Lecture 10 Magnetostatics (Ch.3)

- Maynetic field $\overline{B}(\vec{r})$ defined by noticity that a charge Q at \vec{r} writing with velocity \vec{v} experiences a force $\vec{F} = Q(\vec{E}(\vec{r}) + \vec{v} \times \vec{B}(\vec{r}))$ horents force law (This defines both $\vec{E} + \vec{B}$.)
- Magnetic forces do no work on charged particles because the force is perpendicular to the velocity of the particle: d Wmag = Fmag · dl = (Qvx B) · (vdt) = 0. Fmag still accelerates particle, but only by changing direction, not speeding up or slowing down. So motion in magnetic fields tends to be in circles... (ne Griffiths examples)

· Currents & current deusity - If some charges with density p(r,t) are moving with velocities $\vec{v}(\vec{r},t)$, then

the charge current density is $\overline{J}(\vec{r},t) \doteq p(\vec{r},t) \ \vec{v}(\vec{r},t)$ = <u>Charge</u> <u>lensth</u> <u>Charge</u> Volume time - <u>Grea</u> time = $\frac{C_1}{s}$, $\frac{1}{m^2}$ $\frac{C}{s}$ = A (Augere) "Current" flow of through a surface flow of charge

- In materials (e.g. conductors) can have different types of charges moving at different velocities simultaneously. E.g. electrons w/ fe(r,t), ve(r,t) and ions (nuclei) w/ f; (r,t), ve(r,t).

Then total charge & current densities are $\begin{cases} \rho = \rho e + \rho i \\ \overline{J} = \rho e \overline{v} e + \rho i \overline{v} i \end{cases}$

So, in general JZpJ.

E.g. in a metal pez-pi => p=0 but ve = 0 (electrons moves and ve = 0 (nuclei don't move) => J= seve.

Charge is conserved: any net charge that flows into/out of a volume V will increase/ decrease the charge inside: Net charge flowing out of V per unit time: \$\$\overline{\verline{\overline{\overline{\overl

 $-\frac{d}{dt}\int_{q/p} dz = -\int_{q/pt} \frac{\partial p}{\partial t} dz$

Charge conservation: $-\int dz \frac{\partial z}{\partial t} = \oint \vec{J} \cdot d\vec{a} = \int dz (\vec{\nabla} \cdot \vec{J}) \quad \forall \forall \vec{v} = \mathcal{V}$ $= \int dz = \int dz (\vec{\nabla} \cdot \vec{J}) \quad \forall \forall \vec{v} = \mathcal{V}$

$$\frac{\partial f}{\partial t} = \vec{\nabla} \cdot \vec{J}$$
 Charge conservation
 $\frac{\partial f}{\partial t} = \vec{\nabla} \cdot \vec{J}$ "continuity equation"

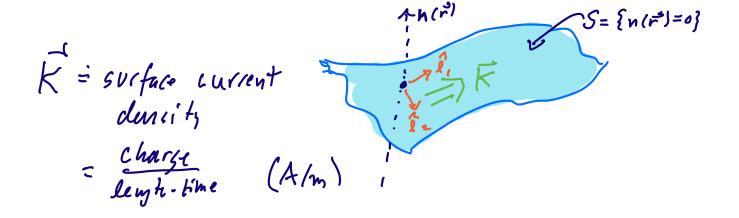
~ If you have a continuous, steady stream
of moving charged particles, then
$$\vec{v}_e(\vec{r},t) = \vec{v}_e(\vec{r}) + e(\vec{r},t) = e(\vec{r})$$

=)
$$\int \vec{J}(\vec{r},t) = \vec{J}(\vec{r}) \Leftrightarrow "steady" or "stationary" correct
 $\int \rho(\vec{r},t) = \rho(\vec{r}) \Leftrightarrow "static"$ charge density.$$

Steady currents and static charges,
$$\partial_t \tilde{J} = \partial_t p = 0$$
,
& charge conservation =>

- Surface, line, & point current densities

* If moving charges confined to a surface, S, Hum $\overline{J}(\vec{r},t) = \overline{K}(\vec{r},t) S(n)$ to S



· If move charger confined to a curve, C, then $\overline{J}(\overline{r}, \overline{t}) = \overline{I}(\overline{r}, t) S(n_1) S(h_2) \xrightarrow{t}{s-fncs} restricting}$ $n_1(\vec{r})$ $n_2(\vec{r})$ $r_1(\vec{r})$ $n_2(\vec{r})$ $C = \xi n_1(\vec{r}) = h_2(\vec{r}) = o\xi$ $r_1(\vec{r})$ TI = line current density ="cunent" = <u>Charge</u> (A) time (A)

