

Ch. 9 Scalar ($j=0$) particles in 3d

$$|\vec{r}\rangle = |x, y, z\rangle = |x, x_2, x_3\rangle \quad (\text{not 'n'})$$

$$\hat{X}_i |\vec{r}\rangle = x_i |\vec{r}\rangle, \quad \hat{\vec{X}} |\vec{r}\rangle = \vec{r} |\vec{r}\rangle$$

on basis

$$\begin{cases} \langle \vec{r} | \vec{r}' \rangle = \delta^3(\vec{r} - \vec{r}') = \delta(x_1 - x_1') \delta(x_2 - x_2') \delta(x_3 - x_3') \\ 1 = \int d^3r |\vec{r}\rangle \langle \vec{r}| \end{cases}$$

Wavefunc:

$$\begin{cases} \psi(\vec{r}) \equiv \langle \vec{r} | \psi \rangle \\ |\psi\rangle = \int d^3r \psi(\vec{r}) |\vec{r}\rangle \end{cases}$$

$$\langle \psi | \psi \rangle = 1 \Rightarrow \int d^3r |\psi(\vec{r})|^2 = 1$$

$$\Rightarrow \text{Prob}(\vec{r}, \vec{r} + d\vec{r}) = d^3r |\psi(\vec{r})|^2$$

$$\hat{P}_i |\vec{r}\rangle = i\hbar \frac{\partial}{\partial x_i} |\vec{r}\rangle \sim \hat{\vec{P}} |\vec{r}\rangle = i\hbar \vec{\nabla}_{\vec{r}} |\vec{r}\rangle$$

Mom. basis

$$|\vec{p}\rangle = |p_x, p_y, p_z\rangle = |p_1, p_2, p_3\rangle$$

$$\hat{P}_i |\vec{p}\rangle = p_i |\vec{p}\rangle \sim \hat{\vec{P}} |\vec{p}\rangle = \vec{p} |\vec{p}\rangle \text{ etc...}$$

$$\langle \vec{r} | \vec{p} \rangle = \frac{1}{(2\pi\hbar)^{3/2}} e^{i\vec{p} \cdot \vec{r} / \hbar}$$

$$[\hat{X}_{ij}, \hat{P}_j] = i\hbar \delta_{ij}$$

Particle in 3d in B-field & E-field

$$\hat{H}_0 = \frac{1}{2m} (\hat{\vec{p}} - q \vec{A}(\hat{\vec{x}}, t))^2 + q V(\hat{\vec{x}}, t)$$

$$\text{when: } \vec{B}(\vec{x}, t) = \vec{\nabla} \times \vec{A}, \quad \vec{E}(\vec{x}, t) = -\vec{\nabla} V - \frac{\partial}{\partial t} \vec{A}$$

$$\text{t-indep't B-fld only: } \vec{A} = \vec{A}(\vec{x}), V=0 \Rightarrow$$

$$\hat{H}_0 = \frac{1}{2m} (\hat{\vec{p}} - q \vec{A}(\hat{\vec{x}}))^2 = \frac{1}{2m} \hat{\vec{p}} \cdot \hat{\vec{p}} - \frac{q}{mc} (\hat{\vec{p}} \cdot \vec{A}(\vec{x}) + \vec{A}(\vec{x}) \cdot \hat{\vec{p}}) + \frac{q^2}{2mc^2} \vec{A}(\vec{x}) \cdot \vec{A}(\vec{x})$$

2 particles in central potential

$$\hat{H} = \frac{1}{2m_1} \hat{\vec{p}}_1^2 + \frac{1}{2m_2} \hat{\vec{p}}_2^2 + V(|\hat{\vec{r}}_1 - \hat{\vec{r}}_2|)$$

$$\hat{\vec{p}}^2 \doteq \hat{\vec{p}} \cdot \hat{\vec{p}}$$

$$|\hat{\vec{r}}| \doteq (\hat{\vec{r}} \cdot \hat{\vec{r}})^{1/2}$$

- Define: C.O.M. & relative coordinates (operators)

$$\hat{\vec{P}} \doteq \hat{\vec{p}}_1 + \hat{\vec{p}}_2 \quad \hat{\vec{p}} \doteq \frac{m_2 \hat{\vec{p}}_1 - m_1 \hat{\vec{p}}_2}{m_1 + m_2}$$

$$\hat{\vec{R}} \doteq \frac{m_1 \hat{\vec{r}}_1 + m_2 \hat{\vec{r}}_2}{m_1 + m_2} \quad \hat{\vec{r}} \doteq \hat{\vec{r}}_1 - \hat{\vec{r}}_2$$

