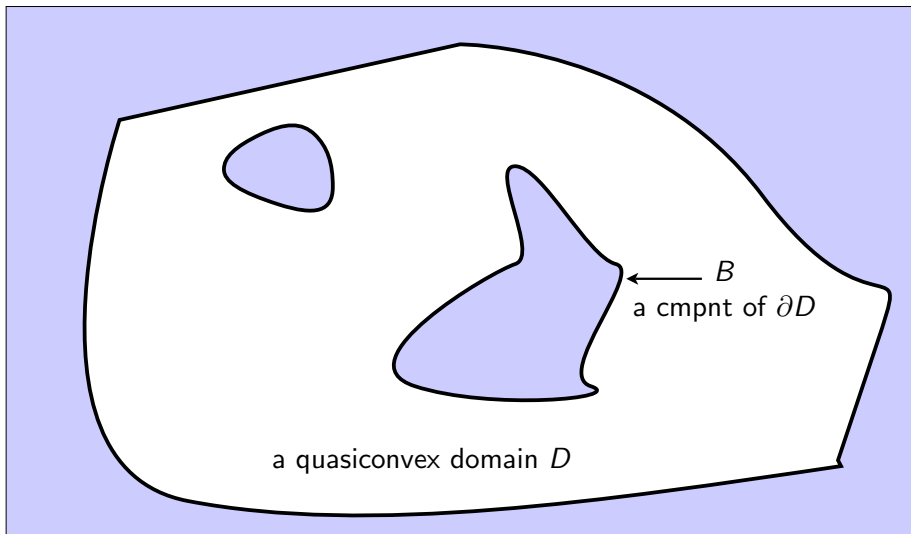
A simply connected Jordan curve domain

Figure: Infinitely many unbounded boundary components

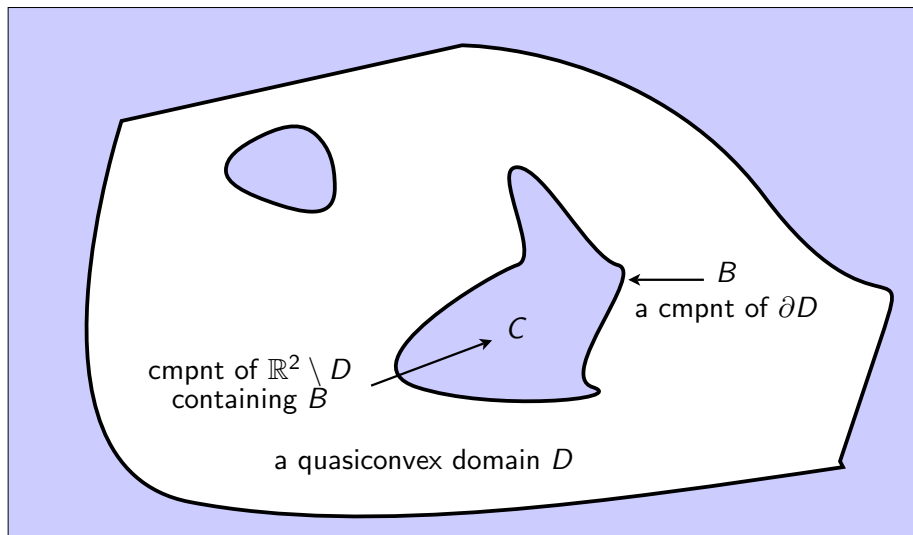
QuasiConvex Plane Domains are Jordan Curve Domains



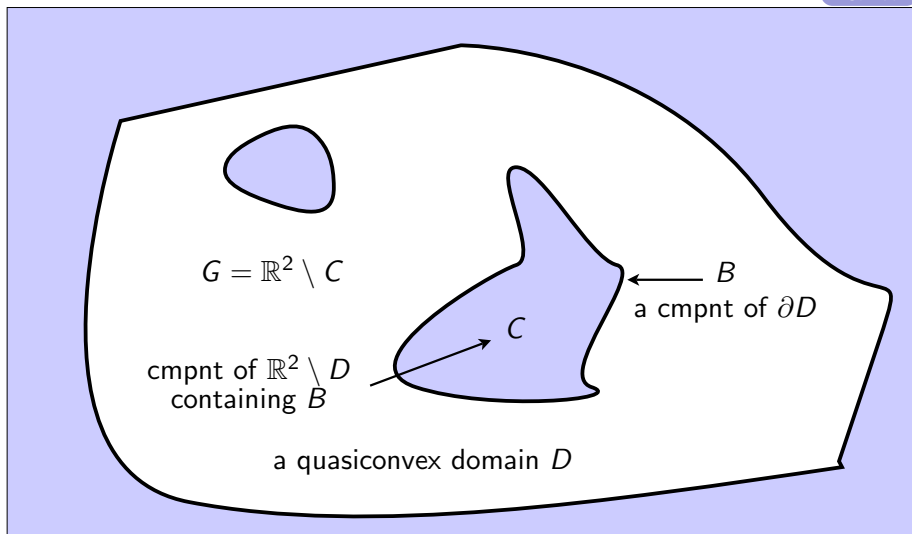
QuasiConvex Plane Domains are Jordan Curve Domains