• For these to make sense (charge conservation) the charges must flow along (thingent to) the surface S or curve G:

$$\vec{K} \cdot \hat{n} = 0 \qquad \vec{T} \cdot \hat{n}_1 = \vec{T} \cdot \hat{n}_2 = 0$$

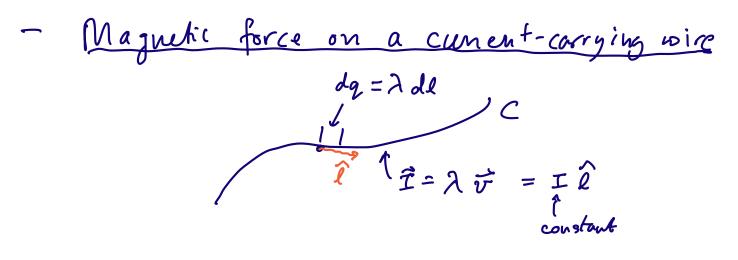
$$\vec{K} = K_1 \hat{\ell}_1 + K_2 \hat{\ell}_2 \qquad \Rightarrow \vec{T} = I \hat{\ell}$$

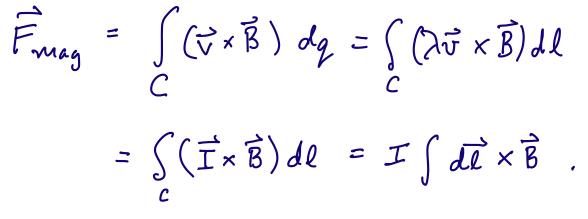
Steady current conservation, $\nabla \cdot J = 0$ implies $o = \overline{\nabla}_{ij} \cdot \overline{K} = \partial_{e_1} K_1 + \partial_{e_2} K_2$

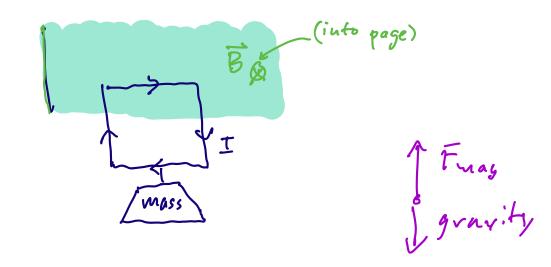
$$o = \overrightarrow{\nabla}_{ij} \cdot \overrightarrow{I} = \partial_{j} I \Rightarrow I = constant, $\mathcal{X}$$$

* Steady line currents = constant currents down wires, are the main experimental current realization.

• For a moving point charge
$$q$$
 at $\vec{r} = \vec{r}_0(t)$
Path in space Z_1''
 $\vec{T}(\vec{r}_1 t) = q \vec{v}(\vec{r}_1 t) S^3(\vec{r} - \vec{r}_0(t))$
Even if velocity $i' = \vec{v}(t)$
 $\vec{T}(t) = \vec{r}(t)$
of particle is constant, $\vec{v} = \vec{v}(\vec{r}_1)$, cannot
have $\frac{2}{2t} \vec{T}(\vec{r}_1 t) = 0$!
So no such thing as a steady current
of a particle.







If B does no work, what lifts the mass ??

· Biot-Savart law : moving charges Source (create) magnetic fields: It is found experimentally that a steadily moving change q at position r' with velocity à creates a magnetic field at the point r : $\vec{B}(\vec{r},t) = \frac{\mu_0}{4\pi} \qquad \frac{2\vec{v}\times\vec{n}}{n^2}, \quad \vec{n} = \vec{r} - \vec{r} \qquad Biot-Savart \\ Law$ $\vec{B}(\vec{n}) = \vec{r}_{s} + \vec{v}t$ (Griffiths says this formula is wrong because it only applies if the particle is moving steadily (constant velocity) and if the velocity is small compared to the speed of light! So it is only an approximation. It becomes exact if r'(t) -> r'(tr) where to is the "retarded time" given implicitly by $t_r=t-\frac{1}{c}|\vec{r}-\vec{r}'(t_r)|$. In $c \rightarrow \infty$ limit, $t_r=t$.)