Check:

$$[\hat{\vec{R}}, \hat{\vec{p}}] = 0$$

$$[\hat{R}_i, \hat{p}_j] = i\hbar \delta_{ij} \quad [\hat{\vec{r}}, \hat{\vec{P}}] = 0$$

$$[\hat{r}_i, \hat{p}_j] = i\hbar \delta_{ij}$$

$$\hat{H} = \underbrace{\frac{1}{2M} \hat{\vec{P}}^2}_{\hat{H}_{CM}} + \underbrace{\frac{1}{2\mu} \hat{\vec{p}}^2 + V(\hat{r})}_{\hat{H}_{rel}} \quad \begin{cases} \hat{r} \equiv \sqrt{\hat{r}^2} = \sqrt{\hat{\vec{r}} \cdot \hat{\vec{r}}} \\ M \equiv m_1 + m_2 \\ \mu \equiv \frac{m_1 m_2}{m_1 + m_2} \end{cases}$$

$$\mathcal{H}_1 \otimes \mathcal{H}_2 \simeq \mathcal{H}_{CM} \otimes \mathcal{H}_{rel} \quad (*)$$

$$\{|\vec{r}_1, \vec{r}_2\rangle\} \xrightarrow{\text{c.o.b.}} \{|\vec{R}, \vec{r}\rangle\}$$

$$(|\vec{r}_1, \vec{r}_2\rangle)_{1,2} = \left| \frac{m_1 \vec{r}_1 + m_2 \vec{r}_2}{M}, \vec{r}_1 - \vec{r}_2 \right\rangle_{CM}$$

Check: $[\hat{H}_{CM}, \hat{H}_{rel}] = 0$

$\Rightarrow \mathcal{H}_{CM} \times \mathcal{H}_{rel}$ "decouple":

$$\hat{H}_{cm} |E_{cm}\rangle = E_{cm} |E_{cm}\rangle \quad \& \quad \hat{H}_{rel} |E_{rel}\rangle = E_{rel} |E_{rel}\rangle$$

$$\Rightarrow |E\rangle = |E_{cm}\rangle \otimes |E_{rel}\rangle \Rightarrow \hat{H} |E\rangle = E |E\rangle \quad \text{w/ } E = E_{cm} + E_{rel}$$

"Separation of variables". $\longleftrightarrow$ factorize: $H = H_A \otimes H_B$ (*)

• H_{cm} part: $\hat{H}_{cm} = \frac{1}{2M} \hat{P}^2 \Rightarrow$ free particle
of mass $M = m_1 + m_2$

$\Rightarrow$ eigenstates all "scattering" states
of overall momentum: $|\vec{P}\rangle$

• F.N.O.: ignore! Only interested in relative motion:

• $\hat{H}_{rel} \equiv \hat{H} = \frac{1}{2\mu} \hat{P}^2 + V(\hat{r})$

$\approx$ 'particle' of mass μ in 3d central pot'l $V(r)$.

$$H_{rel} \equiv H \quad \text{Hilb. space.}$$

• $\hat{H}$ has rotational symmetry around origin ($\vec{r}=0$)

$\therefore$ (1) work in spherical coordinates

(2) angular momentum $\vec{L} \equiv \vec{r} \times \vec{p}$ is conserved.

