## Characteristic Equation and Similar Matrices

Linear Algebra MATH 2076



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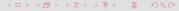
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For item (3), just note that on  $\mathbb{E}(\lambda)$ , A acts like the dilation  $A\vec{x} = \lambda \vec{x}$  (since each *non-zero* vector in  $\mathbb{E}(\lambda)$  is an eigenvector for A).



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Notice that A's two eigenvectors  $\vec{v_1}, \vec{v_2}$  are LI, so form an eigenbasis.

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#### Definition

The *characteristic polynomial* for A is  $p_A(\lambda) = \det(A - \lambda I)$ .

The *characteristic equation* for A is  $det(A - \lambda I) = 0$  (or just  $\boldsymbol{p}_A(\lambda) = 0$ ).

For a 2 × 2 matric 
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For a 3 × 3 matric A,  $\boldsymbol{p}_A(\lambda) = \det(A - \lambda I)$  is always a cubic polynomial of the form  $\boldsymbol{p}_A(\lambda) = c_0 + c_1\lambda + c_2\lambda^2 - \lambda^3$ .

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$$A_1 = \begin{bmatrix} 4 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 4 \end{bmatrix}$$
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Here  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$  is an eigenbasis assoc'd with  $A_1$ ; that is, this is a basis for  $\mathbb{R}^3$  consisting of eigenvectors for A.

$$A_2 = \begin{bmatrix} 1 & 4 & 4 \\ 0 & 3 & 2 \\ 0 & 2 & 3 \end{bmatrix}$$
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$$A_3 = \begin{bmatrix} 5 & -6 & 0 \\ 1 & -2 & 0 \\ 4 & 6 & -1 \end{bmatrix}$$
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There is **NO** eigenbasis assoc'd with  $A_3$ .



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When we have an *eigenbasis* assoc'd with A, it is especially simple to understand the action of the matrix transformation  $\vec{x} \mapsto A\vec{x}$ .

This is because A is *similar* to a diagonal matrix!



Recall that  $A=\begin{bmatrix}1&2\\4&3\end{bmatrix}$  has *simple* eigenvalues  $\lambda_1=5$  and  $\lambda_2=-1$  with

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Thus using  $\mathcal{B}\text{-coordinates}$ , the action of A is just multiplication by the diagonal matrix

$$D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}.$$

assoc'd eigenvectors  $\vec{v}_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$  and  $\vec{v}_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ . Since A's two eigenvectors are LI, they form an *eigenbasis*  $\mathcal{B} = \{\vec{v}_1, \vec{v}_2\}$ .

Suppose 
$$\vec{x} = c_1 \vec{v}_1 + c_2 \vec{v}_2$$
; so  $\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}} = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$ .

Look at

$$A\vec{x} = A(c_1\vec{v}_1 + c_2\vec{v}_2) = c_1A\vec{v}_1 + c_2A\vec{v}_2 = 5c_1\vec{v}_1 - c_2\vec{v}_2$$

which says that

$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = \begin{bmatrix} 5c_1 \\ -c_2 \end{bmatrix} = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}}.$$

Thus using  $\mathcal{B}$ -coordinates, the action of A is just multiplication by the diagonal matrix

$$D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}.$$

But, how do we get  $A\vec{x}$ ?



$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = D\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}}$$
 where  $D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix}$  and  $A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$ 

and we have an eigenbasis assoc'd with A given by

$$\mathcal{B} = \{ ec{v}_1, ec{v}_2 \}$$
 where  $ec{v}_1 = egin{bmatrix} 1 \\ 2 \end{bmatrix}$  ,  $ec{v}_2 = egin{bmatrix} 1 \\ -1 \end{bmatrix}$  .

$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = D\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}} \quad \text{where} \quad D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix} \quad \text{and} \quad A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$$

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$$\mathcal{B} = \{ ec{v}_1, ec{v}_2 \}$$
 where  $ec{v}_1 = egin{bmatrix} 1 \ 2 \end{bmatrix}$  ,  $ec{v}_2 = egin{bmatrix} 1 \ -1 \end{bmatrix}$  .

