

# Vector Equations Matrix Equations Linear Combinations

Linear Algebra  
MATH 2076



## Three Views of Same Idea

Let  $\vec{a}_j$  be the  $j^{\text{th}}$  column of the coefficient matrix  $A$  for some SLE

$$\begin{array}{r} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2 \\ \vdots \qquad \qquad \qquad \vdots \qquad \qquad \qquad \vdots \qquad \qquad \qquad \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m \end{array}$$



## Three Views of Same Idea

Let  $\vec{a}_j$  be the  $j^{\text{th}}$  column of the coefficient matrix  $A$  for some SLE

$$\begin{array}{r} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2 \\ \vdots \qquad \qquad \qquad \vdots \qquad \qquad \qquad \vdots \qquad \qquad \qquad \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m \end{array}$$

The above SLE has exactly the same solutions as the vector equation

$$x_1\vec{a}_1 + x_2\vec{a}_2 + \cdots + x_n\vec{a}_n = \vec{b}$$

# Three Views of Same Idea

Let  $\vec{a}_j$  be the  $j^{\text{th}}$  column of the coefficient matrix  $A$  for some SLE

$$\begin{array}{cccc} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n & = & b_1 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n & = & b_2 \\ \vdots & & \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n & = & b_m \end{array}$$

The above SLE has exactly the same solutions as the vector equation

$$x_1\vec{a}_1 + x_2\vec{a}_2 + \cdots + x_n\vec{a}_n = \vec{b}$$

which in turn has exactly the same solutions as the matrix equation

$$A\vec{x} = \vec{b}.$$

# REF Solution Information

Look at a REF for the *augmented* matrix associated with the SLE.

## REF Solution Information

Look at a REF for the *augmented* matrix associated with the SLE.  
If the last column has a row leader, there are NO solutions;

## REF Solution Information

Look at a REF for the *augmented* matrix associated with the SLE.  
If the last column has a row leader, there are NO solutions;  
assume otherwise.



## REF Solution Information

Look at a REF for the *augmented* matrix associated with the SLE.  
If the last column has a row leader, there are NO solutions;  
assume otherwise.

Identify the columns that do *not* have row leaders;

## REF Solution Information

Look at a REF for the *augmented* matrix associated with the SLE. If the last column has a row leader, there are NO solutions; assume otherwise.

Identify the columns that do *not* have row leaders; the corresponding variables are *free*.

## REF Solution Information

Look at a REF for the *augmented* matrix associated with the SLE. If the last column has a row leader, there are NO solutions; assume otherwise.

Identify the columns that do *not* have row leaders; the corresponding variables are *free*.

If there are no free variables, get a unique solution; if there are free variables, get infinitely many solutions and need to describe all of them.

## REF Solution Information

Look at a REF for the *augmented* matrix associated with the SLE.  
If the last column has a row leader, there are NO solutions;  
assume otherwise.

Identify the columns that do *not* have row leaders; the corresponding variables are *free*.

If there are no free variables, get a unique solution; if there are free variables, get infinitely many solutions and need to describe all of them.

Each *basic* (aka, non-free) variable can be expressed in terms of the free variables.

## REF Solution Information

Look at a REF for the *augmented* matrix associated with the SLE. If the last column has a row leader, there are NO solutions; assume otherwise.

Identify the columns that do *not* have row leaders; the corresponding variables are *free*.

If there are no free variables, get a unique solution; if there are free variables, get infinitely many solutions and need to describe all of them.

Each *basic* (aka, non-free) variable can be expressed in terms of the free variables. We can do this by back substitution, or by continuing to row reduce to get reduced REF.

# Linear Combinations

Suppose  $s_1, s_2, \dots, s_p$  are scalars and  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$  are vectors (all in the same space  $\mathbb{R}^n$ ).

# Linear Combinations

Suppose  $s_1, s_2, \dots, s_p$  are scalars and  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$  are vectors (all in the same space  $\mathbb{R}^n$ ). We call

$$s_1 \vec{v}_1 + s_2 \vec{v}_2 + \dots + s_p \vec{v}_p$$

a *linear combination* of the vectors  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$ .

# Linear Combinations

Suppose  $s_1, s_2, \dots, s_p$  are scalars and  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$  are vectors (all in the same space  $\mathbb{R}^n$ ). We call

$$s_1 \vec{v}_1 + s_2 \vec{v}_2 + \cdots + s_p \vec{v}_p$$

a *linear combination* of the vectors  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$ . For example, we always have the *trivial* linear combination

$$0 \cdot \vec{v}_1 + 0 \cdot \vec{v}_2 + \cdots + 0 \cdot \vec{v}_p = \vec{0}.$$



# Linear Combinations

Suppose  $s_1, s_2, \dots, s_p$  are scalars and  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$  are vectors (all in the same space  $\mathbb{R}^n$ ). We call

$$s_1 \vec{v}_1 + s_2 \vec{v}_2 + \dots + s_p \vec{v}_p$$

a *linear combination* of the vectors  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$ . For example, we always have the *trivial* linear combination

$$0 \cdot \vec{v}_1 + 0 \cdot \vec{v}_2 + \dots + 0 \cdot \vec{v}_p = \vec{0}.$$

We'll be most interested in the set of *all* LCs of  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$ .

# Linear Combinations

Suppose  $s_1, s_2, \dots, s_p$  are scalars and  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$  are vectors (all in the same space  $\mathbb{R}^n$ ). We call

$$s_1 \vec{v}_1 + s_2 \vec{v}_2 + \dots + s_p \vec{v}_p$$

a *linear combination* of the vectors  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$ . For example, we always have the *trivial* linear combination

$$0 \cdot \vec{v}_1 + 0 \cdot \vec{v}_2 + \dots + 0 \cdot \vec{v}_p = \vec{0}.$$

We'll be most interested in the set of *all* LCs of  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$ . We call this the *span* of the vectors  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$ , and write it as

$$\text{Span}\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p\}.$$

# Solutions

Remember that a vector equation such as

$$x_1\vec{a}_1 + x_2\vec{a}_2 + \cdots + x_n\vec{a}_n = \vec{b}$$

has a solution if and only if the rhs  $\vec{b}$  is a LC of  $\vec{a}_1, \dots, \vec{a}_n$ .

# Solutions

Remember that a vector equation such as

$$x_1\vec{a}_1 + x_2\vec{a}_2 + \cdots + x_n\vec{a}_n = \vec{b}$$

has a solution if and only if the rhs  $\vec{b}$  is a LC of  $\vec{a}_1, \dots, \vec{a}_n$ .

This means that there is a solution if and only if  $\vec{b}$  belongs to

$$\text{Span}\{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n\}.$$

# Solutions

Remember that a vector equation such as

$$x_1\vec{a}_1 + x_2\vec{a}_2 + \cdots + x_n\vec{a}_n = \vec{b}$$

has a solution if and only if the rhs  $\vec{b}$  is a LC of  $\vec{a}_1, \dots, \vec{a}_n$ .

This means that there is a solution if and only if  $\vec{b}$  belongs to

$$\text{Span}\{\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n\}.$$

This does not tell us how to find the solution.

# Theorem 4—bottom of page 37 in Section 1.4

# Theorem 4—bottom of page 37 in Section 1.4

Look at this!