Goal: further separation of variables $H = H_r \otimes H_{\theta, \varphi}$
radial $\quad$ angular

$\& \quad H_{\theta, \varphi} = \bigoplus_{j=0}^{\infty} H_j$ $\swarrow$ ang. mom. H.S. $\{ |j, m\rangle, |m| \leq j \}$

• Summary:

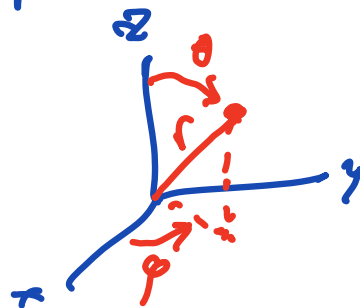
$$\begin{aligned}\mathcal{H}_{2\text{-particle}} &= \mathcal{H}_1 \otimes \mathcal{H}_2 = \mathcal{H}_{1x} \otimes \mathcal{H}_{1y} \otimes \mathcal{H}_{1z} \otimes \mathcal{H}_{2x} \otimes \mathcal{H}_{2y} \otimes \mathcal{H}_{2z} \\ &= \mathcal{H}_{rel} \otimes \mathcal{H}_{cm} \\ &= \mathcal{H}_r \otimes \left(\bigoplus_{j=0}^{\infty} \mathcal{H}_j \right) \otimes \mathcal{H}_{cm}\end{aligned}$$

(1) Spherical Coordinates (review)

$$(x, y, z) \leftrightarrow (r, \theta, \varphi) \equiv \vec{r}$$

$$\begin{cases} x = r \sin \theta \cos \varphi \\ y = r \sin \theta \sin \varphi \\ z = r \cos \theta \end{cases}$$

$$\begin{cases} r = \sqrt{x^2 + y^2 + z^2} \\ \theta = \dots \\ \varphi = \dots \end{cases}$$



$$0 \leq \theta \leq \pi \quad \text{not periodic!}$$

$$0 \leq \varphi < 2\pi \quad \text{periodic!}$$

$$\vec{\nabla} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right) = ? \text{ in sph. coords?}$$

Chain rule: $\frac{\partial}{\partial r} = \frac{\partial x}{\partial r} \frac{\partial}{\partial x} + \frac{\partial y}{\partial r} \frac{\partial}{\partial y} + \frac{\partial z}{\partial r} \frac{\partial}{\partial z}$

$$\frac{\partial}{\partial \theta} = \dots$$

$$\frac{\partial}{\partial \varphi} = \dots$$

$$\frac{\partial x}{\partial r} = \frac{x}{r}, \dots \Rightarrow r \frac{\partial}{\partial r} = x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + z \frac{\partial}{\partial z} = \vec{r} \cdot \vec{\nabla}$$

$$\frac{\partial x}{\partial \varphi} = -y, \frac{\partial y}{\partial \varphi} = x, \frac{\partial z}{\partial \varphi} = 0$$

$$\therefore \frac{\partial}{\partial \varphi} = x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} = \hat{e}_z \cdot (\vec{r} \times \vec{\nabla})$$

$$\Delta \quad \frac{\partial x}{\partial \theta} = z \cos \varphi, \quad \frac{\partial y}{\partial \theta} = z \sin \varphi, \quad \frac{\partial z}{\partial \theta} = -r \sin \theta$$

$$\therefore \left[\frac{\partial}{\partial \theta} = \dots \text{ messy} \right]$$

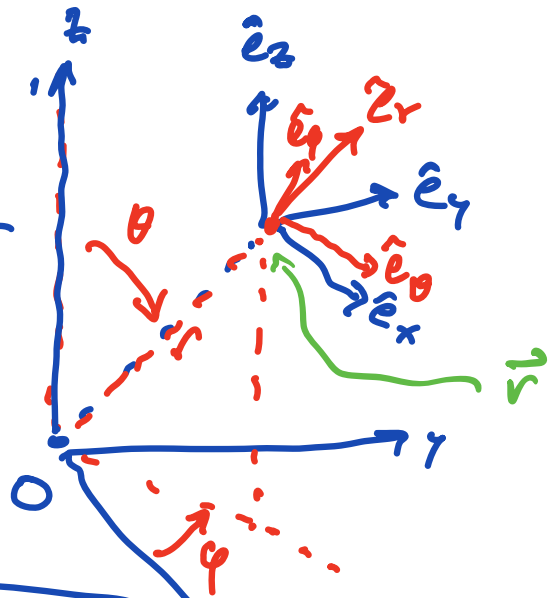
$$\vec{\nabla} = \hat{e}_x \frac{\partial}{\partial x} + \hat{e}_y \frac{\partial}{\partial y} + \hat{e}_z \frac{\partial}{\partial z}$$

