

Lecture 11

Magnetic fields in matter Ch. 6

• Magnetic dipole model of matter (heuristic)

- Atoms or molecules of matter can be approximated as point dipoles " \vec{m} ".
- With no applied \vec{B} field, some* materials' atoms have no dipole moment, but most have "permanent dipole moments".
(* mostly in atoms with even numbers of electrons)
- Can think of dipole moments as due to electrons orbiting nuclei so something like a small current loop, or due to electron spin. Both really need quantum mechanics to understand.

• Diamagnetism

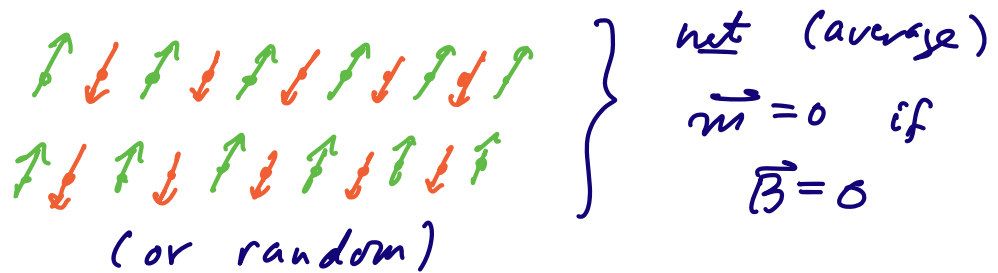
- Material has atomic $\vec{m} = 0$ when

$\vec{B} = 0$. Applied $\vec{B} \neq 0$ induces
 $\vec{m} \propto -\vec{B}$ (pointing opposite to \vec{B})

- Griffiths gives classical model of this effect due to change in electron orbit in presence of \vec{B} .

• Paramagnetism

- Material has atoms with permanent dipoles $\vec{m} \neq 0$:



- Force on a dipole in applied \vec{B} :

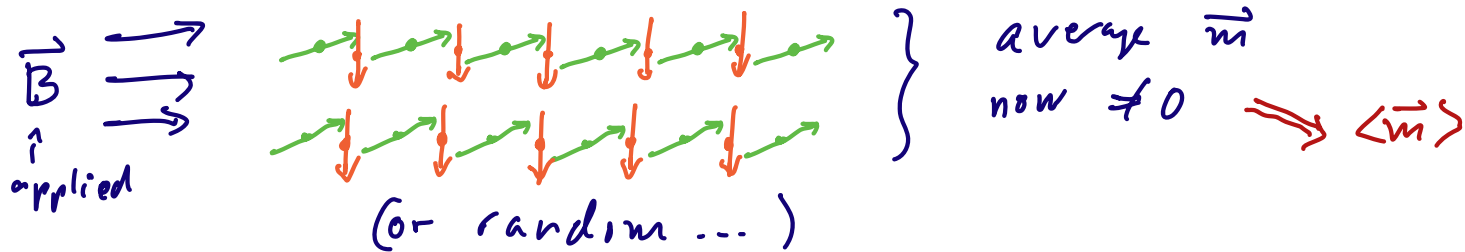
$$\vec{F} = (\vec{m} \cdot \vec{\nabla}) \vec{B} \quad \text{force}$$

$$\vec{N} = \vec{m} \times \vec{B} \quad \text{torque}$$

(Recall elec. dipoles: $\vec{F} = (\vec{p} \cdot \vec{\nabla}) \vec{E}$, $\vec{N} = \vec{p} \times \vec{E}$)

(See Griffiths see 6.1.)

\vec{N} tends to rotate \vec{m} to be parallel to \vec{B} :

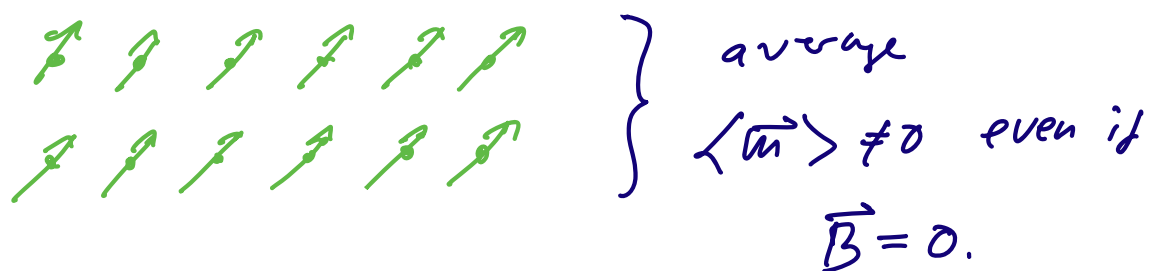


So tend to develop net $\vec{m} \propto + \vec{B}$
 (aligning with applied \vec{B}).