Recall that for any vector  $\vec{w}$  in  $\mathbb{R}^2$  we have

$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = D\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}}$$
 where  $D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix}$  and  $A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$ 

and we have an eigenbasis assoc'd with A given by

$$\mathcal{B} = \{ ec{v_1}, ec{v_2} \}$$
 where  $ec{v_1} = egin{bmatrix} 1 \ 2 \end{bmatrix}$  ,  $ec{v_2} = egin{bmatrix} 1 \ -1 \end{bmatrix}$  .

Recall that for any vector  $\vec{w}$  in  $\mathbb{R}^2$  we have

$$\vec{w} = P ig[ \vec{w} ig]_{\mathcal{B}}$$
 and

$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = D\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}}$$
 where  $D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix}$  and  $A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$ 

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Recall that for any vector  $\vec{w}$  in  $\mathbb{R}^2$  we have

$$ec{w} = Pig[ec{w}ig]_{\mathcal{B}} \quad ext{and} \quad ig[ec{w}ig]_{\mathcal{B}} = P^{-1}ec{w}$$

$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = D\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}}$$
 where  $D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix}$  and  $A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$ 

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$$\mathcal{B} = \{ ec{v}_1, ec{v}_2 \}$$
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Recall that for any vector  $\vec{w}$  in  $\mathbb{R}^2$  we have

$$\vec{w} = P[\vec{w}]_{\mathcal{B}}$$
 and  $[\vec{w}]_{\mathcal{B}} = P^{-1}\vec{w}$ 

where the  ${\mathcal B}$  to  ${\mathcal S}$  change of coordinates matrix is given by

$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = D\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}} \quad \text{where} \quad D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix} \quad \text{and} \quad A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$$

and we have an eigenbasis assoc'd with A given by

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where the  $\ensuremath{\mathcal{B}}$  to  $\ensuremath{\mathcal{S}}$  change of coordinates matrix is given by

$$P = P_{SB} =$$

$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = D\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}}$$
 where  $D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix}$  and  $A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$ 

and we have an eigenbasis assoc'd with A given by

$$\mathcal{B} = \{ ec{v}_1, ec{v}_2 \}$$
 where  $ec{v}_1 = egin{bmatrix} 1 \\ 2 \end{bmatrix}$  ,  $ec{v}_2 = egin{bmatrix} 1 \\ -1 \end{bmatrix}$  .

Recall that for any vector  $\vec{w}$  in  $\mathbb{R}^2$  we have

$$ec{w} = Pig[ec{w}ig]_{\mathcal{B}} \quad ext{and} \quad ig[ec{w}ig]_{\mathcal{B}} = P^{-1}ec{w}$$

where the  $\ensuremath{\mathcal{B}}$  to  $\ensuremath{\mathcal{S}}$  change of coordinates matrix is given by

$$P = P_{\mathcal{SB}} = \left[ \vec{v}_1 \ \vec{v}_2 
ight] =$$

$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = D\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}}$$
 where  $D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix}$  and  $A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$ 

and we have an eigenbasis assoc'd with A given by

$$\mathcal{B} = \{ ec{v}_1, ec{v}_2 \}$$
 where  $ec{v}_1 = egin{bmatrix} 1 \ 2 \end{bmatrix}$  ,  $ec{v}_2 = egin{bmatrix} 1 \ -1 \end{bmatrix}$  .

Recall that for any vector  $\vec{w}$  in  $\mathbb{R}^2$  we have

$$ec{w} = Pig[ec{w}ig]_{\mathcal{B}} \quad ext{and} \quad ig[ec{w}ig]_{\mathcal{B}} = P^{-1}ec{w}$$

where the  ${\cal B}$  to  ${\cal S}$  change of coordinates matrix is given by

$$P = P_{\mathcal{SB}} = \begin{bmatrix} \vec{v_1} & \vec{v_2} \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 2 & -1 \end{bmatrix}.$$

$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = D\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}}$$
 where  $D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix}$  and  $A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$ 

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$$\mathcal{B} = \{ ec{v}_1, ec{v}_2 \}$$
 where  $ec{v}_1 = egin{bmatrix} 1 \\ 2 \end{bmatrix}$  ,  $ec{v}_2 = egin{bmatrix} 1 \\ -1 \end{bmatrix}$  .