Geometry $\Rightarrow$

$$\hat{e}_r = \frac{\vec{r}}{r} = \frac{x \hat{e}_x + y \hat{e}_y + z \hat{e}_z}{r}$$

$$\hat{e}_\theta = \frac{\partial \vec{r}}{\partial \theta} = \frac{1}{r} \left(\frac{\partial x}{\partial \theta} \hat{e}_x + \frac{\partial y}{\partial \theta} \hat{e}_y + \frac{\partial z}{\partial \theta} \hat{e}_z \right)$$

$$\hat{e}_\varphi = \frac{\partial \vec{r}}{\partial \varphi} = \dots$$



CartesianSpherical

$$d\vec{r} = dx \hat{e}_x + dy \hat{e}_y + dz \hat{e}_z = dr \hat{e}_r + r d\theta \hat{e}_\theta + r \sin\theta d\varphi \hat{e}_\varphi$$

$$\vec{r} = x \hat{e}_x + y \hat{e}_y + z \hat{e}_z = r \hat{e}_r \quad \text{with } dV = r^2 \sin\theta dr d\theta d\varphi$$

$$\left. \begin{aligned} \hat{e}_x &= \sin\theta \cos\varphi \hat{e}_r + \cos\theta \cos\varphi \hat{e}_\theta - \sin\varphi \hat{e}_\varphi \\ \hat{e}_y &= \sin\theta \sin\varphi \hat{e}_r + \cos\theta \sin\varphi \hat{e}_\theta + \cos\varphi \hat{e}_\varphi \\ \hat{e}_z &= \cos\theta \hat{e}_r - \sin\theta \hat{e}_\theta \end{aligned} \right\} \begin{aligned} \hat{e}_r &= \sin\theta \cos\varphi \hat{e}_x + \sin\theta \sin\varphi \hat{e}_y + \cos\theta \hat{e}_z \\ \hat{e}_\theta &= \cos\theta \cos\varphi \hat{e}_x + \cos\theta \sin\varphi \hat{e}_y - \sin\theta \hat{e}_z \\ \hat{e}_\varphi &= -\sin\varphi \hat{e}_x + \cos\varphi \hat{e}_y \end{aligned}$$

$$\vec{\nabla} = \hat{e}_r \frac{\partial}{\partial r} + \hat{e}_\theta \frac{1}{r} \frac{\partial}{\partial \theta} + \hat{e}_\varphi \frac{1}{r \sin\theta} \frac{\partial}{\partial \varphi}$$

$$\frac{\partial}{\partial r}(\hat{e}_r, \hat{e}_\theta, \hat{e}_\varphi) = 0, \text{ but } \left(\frac{\partial}{\partial \theta}, \frac{\partial}{\partial \varphi}\right)(\hat{e}_r, \hat{e}_\theta, \hat{e}_\varphi) \neq 0! \Rightarrow \dots$$

$$\vec{\nabla} \cdot \vec{A} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) + \frac{1}{r \sin\theta} \frac{\partial}{\partial \theta} (\sin\theta A_\theta) + \frac{1}{r \sin\theta} \frac{\partial}{\partial \varphi} (A_\varphi)$$

$$\vec{\nabla} \times \vec{A} = \dots$$

$$\text{w/ } \vec{A} = A_r \hat{e}_r + A_\theta \hat{e}_\theta + A_\varphi \hat{e}_\varphi.$$

$$\nabla^2 f = \vec{\nabla} \cdot \vec{\nabla} f = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial f}{\partial r} \right) + \frac{1}{r^2 \sin\theta} \frac{\partial}{\partial \theta} \left(\sin\theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{r^2 \sin^2\theta} \frac{\partial^2 f}{\partial \varphi^2}$$