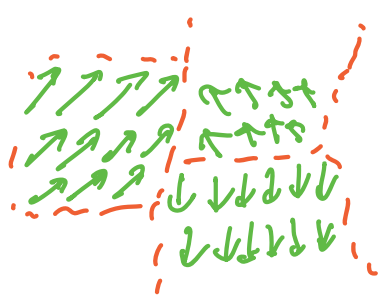
- Paramagnetism tends to be much stronger than diamagnetism.

• Ferromagnetism

- Material has permanent dipoles and they do not cancel on average:

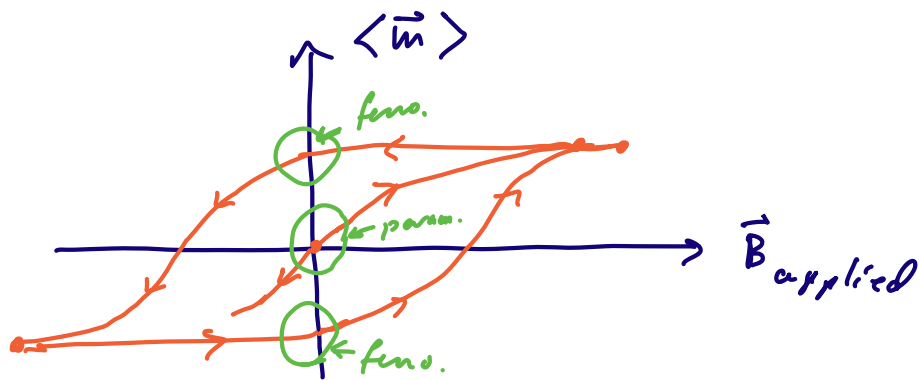


- Many ferromagnetic solids look paramagnetic at large scales because ferromagnetic "domains" are randomly mis-aligned:



so average $\langle \vec{m} \rangle = 0$

Apply \vec{B} , has paramagnetic response as \vec{m} 's tend to align. For strong enough \vec{B} , can move/merge domains so mostly aligned. Then when turn off \vec{B} , remains ferromagnetic



"Hysteresis" = "history dependences"

- Reason permanent magnets (ferromagnetic) occurs is that it is energetically favorable for neighboring dipoles to align:

$$E(\uparrow\uparrow) < E(\uparrow\downarrow)$$

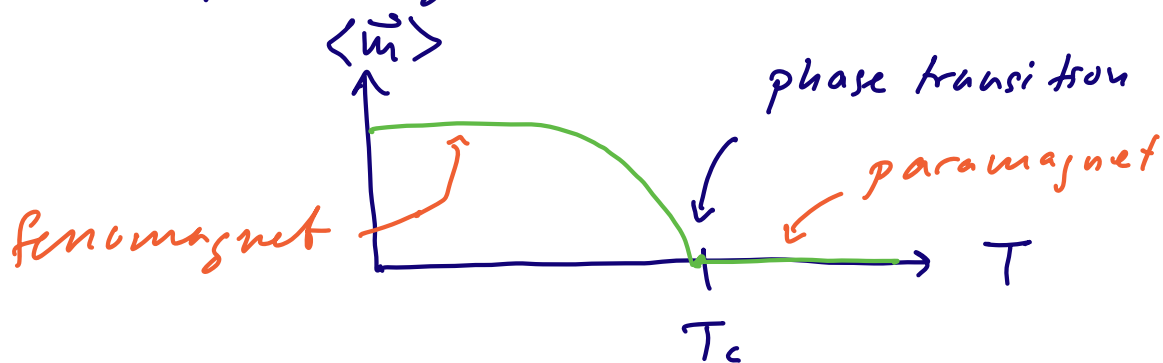
The reason is essentially quantum mechanical.

