# Vectors, Equations, Linear Combinations

Linear Algebra MATH 2076



Recall that a *matrix* is a rectangular array of numbers.

We call

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

an  $m \times n$  matrix; it has *m* rows and *n* columns.

We write  $\mathbb{R}^{m \times n}$  for the space of all  $m \times n$  matrices.

### Vectors

Matrices that have just a single row, or a single column, are often called *row vectors*, or *column vectors*. For us, a *vector* is always a column vector, that is, a matrix with exactly one column. So, a vector is an  $n \times 1$  matrix, where *n* is the number of rows (or entries, or coordinates).

It is useful to adopt a notation that helps distinguish between numbers (aka scalars), matrices, and vectors; I'll use arrows. Thus a vector of "size" n (i.e., with n coordinates) is written as

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \text{ where } x_1, x_2, \dots, x_n \text{ are the coordinates of } \vec{x}.$$

The space of all such vectors, of "size" n, is  $\mathbb{R}^{n \times 1}$ . We usually just write  $\mathbb{R}^n$ , but this is not exactly correct, is it?

# Vector Arithmetic

We can add two vectors, provided they have the same number of coordinates. If  $\vec{x}$  and  $\vec{y}$  are both in  $\mathbb{R}^n$ , say with coordinates  $x_1, \ldots, x_n$  and  $y_1, \ldots, y_n$ , then

$$\vec{x} + \vec{y} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} + \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} x_1 + y_1 \\ x_2 + y_2 \\ \vdots \\ x_n + yn \end{bmatrix}$$

We can also multiply vectors by scalars. If s is any scalar, then

$$s\vec{x} = s \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} s & x_1 \\ s & x_2 \\ \vdots \\ s & x_n \end{bmatrix}.$$

#### Linear Combinations

Suppose  $s_1, s_2, \ldots, s_p$  are scalars and  $\vec{v_1}, \vec{v_2}, \ldots, \vec{v_p}$  are vectors (all in the same space  $\mathbb{R}^n$ ). We call

$$s_1\vec{v}_1+s_2\vec{v}_2+\cdots+s_p\vec{v}_p$$

a *linear combination* of the vectors  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$ . For example, we always have the *trivial* linear combination

$$0\cdot \vec{v_1} + 0\cdot \vec{v_2} + \cdots + 0\cdot \vec{v_p} = \vec{0}.$$

Consider the vectors 
$$\vec{e_1} = \begin{bmatrix} 1\\0\\0 \end{bmatrix}$$
,  $\vec{e_2} = \begin{bmatrix} 0\\1\\0 \end{bmatrix}$ ,  $\vec{e_3} = \begin{bmatrix} 0\\0\\1 \end{bmatrix}$ . Notice that  
 $x_1\vec{e_1} + x_2\vec{e_2} + x_3\vec{e_3} = x_1\begin{bmatrix} 1\\0\\0 \end{bmatrix} + x_2\begin{bmatrix} 0\\1\\0 \end{bmatrix} + x_3\begin{bmatrix} 0\\0\\1 \end{bmatrix} = \begin{bmatrix} x_1\\x_2\\x_3 \end{bmatrix}$ .

Thus every vector in  $\mathbb{R}^3$  can be expressed as a LC of  $\vec{e_1}, \vec{e_2}, \vec{e_3}$ .

Linear Algebra

# Vector Equations

Let  $\vec{a_1}, \ldots, \vec{a_n}$  and  $\vec{b}$  be given vectors (all in the same space  $\mathbb{R}^m$ ). Then  $x_1\vec{a_1} + x_2\vec{a_2} + \cdots + x_n\vec{a_n} = \vec{b}$ 

is called a *vector equation*; here  $x_1, x_2, ..., x_n$  are the variables. For example, the vector equation

$$x_1 \vec{e_1} + x_2 \vec{e_2} + x_3 \vec{e_3} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

has solution  $x_1 = b_1, x_2 = b_2, x_3 = b_3$ , or more simply,  $\vec{x} = \vec{b}$ .

Notice that the above vector equation (at top of page) has a solution if and only if the rhs  $\vec{b}$  is a LC of  $\vec{a_1}, \ldots, \vec{a_n}$ . Right?

If A is the coefficient matrix for some SLE, and  $\vec{a}_j$  is the  $j^{\text{th}}$  column of A, then

$$x_1\vec{a}_1 + x_2\vec{a}_2 + \dots + x_n\vec{a}_n = \vec{b}$$

has exactly the same solutions as the original SLE. Thus, an SLE has a solution if and only if ....

Linear Algebra

# Matrix Multiplication—preliminary product

Let  $\vec{x}$  be a vector in  $\mathbb{R}^n$  and A a matrix in  $\mathbb{R}^{m \times n}$ . So

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \text{ and } A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

The product  $A\vec{x}$  is defined to be the LC

$$x_1\vec{a}_1 + x_2\vec{a}_2 + \cdots + x_n\vec{a}_n$$

where  $\vec{a_j}$  is the  $j^{\text{th}}$  column of A. If  $\vec{b}$  is a vector in  $\mathbb{R}^m$ , we call  $A\vec{x} = \vec{b}$  a matrix equation; here  $\vec{x}$  is the variable.

#### Three Views of Same Idea

Let  $\vec{a}_i$  be the  $j^{\text{th}}$  column of the coefficient matrix A for some SLE

$$a_{11}x_{1} + a_{12}x_{2} + \dots + a_{1n}x_{n} = b_{1}$$
  

$$a_{21}x_{1} + a_{22}x_{2} + \dots + a_{2n}x_{n} = b_{2}$$
  

$$\vdots \qquad \vdots \qquad \vdots \qquad \vdots \qquad \vdots$$
  

$$a_{m1}x_{1} + a_{m2}x_{2} + \dots + a_{mn}x_{n} = b_{m}$$

The above SLE has exactly the same solutions as the vector equation

$$x_1\vec{a}_1 + x_2\vec{a}_2 + \dots + x_n\vec{a}_n = \vec{b}$$

which in turn has exactly the same solutions as the matrix equation

$$A\vec{x} = \vec{b}.$$