Recall that for any vector  $\vec{w}$  in  $\mathbb{R}^2$  we have

$$\vec{w} = P[\vec{w}]_{\mathcal{B}}$$
 and  $[\vec{w}]_{\mathcal{B}} = P^{-1}\vec{w}$ 

where the  $\ensuremath{\mathcal{B}}$  to  $\ensuremath{\mathcal{S}}$  change of coordinates matrix is given by

$$P = P_{SB} = \begin{bmatrix} \vec{v}_1 \ \vec{v}_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 2 & -1 \end{bmatrix}.$$

$$[\vec{x}]_{\mathcal{B}} = P^{-1}\vec{x}$$
 and

$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = D\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}}$$
 where  $D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix}$  and  $A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$ 

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$$\mathcal{B} = \{ ec{v}_1, ec{v}_2 \}$$
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Recall that for any vector  $\vec{w}$  in  $\mathbb{R}^2$  we have

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where the  $\ensuremath{\mathcal{B}}$  to  $\ensuremath{\mathcal{S}}$  change of coordinates matrix is given by

$$P = P_{SB} = \begin{bmatrix} \vec{v}_1 \ \vec{v}_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 2 & -1 \end{bmatrix}.$$

$$\left[\vec{x}\right]_{\mathcal{B}} = P^{-1}\vec{x}$$
 and  $A\vec{x} =$ 

$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = D\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}}$$
 where  $D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix}$  and  $A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$ 

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$$\mathcal{B} = \{ ec{v}_1, ec{v}_2 \}$$
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 and  $ig[ec{w}ig]_{\mathcal{B}} = P^{-1}ec{w}$ 

where the  $\ensuremath{\mathcal{B}}$  to  $\ensuremath{\mathcal{S}}$  change of coordinates matrix is given by

$$P = P_{\mathcal{SB}} = \begin{bmatrix} \vec{v}_1 \ \vec{v}_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 2 & -1 \end{bmatrix}.$$

$$\left[ \vec{x} \right]_{\mathcal{B}} = P^{-1} \vec{x}$$
 and  $A \vec{x} = P \left[ A \vec{x} \right]_{\mathcal{B}} =$ 

$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = D\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}}$$
 where  $D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix}$  and  $A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$ 

and we have an eigenbasis assoc'd with A given by

$$\mathcal{B} = \{ ec{v}_1, ec{v}_2 \}$$
 where  $ec{v}_1 = egin{bmatrix} 1 \\ 2 \end{bmatrix}$  ,  $ec{v}_2 = egin{bmatrix} 1 \\ -1 \end{bmatrix}$  .

Recall that for any vector  $\vec{w}$  in  $\mathbb{R}^2$  we have

$$ec{w} = Pig[ec{w}ig]_{\mathcal{B}} \quad ext{and} \quad ig[ec{w}ig]_{\mathcal{B}} = P^{-1}ec{w}$$

where the  $\ensuremath{\mathcal{B}}$  to  $\ensuremath{\mathcal{S}}$  change of coordinates matrix is given by

$$P = P_{\mathcal{SB}} = \begin{bmatrix} \vec{v}_1 \ \vec{v}_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 2 & -1 \end{bmatrix}.$$

$$\left[\vec{x}\right]_{\mathcal{B}} = P^{-1}\vec{x}$$
 and  $A\vec{x} = P\left[A\vec{x}\right]_{\mathcal{B}} = PD\left[\vec{x}\right]_{\mathcal{B}} =$ 

$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = D\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}}$$
 where  $D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix}$  and  $A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$ 

and we have an eigenbasis assoc'd with A given by

$$\mathcal{B} = \{ ec{v}_1, ec{v}_2 \}$$
 where  $ec{v}_1 = egin{bmatrix} 1 \\ 2 \end{bmatrix}$  ,  $ec{v}_2 = egin{bmatrix} 1 \\ -1 \end{bmatrix}$  .