(- There are situations in which the reverse is true and dipoles tend to "anti-align":



Then $\langle \vec{m} \rangle = 0$ if $\vec{B} = 0$ & looks paramagnetic. This is "anti-ferromagnetism.")

- At high temperatures, thermal motion tends to randomize dipoles, overcoming ferromagnetic alignment:



• Linear media

- Concentrate on diamagnets & paramagnets with small applied \vec{B} fields.

Then expect linear response:

$$\langle \vec{m} \rangle \propto \vec{B}$$

just as with dielectrics.

- Define $\vec{M} \equiv \frac{\langle \vec{m} \rangle}{\text{unit volume}}$ "Magnetization"

Recall $\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \frac{\vec{m} \times \hat{r}}{r^2}$ for dipole.

Average over many dipoles:

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int d\epsilon' \frac{\vec{M}(\vec{r}') \times \hat{r}}{r^2}$$

∴ (just as for $V(\vec{r})$ in dielectrics)

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \int d\epsilon' \frac{\vec{J}_b(\vec{r}')}{r}$$

$$\text{w/ } \vec{J}_b \equiv \vec{\nabla} \times \vec{M}$$

"bound current density"

$$(\Rightarrow \vec{\nabla} \cdot \vec{J}_b = 0 \checkmark)$$

- At surface of material where \vec{M} goes to 0 discontinuously, develop a "bound surface current"

$$\vec{K}_b = \vec{M} \times \hat{n}$$



$$\left(\text{Parallel to dielectric polarization, } \vec{P} \right)$$

$$\rho_b = -\vec{\nabla} \cdot \vec{P} \quad \sigma_b = \vec{P} \cdot \hat{n}$$

- Say we have some magnetic material and we specify some steady "free" currents \vec{J}_f . Then total current in

$$\vec{J} = \vec{J}_f + \vec{J}_b \quad \leftarrow \text{"induced current"}$$

and Ampere's law \Rightarrow

$$\frac{1}{\mu_0} (\vec{\nabla} \times \vec{B}) = \vec{J} = \vec{J}_f + \vec{J}_b = \vec{J}_f + \vec{\nabla} \times \vec{M}$$

$$\Rightarrow \vec{\nabla} \times \vec{H} = \vec{J}_f \quad \text{w/} \quad \vec{H} \doteq \frac{1}{\mu_0} \vec{B} - \vec{M}$$

$$\Rightarrow \oint \vec{H} \cdot d\vec{l} = I_f \text{ enc.}$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

- Boundary conditions:

$$H_{\text{above}}^{\perp} - H_{\text{below}}^{\perp} = -(M_{\text{above}}^{\perp} - M_{\text{below}}^{\perp}) \quad \Leftrightarrow \quad B_{\text{above}}^{\perp} = B_{\text{below}}^{\perp}$$

$$\vec{H}_{\text{above}}^{\parallel} - \vec{H}_{\text{below}}^{\parallel} = \vec{K}_f \times \hat{n}$$

$$\Leftrightarrow \vec{B}_{\text{above}}^{\parallel} - \vec{B}_{\text{below}}^{\parallel} = \mu_0 (\vec{K} \times \hat{n})$$

- Linear (isotropic, homogeneous) media:

$$\vec{M} = \chi_m \vec{H}$$

"magnetic susceptibility"
(constant)

$$\chi_m < 0 \Rightarrow \text{Diamagnet}$$

$$\chi_m > 0 \Rightarrow \text{Paramagnet}$$

$$\Rightarrow \vec{B} = \mu \vec{H} \quad \text{w/} \quad \mu \doteq \mu_0 (1 + \chi_m)$$

"permeability"