(2) Angular momentum ("Orbital")

$$\vec{L} = \vec{r} \times \vec{p} \quad \Leftrightarrow \quad L_i = \sum_{j,k=1}^3 \epsilon_{ijk} r_j p_k$$

$$\& [\hat{L}_i, \hat{L}_j] = i\hbar \sum_k \epsilon_{ijk} \hat{L}_k \quad (\text{follows from } [\hat{x}_i, \hat{p}_j] = i\hbar \delta_{ij})$$

$$2 \Rightarrow [\hat{L}_i, \hat{p}_j] = i\hbar \sum_k \epsilon_{ijk} \hat{p}_k \Rightarrow [\hat{L}_i, \hat{p}^2] = 0$$

$$[\hat{L}_i, \hat{r}_j] = i\hbar \sum_k \epsilon_{ijk} \hat{r}_k \Rightarrow [\hat{L}_i, \hat{r}^2] = 0 \Rightarrow [\hat{L}_i, \hat{r}] = 0.$$

$$\therefore [\hat{L}_i, \hat{H}] = 0 \quad \checkmark$$

• Choose max. commuting subset of $\hat{L}_i, \hat{L}^2, \hat{p}_i, \hat{p}^2, \hat{r}_i, \hat{r}^2, \hat{H}$

$\Rightarrow \hat{H}, \hat{L}^2, \hat{L}_z \Rightarrow$ common eigenstates $|n, l, m\rangle$

$$\hat{H}|n, l, m\rangle = E_n |n, l, m\rangle \quad n = 1, 2, 3, \dots \quad E_n ??$$

$$\hat{L}^2 |n, l, m\rangle = \hbar^2 l(l+1) |n, l, m\rangle \quad l = ?? \in \{0, \cancel{\frac{1}{2}}, \cancel{\frac{3}{2}}, \dots\}$$

$$\hat{L}_z |n, l, m\rangle = \hbar m |n, l, m\rangle \quad m \in \{-l, -l+1, \dots, l-1, l\}$$

• $l \in \{0, 1, 2, 3, \dots\}$ only!

$$\begin{aligned} \hat{L}_z &= \hat{x} \hat{p}_y - \hat{y} \hat{p}_x = -i\hbar \left(x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right) \quad \text{on w. fns} \\ &= -i\hbar \frac{\partial}{\partial \varphi} \end{aligned}$$

Say have eigenstate w/ wfnc $\Psi(r, \theta, \varphi)$ & $\hat{L}_z$ eigenvalue $\hbar m$:

$$\Rightarrow -i\hbar \frac{\partial \Psi}{\partial \varphi} = \hbar m \Psi$$

$$\Rightarrow \frac{\partial \Psi}{\partial \varphi} = im \Psi \Rightarrow \Psi = \chi e^{im\varphi}$$

But periodic $\varphi \simeq \varphi + 2\pi \Rightarrow m \in \mathbb{Z}$

$\Rightarrow l$ integer. $\checkmark$ $\rightarrow e^{2\pi im} = 1$

- $\langle \vec{r} | \hat{p}^2 | \psi \rangle = -\hbar^2 \left(\frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} \right) \psi(r, \theta, \varphi) + \frac{1}{r^2} \langle \vec{r} | \hat{L}^2 | \psi \rangle$

$$\hat{H} = \frac{1}{2\mu} \hat{p}^2 + \dots \Rightarrow \text{What is } \hat{p}^2 \text{ in } \vec{r}\text{-basis?}$$

$$\hat{\vec{p}}(\vec{r}) = i\hbar \vec{\nabla}(\vec{r}) \dots \rightarrow \text{change variables} \dots$$

Alternative derivation:

