

# Subspaces of Euclidean Space $\mathbb{R}^n$

Linear Algebra  
MATH 2076



## Vector Subspaces—Basic Example

$\mathbb{V}$  is a *vector subspace* (of  $\mathbb{R}^n$ ) if and only if

- $\vec{0}$  is in  $\mathbb{V}$ ,
- $\mathbb{V}$  closed with respect to vector addition ( $\vec{u}, \vec{v}$  in  $\mathbb{V} \implies \vec{u} + \vec{v}$  in  $\mathbb{V}$ )
- $\mathbb{V}$  closed with respect to scalar mult ( $s$  scalar,  $\vec{v}$  in  $\mathbb{V} \implies s\vec{v}$  in  $\mathbb{V}$ )

### Example (Basic Vector SubSpace)

For any  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$  in  $\mathbb{R}^n$ ,  $\text{Span}\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p\}$  is a vector subspace.

# Column Space of a Matrix

Let  $A = [\vec{a}_1 \ \vec{a}_2 \ \dots \ \vec{a}_n]$  be an  $m \times n$  matrix; so, each  $\vec{a}_j$  is in  $\mathbb{R}^m$ .

The *column space*  $\mathcal{CS}(A)$  of  $A$  is the span of the columns of  $A$ , i.e.,  
 $\mathcal{CS}(A) = \text{Span}\{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n\}$ .

## Three Ways to View $\mathcal{CS}(A)$

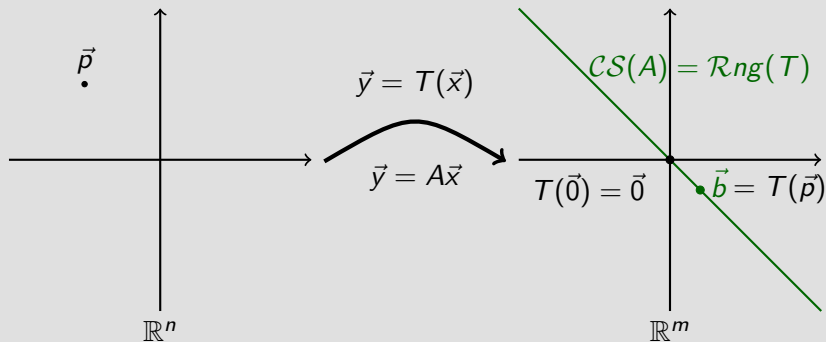
The column space  $\mathcal{CS}(A)$  of  $A = [\vec{a}_1 \ \vec{a}_2 \ \dots \ \vec{a}_n]$  is:

- $\mathcal{CS}(A) = \text{Span}\{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n\}$
- $\mathcal{CS}(A) = \{\vec{b} \text{ in } \mathbb{R}^m \mid A\vec{x} = \vec{b} \text{ has a solution}\}$
- $\mathcal{CS}(A) = \mathcal{Rng}(T)$  where  $\mathbb{R}^n \xrightarrow{T} \mathbb{R}^m$  is  $T(\vec{x}) = A\vec{x}$

## Three Ways to View the Column Space $\mathcal{CS}(A)$

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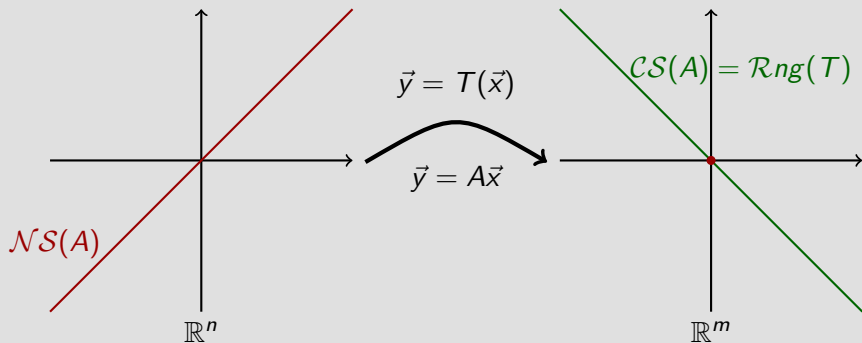


## Vector Subspaces—Another Basic Example

Again, let  $A$  be an  $m \times n$  matrix. The *null space*  $\mathcal{N}\mathcal{S}(A)$  of  $A$  is

$$\mathcal{N}\mathcal{S}(A) = \{\vec{x} \mid A\vec{x} = \vec{0}\};$$

just the solution set for the homogeneous equation  $A\vec{x} = \vec{0}$ . This is a vector subspace of  $\mathbb{R}^n$ .