- Compare to electrostatics in insulators:

insulators

$$\vec{\nabla} \cdot \vec{D} = \rho_f$$

$$\vec{\nabla} \times \vec{E} = 0$$

$$\vec{D} \doteq \epsilon_0 \vec{E} + \vec{P}$$

$$\Delta D^\perp = \sigma_f$$

$$\Delta \vec{E}^\parallel = 0$$

$$\vec{P} = \epsilon_0 \chi_e \vec{E}$$

$$\vec{D} = \epsilon \vec{E}$$

$$\epsilon = \epsilon_0 (1 + \chi_e)$$

magn. materials

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{H} = \vec{J}_f$$

$$\vec{H} \doteq \frac{1}{\mu_0} \vec{B} - \vec{M}$$

$$\Delta B^\perp = 0 \quad (\text{continuous})$$

$$\Delta \vec{H}^\parallel = \vec{K}_f \times \hat{n}$$

$$\vec{M} = \chi_m \vec{H}$$

$$\vec{B} = \mu \vec{H}$$

$$\mu \doteq \mu_0 (1 + \chi_m)$$

} @ bdy

} linear media

Conductors

• Recall in electrostatics, in conductors:

- $\vec{E} = \rho = 0$ in interior ($V = \text{constant}$)

- $\vec{E}_{\text{out}}^{\parallel} = 0$ | boundary } $\Rightarrow \vec{E}_{\text{out}}|_{\text{bdry}} = \frac{\sigma}{\epsilon_0} \hat{n}$

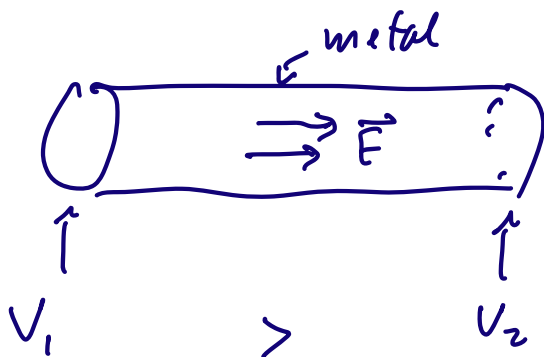
- $E_{\text{out}}^{\perp} = \sigma$ | boundary }

$$\Rightarrow V = \text{constant, but } \frac{\partial V}{\partial n} = \frac{\sigma}{\epsilon_0}$$

$\sigma \equiv$ induced surface charge on bdry

• But can also have steady currents in conductors, giving sources for magnetostatic fields.

• Currents are response of conduction charges (electrons) to applied \vec{E} field inside conductor:



If we can add/subtract conduction charges at ends of wire so as to keep $V_1 - V_2 = \text{constant}$ (e.g., use a battery) then keep steady $\vec{E} \neq 0$ inside metal! This \vec{E} accelerates conduction electrons, forming current.

- In conductors there are frictional forces on the conduction electrons (e.g., scattering off impurities...) which slows them down (dissipating their energy as heat). A given \vec{E} then accelerates e's to a steady velocity \vec{v} at which the frictional force counterbalances $e\vec{E}$. Then get a steady current $\vec{J} = \rho_e \vec{v}$.

- "Constitutive relation" $\vec{J} = \vec{J}(\vec{E})$?

In linear (small enough applied \vec{E}), homogeneous, isotropic conductor have

$$\vec{J} = \sigma \vec{E}$$

"Ohm's law"

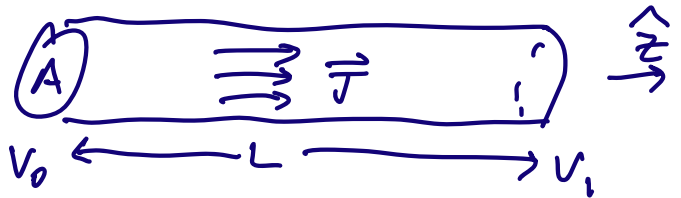
σ^* = constant
= "conductivity"

($1/\sigma$ = "resistivity")

* NOT surface charge!

[- If conductor moves w/ steady velocity \vec{v} in \vec{B} -field:
then $\vec{J} = \sigma (\vec{E} + \vec{v} \times \vec{B})$.]