$$\begin{aligned} \hat{L}^2 &= (\hat{\vec{r}} \times \hat{\vec{p}}) \cdot (\hat{\vec{r}} \times \hat{\vec{p}}) = \sum_i \left(\sum_{j,k} \epsilon_{ijk} \hat{x}_j \hat{p}_k \right) \left(\sum_{l,m} \epsilon_{ilm} \hat{x}_l \hat{p}_m \right) \\ &= \sum_{j,k,l,m} \left(\sum_i \epsilon_{ijk} \epsilon_{ilm} \right) \hat{x}_j \hat{p}_k \hat{x}_l \hat{p}_m \quad (\text{keep order!}) \\ &= \sum_{j,k,l,m} (\delta_{jl} \delta_{km} - \delta_{jm} \delta_{kl}) \hat{x}_j \hat{p}_k \hat{x}_l \hat{p}_m \\ &= \sum_{j,k} (\hat{x}_j \hat{p}_k \hat{x}_j \hat{p}_k - \hat{x}_j \hat{p}_k \hat{x}_k \hat{p}_j) \\ &= \sum_{j,k} (\hat{x}_j \hat{x}_j \hat{p}_k \hat{p}_k - i\hbar \delta_{jk} \hat{x}_j \hat{p}_k \\ &\quad - \delta_j \hat{p}_j \hat{x}_k \hat{p}_k - i\hbar \delta_{jk} \hat{x}_j \hat{p}_k + \hat{x}_j \hat{p}_j i\hbar \delta_{kk}) \quad \begin{aligned} [\hat{x}_j, \hat{p}_k] &= i\hbar \delta_{jk} \\ (\vec{r} \cdot \vec{p} &\neq \vec{p} \cdot \vec{r}!) \end{aligned} \\ &= \hat{r}^2 \hat{p}^2 - (\hat{\vec{r}} \cdot \hat{\vec{p}})^2 + i\hbar (\hat{\vec{r}} \cdot \hat{\vec{p}}) \end{aligned}$$

Use: $\langle \vec{r} | \hat{\vec{r}} = \vec{r} \langle \vec{r} |$ and $\langle \vec{r} | \hat{\vec{p}} = -i\hbar \vec{\nabla} \langle \vec{r} | \Rightarrow$

$$\langle \vec{r} | \hat{L}^2 = r^2 \langle \vec{r} | \hat{p}^2 + \hbar^2 (\vec{r} \cdot \vec{\nabla})^2 \langle \vec{r} | + \hbar^2 (\vec{r} \cdot \vec{\nabla}) \langle \vec{r} |$$

$$\therefore \langle \vec{r} | \hat{p}^2 | \psi \rangle = \frac{1}{r^2} \left[\langle \vec{r} | \hat{L}^2 | \psi \rangle - \hbar^2 \left(r \frac{\partial}{\partial r} \right)^2 \psi - \hbar^2 \left(r \frac{\partial}{\partial r} \right) \psi \right] \quad \checkmark$$

Since $\hat{p}^2 \sim -\hbar^2 \nabla^2$, also written

$$\nabla^2 = \frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} - \frac{1}{\hbar^2} \frac{\hat{L}^2}{r^2}$$

$$\bullet \langle \vec{r} | \hat{H} | \psi \rangle = \frac{1}{2\mu} \langle \vec{r} | \hat{p}^2 | \psi \rangle + \langle \vec{r} | V(\vec{r}) | \psi \rangle$$

$$= -\frac{\hbar^2}{2\mu} \left(\frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} \right) \psi + \frac{1}{2\mu r^2} \langle \vec{r} | \hat{L}^2 | \psi \rangle + V(r) \psi$$

Choose $|\psi\rangle = |n, l, m\rangle \Rightarrow \hat{L}^2 |\psi\rangle = \hbar^2 l(l+1) |\psi\rangle \Rightarrow$

$$\langle \vec{r} | \hat{H} | \psi \rangle = \underbrace{-\frac{\hbar^2}{2\mu} \left(\frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} \right) \psi}_{\text{"radial KE"}} + \underbrace{\left[\frac{\hbar^2 l(l+1)}{2\mu r^2} + V(r) \right] \psi}_{\substack{\text{"centrifugal barrier"} \\ \text{"effective" radial P.E.}}}$$

$\psi(r, \theta, \phi) \doteq \langle \vec{r} | n, l, m \rangle$, then $\hat{H} |n, l, m\rangle = E_n |n, l, m\rangle$
gives P.D.E. for ψ , depends only on r ! :

$$\underbrace{-\frac{\hbar^2}{2\mu} \left(\frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} \right) \psi + \left(\frac{\hbar^2 l(l+1)}{2\mu r^2} + V(r) \right) \psi}_{\equiv \mathcal{D}_l(r) \psi} = E_n \psi$$