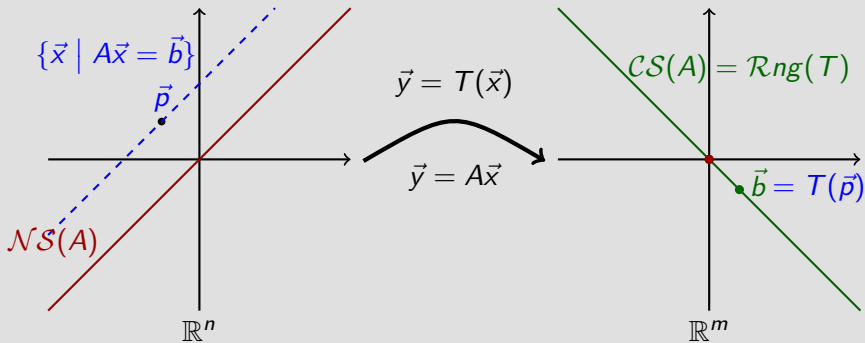
$A = [\vec{a}_1 \ \vec{a}_2 \ \dots \ \vec{a}_n]$  an  $m \times n$  matrix and  $\mathbb{R}^n \xrightarrow{T} \mathbb{R}^m$  is  $T(\vec{x}) = A\vec{x}$

$$\mathcal{NS}(A) = \{\vec{x} \mid A\vec{x} = \vec{0}\} \quad \text{and}$$

$$\mathcal{CS}(A) = \text{Span}\{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n\}$$

$$= \{\vec{b} \text{ in } \mathbb{R}^m \mid A\vec{x} = \vec{b} \text{ has a solution}\}$$

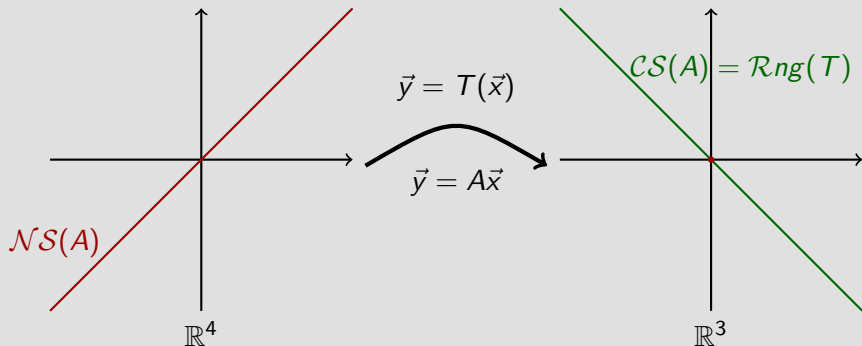
$$= \mathcal{CS}(A) = \mathcal{Rng}(T)$$



# Null Space and Column Space Example

Find the null space and column space of

$$A = \begin{bmatrix} 1 & -1 & 1 & 2 \\ 1 & 0 & 1 & 1 \\ 1 & 2 & 1 & -1 \end{bmatrix}$$



What should we do now? How about row reducing  $A$ ?

## “Finding” Null Space and Column Space

To “find” the null space  $\mathcal{NS}(A)$  and column space  $\mathcal{CS}(A)$  of a matrix  $A$ :

- row reduce  $A$  to  $E$ , a REF (or RREF) for  $A$
- columns of  $E$  containing row leaders correspond to *pivot* columns of  $A$
- the *pivot* columns of  $A$  are LI and span  $\mathcal{CS}(A)$
- write the SS for  $A\vec{x} = \vec{0}$  in parametric vector form
- identify LI vectors that span  $\mathcal{NS}(A)$

So, “find” means to find a *linearly independent spanning* set.



## Example—Null Space and Column Space

Find the null space and column space of

$$A = \begin{bmatrix} 1 & 2 & 3 & 4 & 5 \\ 0 & 1 & 1 & 1 & 0 \\ 3 & 6 & 9 & 2 & -5 \\ 2 & 4 & 6 & 1 & -4 \end{bmatrix}$$