QuasiConvex Plane Domains are Jordan Curve Domains



QuasiConvex Plane Domains are Jordan Curve Domains

[◀ Go Back](#)


Qcvx Have Finitely Many Unbdd Bdry Components

Basic Example Given $0 < \theta \leq \pi/2$, $C_\theta = \{z \in \mathbb{C} : |\text{Arg}(z)| \leq \theta\}$ is closed convex sector and the concave sector $D_\theta = \mathbb{R}^2 \setminus C_\theta$ is $\text{csc } \theta$ -quasiconvex.

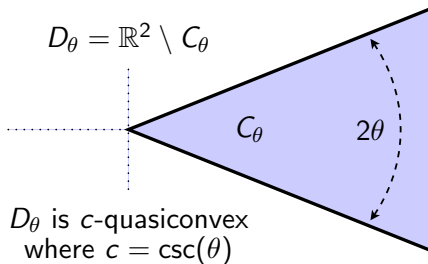


Figure: A concave sector is quasiconvex.

Qcvx Have Finitely Many Unbdd Bdry Components

$\theta = \pi/n$, $\zeta_k = e^{2ki\theta}$ ($1 \leq k \leq n$), $C_k = \zeta_k C_\theta + \zeta_k$ (closed convex sectors obtained by rotating C_θ and then translating) \implies

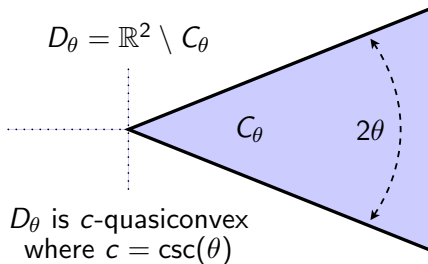
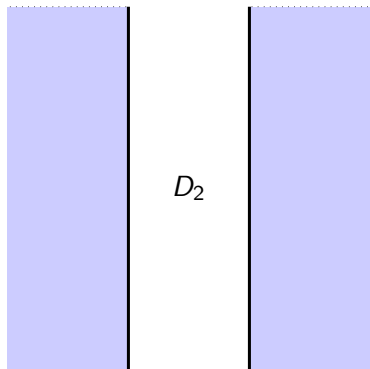


Figure: A concave sector is quasiconvex.

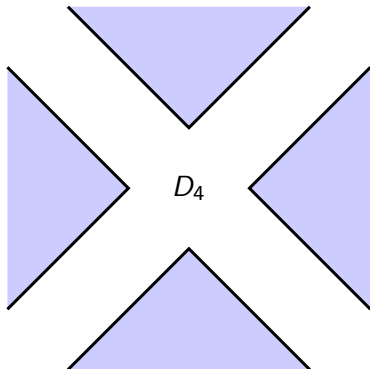
Qcvx Have Finitely Many Unbdd Bdry Components

[◀ Go Back](#)

$\theta = \pi/n$, $\zeta_k = e^{2ki\theta}$ ($1 \leq k \leq n$), $C_k = \zeta_k C_\theta + \zeta_k$ (closed convex sectors obtained by rotating C_θ and then translating) $\implies D_n = \mathbb{R}^2 \setminus \bigcup_{k=1}^n C_k$ is simply connected csc θ -quasiconvex domain with n unbdd bdry cmpnts