Solved by $\psi(r, \theta, \phi) = R(r) Y(\theta, \phi)$ (ang Y)

s.t. $\mathcal{D}_l(r) R(r) = E_n R(r) \quad \leftarrow \quad \underline{\text{ODE}} = \text{"radial Schr. eqn."}$

What determines $Y(\theta, \phi)$? Other eigenvalue eqns:

$$\left. \begin{aligned} \hat{L}^2 |n, l, m\rangle &= \hbar^2 l(l+1) |n, l, m\rangle \\ \hat{L}_z |n, l, m\rangle &= \hbar m |n, l, m\rangle \end{aligned} \right\} \text{only involves } \theta, \phi \dots$$

• Angular part $\psi = R(r) Y(\theta, \varphi)$

$$\begin{cases} \hat{L}^2 |\psi\rangle = \hbar^2 l(l+1) |\psi\rangle \\ \hat{L}_z |\psi\rangle = \hbar m |\psi\rangle \end{cases} \Rightarrow \text{eqns for } Y \dots$$

$\therefore$ Need $\langle \vec{r} | \hat{L}^2 | \psi \rangle$ & $\langle \vec{r} | \hat{L}_z | \psi \rangle$ in sph. coords.

$\therefore$ Use c.o.v. ...

$$\langle \vec{r} | \hat{L}^2 | \psi \rangle = -\hbar^2 r^2 \left(\nabla^2 - \frac{\partial^2}{\partial r^2} - \frac{2}{r} \frac{\partial}{\partial r} \right) \psi$$

$$\text{& } \nabla^2 = \frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \varphi^2}$$

$$\Rightarrow \langle \vec{r} | \hat{L}^2 | \psi \rangle = -\frac{\hbar^2}{\sin \theta} \left(\frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \psi}{\partial \theta} \right) + \frac{1}{\sin \theta} \frac{\partial^2 \psi}{\partial \varphi^2} \right)$$

$$\text{& calc } \langle \vec{r} | \hat{L}_z | \psi \rangle = -i\hbar \frac{\partial \psi}{\partial \varphi}$$

Only depend on (θ, φ) , so plug in $\psi = R(r) Y(\theta, \varphi)$

$\Rightarrow R(r)$'s cancel & get for $Y_{lm}(\theta, \varphi)$:

$$\left(\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} \right) Y_{lm} = -l(l+1) Y_{lm} \quad (*)$$

$$\frac{\partial}{\partial \varphi} Y_{lm} = im Y_{lm} \quad (**)$$

normalization: $\int_0^\pi \sin \theta d\theta \int_0^{2\pi} d\varphi |Y_{lm}|^2 = 1$

Solve by sep. of vars: $Y_{lm}(\theta, \varphi) = P(\theta) Q(\varphi)$

$(***) \Rightarrow \frac{dQ}{d\varphi} = imQ \Rightarrow Q = e^{im\varphi}$ & per. $\Rightarrow m \in \mathbb{Z}$.

$\therefore Y_{lm}(\theta, \varphi) = P_{lm}(\theta) e^{im\varphi}$ & P_{lm} satisfies

norm: $1 = 2\pi \int_0^\pi \sin \theta d\theta |P_{lm}|^2$

eqn: $\left[\frac{1}{\sin \theta} \frac{d}{d\theta} \left(\sin \theta \frac{d}{d\theta} \right) - \frac{m^2}{\sin^2 \theta} \right] P_{lm} = -l(l+1) P_{lm} \quad (***)$

• How to solve? • Change vars $\theta \rightarrow x \equiv \cos \theta \dots$

Better: Know from angular mom. algebra: $\hat{L}_+ |l, l\rangle = 0$

& $\hat{L}_+ = \hat{L}_x + i\hat{L}_y = \dots$ (in sph. coord). $\Rightarrow$ 1st order ODE

Result: $P_{ll}(\theta) \propto \sin^l \theta$. Then rest P_{lm} by

$\hat{L}_- |l, l\rangle \propto |l, l-1\rangle$, etc.