Recall that for any vector  $\vec{w}$  in  $\mathbb{R}^2$  we have

$$\vec{w} = P[\vec{w}]_{\mathcal{B}}$$
 and  $[\vec{w}]_{\mathcal{B}} = P^{-1}\vec{w}$ 

where the  ${\mathcal B}$  to  ${\mathcal S}$  change of coordinates matrix is given by

$$P = P_{\mathcal{SB}} = \begin{bmatrix} \vec{v}_1 \ \vec{v}_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 2 & -1 \end{bmatrix}.$$

$$\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}} = P^{-1}\vec{x}$$
 and  $A\vec{x} = P \begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = PD \begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}} = PDP^{-1}\vec{x}$ .

$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = D\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}}$$
 where  $D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix}$  and  $A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$ 

and we have an eigenbasis assoc'd with A given by

$$\mathcal{B} = \{ ec{v}_1, ec{v}_2 \}$$
 where  $ec{v}_1 = egin{bmatrix} 1 \\ 2 \end{bmatrix}$  ,  $ec{v}_2 = egin{bmatrix} 1 \\ -1 \end{bmatrix}$  .

Recall that for any vector  $\vec{w}$  in  $\mathbb{R}^2$  we have

$$ec{w} = Pig[ec{w}ig]_{\mathcal{B}} \quad ext{and} \quad ig[ec{w}ig]_{\mathcal{B}} = P^{-1}ec{w}$$

where the  ${\mathcal B}$  to  ${\mathcal S}$  change of coordinates matrix is given by

$$P = P_{\mathcal{SB}} = \begin{bmatrix} \vec{v}_1 \ \vec{v}_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 2 & -1 \end{bmatrix}.$$

Thus

$$\left[\vec{x}\right]_{\mathcal{B}} = P^{-1}\vec{x}$$
 and  $A\vec{x} = P\left[A\vec{x}\right]_{\mathcal{B}} = PD\left[\vec{x}\right]_{\mathcal{B}} = PDP^{-1}\vec{x}$ .

So,

$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = D\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}}$$
 where  $D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix}$  and  $A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$ 

and we have an eigenbasis assoc'd with A given by

$$\mathcal{B} = \{ ec{v}_1, ec{v}_2 \} \quad \text{where} \quad ec{v}_1 = egin{bmatrix} 1 \\ 2 \end{bmatrix} \;, \;\; ec{v}_2 = egin{bmatrix} 1 \\ -1 \end{bmatrix}.$$

Recall that for any vector  $\vec{w}$  in  $\mathbb{R}^2$  we have

$$\vec{w} = P ig[ \vec{w} ig]_{\mathcal{B}} \quad \text{and} \quad ig[ \vec{w} ig]_{\mathcal{B}} = P^{-1} \vec{w}$$

where the  $\ensuremath{\mathcal{B}}$  to  $\ensuremath{\mathcal{S}}$  change of coordinates matrix is given by

$$P = P_{SB} = \begin{bmatrix} \vec{v}_1 \ \vec{v}_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 2 & -1 \end{bmatrix}.$$

Thus

$$\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}} = P^{-1}\vec{x}$$
 and  $A\vec{x} = P \begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = PD \begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}} = PDP^{-1}\vec{x}$ .

So,

$$A = PDP^{-1} \text{ where } D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \ , \ P = \begin{bmatrix} \vec{v}_1 \ \vec{v}_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 2 & -1 \end{bmatrix}.$$

$$\begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = D\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}}$$
 where  $D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix}$  and  $A = \begin{bmatrix} 1 & 2 \\ 4 & 3 \end{bmatrix}$ 

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Recall that for any vector  $\vec{w}$  in  $\mathbb{R}^2$  we have

$$\vec{w} = P[\vec{w}]_{\mathcal{B}}$$
 and  $[\vec{w}]_{\mathcal{B}} = P^{-1}\vec{w}$ 

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Thus

$$\begin{bmatrix} \vec{x} \end{bmatrix}_{\mathcal{B}} = P^{-1}\vec{x}$$
 and  $A\vec{x} = P \begin{bmatrix} A\vec{x} \end{bmatrix}_{\mathcal{B}} = PD[\vec{x}]_{\mathcal{B}} = PDP^{-1}\vec{x}$ .

So,

$$A = PDP^{-1} \text{ where } D = \begin{bmatrix} 5 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \ , \ P = \begin{bmatrix} \vec{v}_1 \ \vec{v}_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 2 & -1 \end{bmatrix}.$$

We say that A and D are similar matrices.