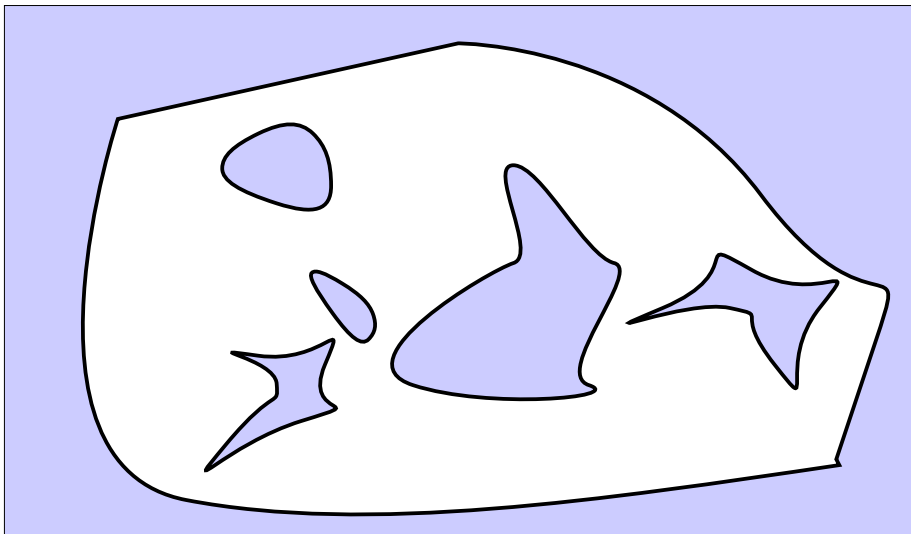


A convex domain

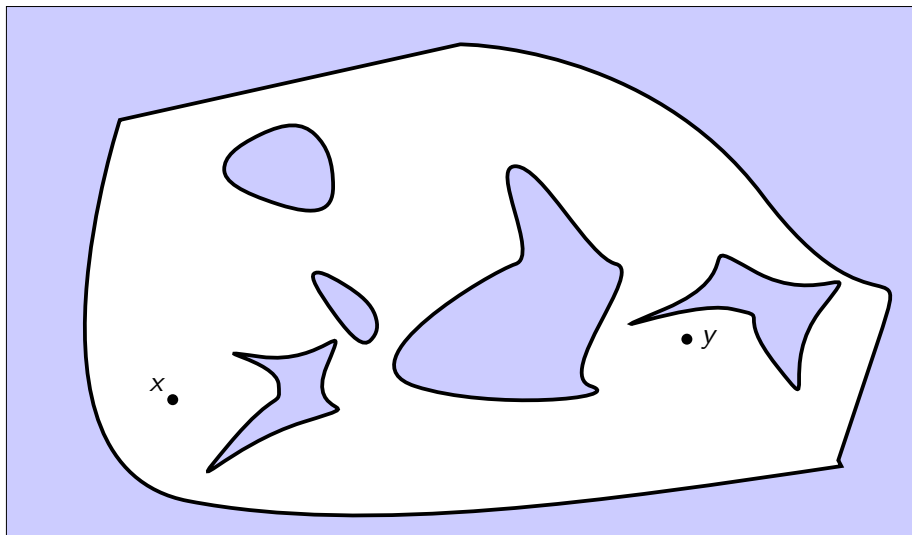


A $\sqrt{2}$ -quasiconvex domain

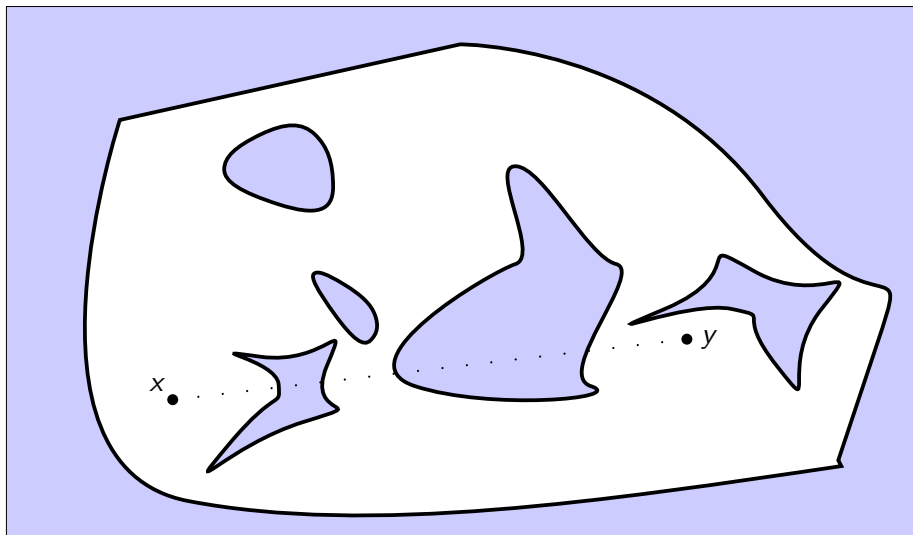
Suff Cond for Finitely Many Bdry Components