- Apply to wire:



$$A \vec{J} \hat{z} = A \vec{J} = A \sigma \vec{E} = A \sigma \frac{V_0 - V_1}{L} \hat{z}$$

$$\Rightarrow \underbrace{A J}_{\text{current} \rightarrow I} = \underbrace{\frac{A \sigma}{L}}_{\text{resistance}^{-1}} \cdot \underbrace{(V_0 - V_1)}_{V \leftarrow \text{voltage difference}} \quad (\text{Ohm's law})$$

- Conductivities can vary $0 \leq \sigma \leq \infty$
 \uparrow insulator \uparrow superconductor

- Conductors can be: diamagnetic (eg. Ag),
paramagnetic (eg. Al), or ferromagnetic (eg. Fe).

Superconductors

- " $\sigma \rightarrow \infty$ limit of a conductor."
 - No friction: applied $\vec{E} \neq 0$ in conductor accelerates charges without limit: $\vec{E} \propto \frac{\partial \vec{J}}{\partial t}$ so no Ohm's law
 - What about magnetic response of superconductors. They still satisfy $\vec{\nabla} \cdot \vec{B} = 0$, $\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$ (static) and can have a steady state if $\vec{E} = 0$ inside.

- London eqns: inside superconductor:

$$\mu_0 \frac{\partial \vec{J}}{\partial t} = \frac{1}{\lambda^2} \vec{E} \quad (1) \quad \& \quad \mu_0 \vec{\nabla} \times \vec{J} = -\frac{1}{\lambda^2} \vec{B} \quad (2)$$

$[\lambda] = \text{length}$ $\lambda \equiv$ "London penetration depth"

Typically $50 \text{ nm} \lesssim \lambda \lesssim 500 \text{ nm}$ (atom $\sim 0.1 \text{ nm}$)

- L.E. (1) intuitive from Lorentz force law:

$$\vec{F} = m_e \dot{\vec{v}} = -e \vec{E} \Rightarrow \vec{J} = -n_e e \dot{\vec{v}} = \frac{n_e e^2}{m_e} \vec{E}$$

e^- number density \uparrow

- Then $\vec{\nabla} \times$ (1) & Faraday's law: $\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \Rightarrow$

$$0 = \mu_0 \vec{\nabla} \times \frac{\partial \vec{J}}{\partial t} - \frac{1}{\lambda^2} \vec{\nabla} \times \vec{E} = \mu_0 \vec{\nabla} \times \frac{\partial \vec{J}}{\partial t} + \frac{1}{\lambda^2} \frac{\partial \vec{B}}{\partial t} \Rightarrow$$

$$0 = \frac{\partial}{\partial t} \left(\mu_0 \vec{\nabla} \times \vec{J} + \frac{1}{\lambda^2} \vec{B} \right)$$

- Then $\mathcal{L}_E \textcircled{2}$ consistent.
- Only honest derivation is from quantum mechanics...

- London penetration & Meissner effect

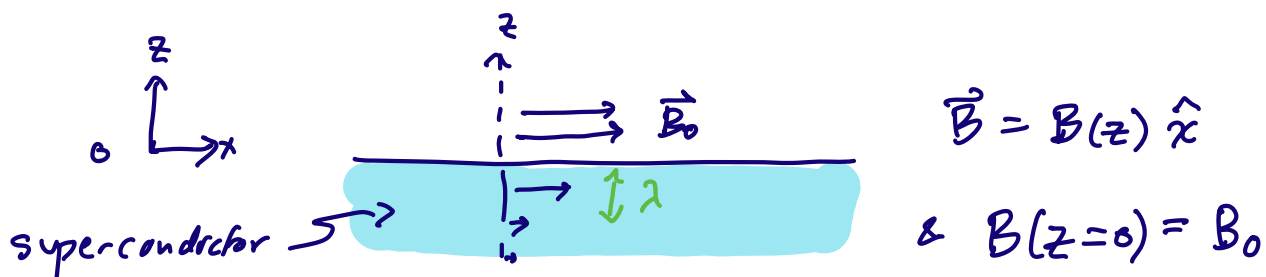
- Ampere $\Rightarrow \mu_0 \vec{J} = \vec{\nabla} \times \vec{B}$, plus in $\mathcal{L}_E \textcircled{2} \Rightarrow$

$$0 = \vec{\nabla} \times (\vec{\nabla} \times \vec{B}) + \frac{1}{\lambda^2} \vec{B}$$

$$= \vec{\nabla} (\vec{\nabla} \cdot \vec{B}) - \nabla^2 \vec{B} + \frac{1}{\lambda^2} \vec{B} \Rightarrow$$

$$\boxed{\nabla^2 \vec{B} = + \frac{1}{\lambda^2} \vec{B}} \quad \textcircled{*}$$