Answer: "Spherical Harmonics"

$$Y_{00} = \sqrt{\frac{1}{4\pi}} \quad (\text{b/c } \int \sin\theta d\theta d\varphi = 4\pi)$$

$$Y_{1,\pm 1} = \mp \sqrt{\frac{3}{8\pi}} \underbrace{e^{\pm i\varphi} \sin\theta}_{= \frac{x \pm iy}{r}}, \quad Y_{1,0} = \sqrt{\frac{3}{4\pi}} \underbrace{\cos\theta}_{= \frac{z}{r}}$$

$$Y_{2,\pm 2}, \dots \quad Y_{2,\pm 1} = \dots \quad Y_{2,0} = \dots \quad \text{etc.}$$

• Useful properties:-

$$Y_{l,m} = \text{Polynomial}(\sin\theta, \cos\theta) e^{im\varphi} = \frac{\text{Poly}(z, x \pm iy)^l}{r^l} \quad \text{order } l$$

$$Y_{l,-m} = (-1)^m (Y_{l,m})^*$$

• Orthonormal:

$$\int d\Omega Y_{lm}^* Y_{l'm'} = \delta_{ll'} \delta_{mm'} = \langle l, m | l', m' \rangle$$

$$\sum_{l=0}^{\infty} \sum_{m=-l}^l Y_{lm}(\theta, \varphi) Y_{lm}^*(\theta', \varphi') = \delta_{\Omega}^2(\theta - \theta', \varphi - \varphi')$$

$$\text{where } \int d\Omega \equiv \int d\varphi \int \sin\theta d\theta$$

$$\left\{ \begin{array}{l} \delta_{\Omega}^2 \equiv \frac{1}{\sin\theta} \delta(\theta - \theta') \delta(\varphi - \varphi') \end{array} \right.$$

$$\sum_{lm} |l, m\rangle \langle l, m| = 1$$

↑
in $\mathcal{H}_{l,p}$

$$Y_{l,m}(\theta, \varphi) = \langle \theta, \varphi | l, m \rangle$$

$$\mathcal{H}_{\vec{r}} = \mathcal{H}_r \otimes \mathcal{H}_{\theta, \varphi}$$

$$\{ |r\rangle \} \otimes \{ |l, m\rangle \}$$

Ortho-normality of $\{ |l, m\rangle \}$:

$$\left\{ \begin{array}{l} \langle \theta, \varphi | \theta', \varphi' \rangle = \delta_{\Omega}^2 (\theta - \theta', \varphi - \varphi') \\ \int d\Omega | \theta, \varphi \rangle \langle \theta, \varphi | = \hat{1} \end{array} \right.$$

$$\langle \theta, \varphi | Y \rangle = \int d\Omega' \langle \theta, \varphi | \theta', \varphi' \rangle \langle \theta', \varphi' | Y \rangle$$

$$= \int d\Omega' \delta_{\Omega}^2 (\theta - \theta', \varphi - \varphi') \langle \theta', \varphi' | Y \rangle$$

$$= \int (\sin \theta') d\theta' d\varphi' \delta_{\Omega}^2 (\theta - \theta', \varphi - \varphi') \langle \theta', \varphi' | Y \rangle$$

$$\therefore \delta_{\Omega}^2 (\theta - \theta', \varphi - \varphi') = \frac{1}{\sin \theta} \delta(\theta - \theta') \delta(\varphi - \varphi')$$

$$\begin{aligned} \delta_{l,l'} \delta_{m,m'} &= \langle l, m | l', m' \rangle = \int d\Omega \langle l, m | \theta, \varphi \rangle \langle \theta, \varphi | l', m' \rangle \\ &= \int d\Omega Y_{lm}^*(\theta, \varphi) Y_{l'm'}(\theta, \varphi) \end{aligned}$$

$$\langle \theta, \varphi | \left(\hat{1} = \sum_{l,m} | l, m \rangle \langle l, m | \right) | \theta', \varphi' \rangle$$

$$\Rightarrow \underbrace{\langle \theta, \varphi | \theta', \varphi' \rangle}_{\delta_{\Omega}^2 (\theta - \theta', \varphi - \varphi')} = \sum_{l,m} \underbrace{\langle \theta, \varphi | l, m \rangle}_{Y_{lm}^*(\theta, \varphi)} \underbrace{\langle l, m | \theta', \varphi' \rangle}_{Y_{lm}(\theta', \varphi')}$$