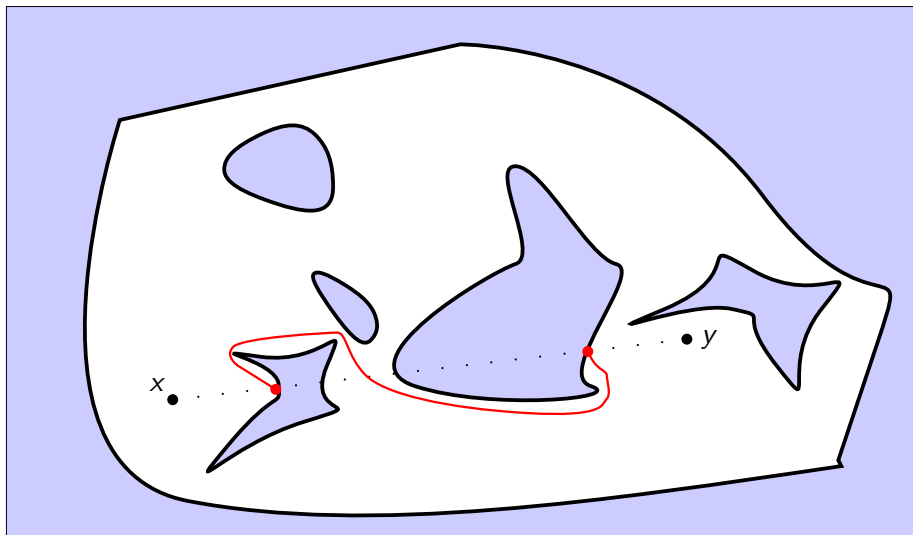
Suff Cond for Finitely Many Bdry Components



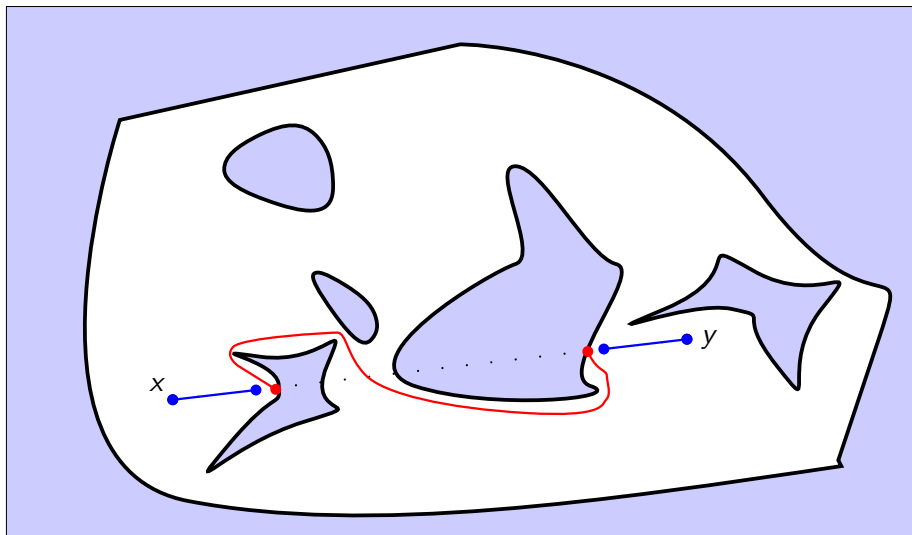
Suff Cond for Finitely Many Bdry Components



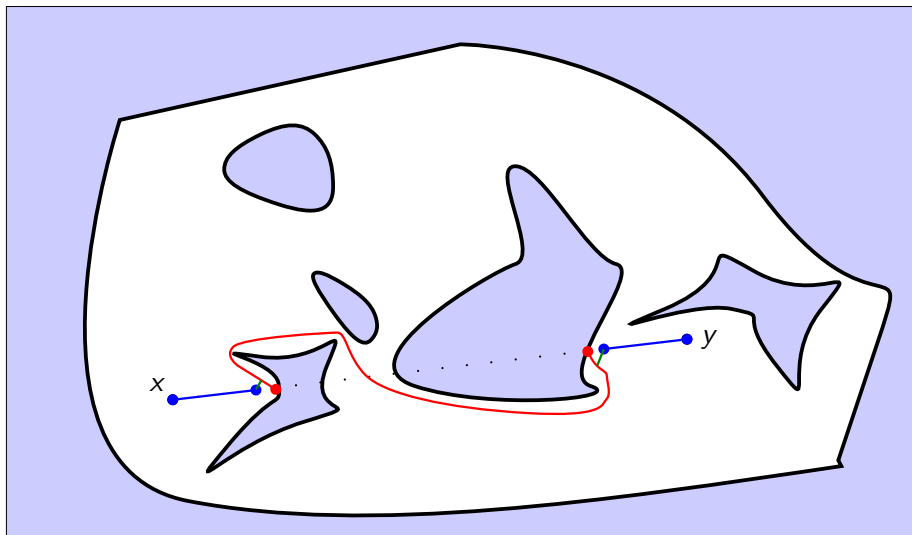
Suff Cond for Finitely Many Bdry Components