- Solution to $\textcircled{*}$ is $\vec{B}(z) = \vec{B}_0 e^{z/\lambda}$;



$$\text{Then } \nabla^2 \vec{B} = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) B(z) \hat{x} = \frac{d^2 B(z)}{dz^2} \hat{x}$$

$$\& \frac{1}{\lambda^2} \vec{B} = \frac{B(z)}{\lambda^2} \hat{x}$$

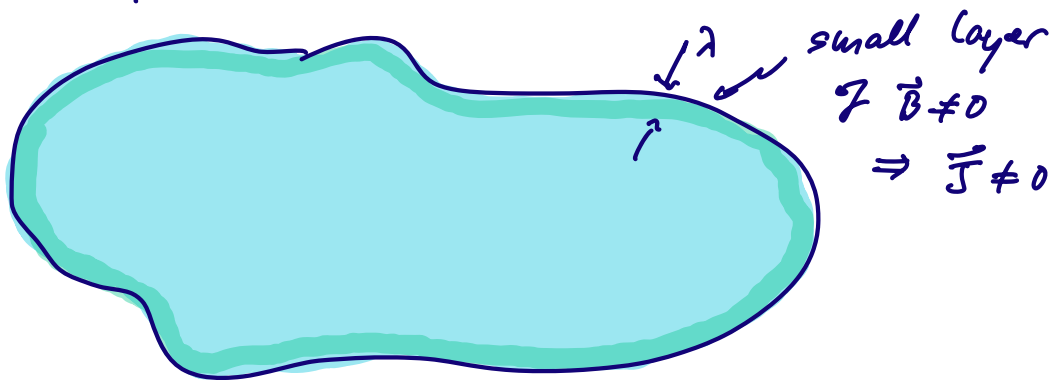
$$\therefore \textcircled{*} \Rightarrow B''(z) = + \frac{1}{\lambda^2} B(z)$$

⇒ gen. sol'n $B(z) = \alpha e^{z/\lambda} + \beta e^{-z/\lambda}$

Determine α, β by boundary conditions:

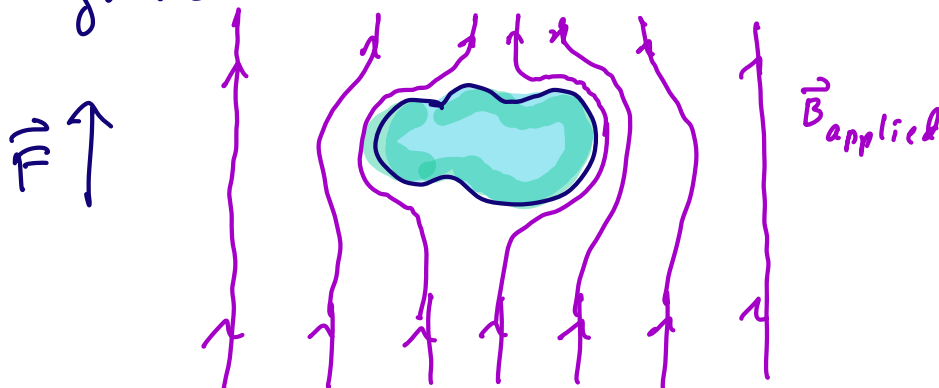
$\left. \begin{array}{l} @ z \rightarrow -\infty \quad B \rightarrow \infty, \text{ so } \beta = 0. \\ @ z = 0 \quad B = B_0, \text{ so } \alpha = B_0. \end{array} \right\} \Rightarrow B(z) = B_0 e^{z/\lambda} \quad \checkmark$

- This implies \vec{B} -field $\rightarrow 0$ (exponentially fast) inside superconductor: "Meissner effect"



So current restricted to within London penetration depth of surface of superconductor.

- Superconductors expel mag'n fields ⇒ "magnetic levitation"



- Steady currents w/o applied $\vec{E} \Rightarrow$ electromagnets without energy loss/heating.