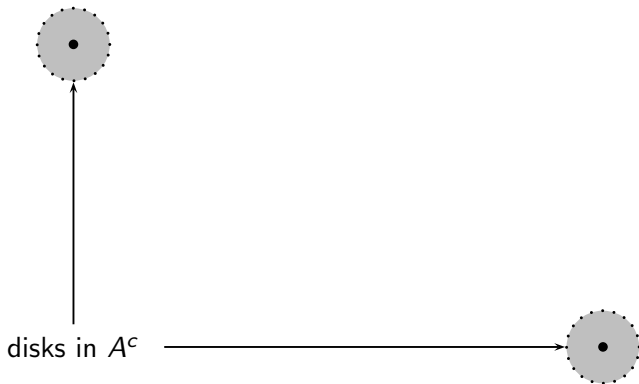
Suff Cond for Finitely Many Bdry Components



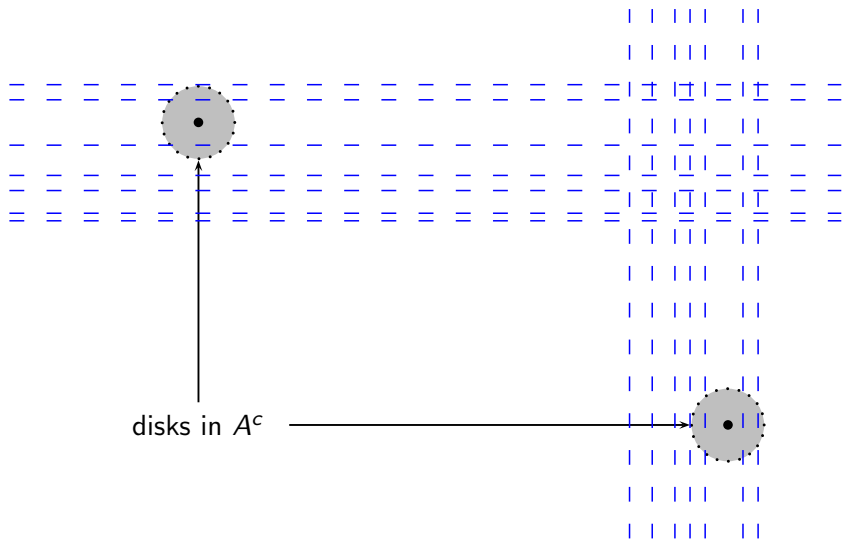
Suff Cond for Finitely Many Bdry Components

[◀ Go Back](#)

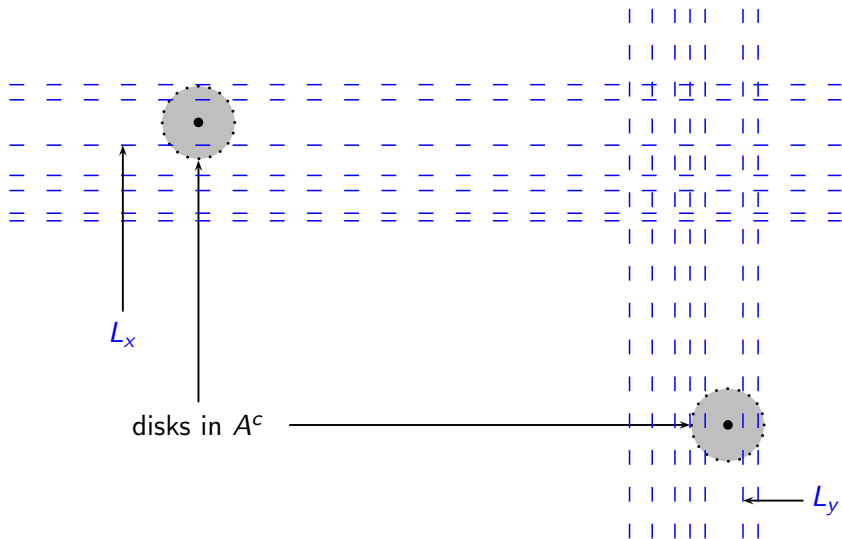
Complement of Plane Set with Zero Measure Projections



Complement of Plane Set with Zero Measure Projections



Complement of Plane Set with Zero Measure Projections



Complement of Plane Set with Zero Measure Projections

[◀ Go Back](#)