- Compare to Coulomb law:

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{2}{7t^2} \hat{r}, \quad \vec{r} = \vec{r} - \vec{r}'$$
(This also only applies if the particles
velocity is small compared to the
speed of light!)
- Units & constants:

$$M_0 \doteq 4\pi \times 10^{-7} \text{ N/A}^2 \quad \{N \doteq \text{kg.m}^2/\text{s}^* (\text{Rewbay})\}$$

$$\frac{1}{1} \quad (\text{exactly}) \quad \{A \doteq C/\text{s} \quad (\text{Ampere})\}$$
"permedility of free spee" (clefinition = clefine A > C !)

$$\vec{EB} = \overline{Tes/a} (T) \text{ or } gaves$$

$$T \doteq N/(A \cdot m) \quad gaves = 10^{4}T$$

$$(1T = \text{hvg}^2; 1 \text{ Jaovs} = \text{everyday})$$

$$Also: \qquad M_0 \in_0 = C^{-2} \qquad (\text{exactly})$$

$$\mathcal{E}(\vec{E}) = M_0 \in_0 = C^{-2} \qquad (\text{exactly})$$

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- Recognize

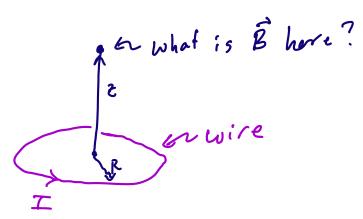
$$\frac{2\vec{v}\times\vec{n}}{n^{2}} = \int dz' \ 2\vec{v}(\vec{r}') \\ \\ \vec{v}' \\$$

- There is something funny going on here: moving charges create B-field, but motion is <u>relative</u>: I can go to an inertial frame where the change is stationary. Does the B-field go away? Yes!

Electric & magnetic fields are frame-dependent: different inertial observers will see different values of EtB ?

(It turns out (special relativity...) that $\vec{E} \cdot \vec{B}$ and $E^2 - \frac{1}{\epsilon_0 \mu_0} B^2$ are frame-indup't.)

- See example 5.6 of Griffiths:



He does the Biot-Savart integral efficiently using the symmetries...

Differential equations satisfied by B B-S: $\vec{B} = \frac{M_0}{4\pi} \int de' \frac{\overline{5(r')} \times fr}{\mu^2}$ $\Rightarrow \overrightarrow{\nabla} \cdot \overrightarrow{B} = \frac{\mu_0}{4\pi} \int de' \overrightarrow{\nabla} \cdot \left(\overrightarrow{J}(\overrightarrow{r'}) \times \overrightarrow{\mu_2} \right)$

 $=\frac{M_{0}}{4\pi}\int dz'\left\{\frac{\hat{\mu}}{\pi^{2}}\cdot\left(\overrightarrow{\nabla}_{\vec{r}}\times\overrightarrow{J}(\vec{r}')\right)-\overrightarrow{J}(\vec{r}')\cdot\left(\overrightarrow{\nabla}_{\vec{r}}\times\overrightarrow{\pi}_{\vec{r}}\right)\right\}$ $\therefore \quad \overrightarrow{\nabla} \cdot \overrightarrow{B} = O$ $\Rightarrow \nabla \times \vec{B} = \frac{M_0}{4\pi} \int dc' \nabla_{\vec{\mu}} \times \left(\vec{J}(\vec{r}') \times \vec{H}_2 \right)$ $= \frac{\mu_0}{4\pi} \int d\tau' \begin{cases} \vec{J}(\vec{r}') & (\vec{J}_{\vec{r}} \cdot \vec{J}_{\vec{r}}) \\ \vec{J}_{\vec{r}} \cdot \vec{J}_{\vec{r}} \end{pmatrix} - \frac{\mu}{\pi^2} & (\vec{T}_{\vec{r}} \cdot \vec{J}(\vec{r}')) \end{cases}$ $+\left(\frac{\hat{r}_{k}}{\pi^{2}}\cdot\vec{\nabla_{\mu}}\right)-\vec{J}(\vec{r}')-\left(\vec{J}(\vec{r}')\cdot\vec{\nabla_{\mu}}\right)\hat{r}_{\mu}^{2}$ $-(\overline{J}.\overline{\nabla})_{\mathcal{H}^{2}}^{\mathcal{H}} = +(\overline{J}.\overline{\nabla})_{\mathcal{H}^{2}}^{\mathcal{H}}$ $(\overline{J},\overline{\phi}') \xrightarrow{\chi-\chi'}_{\pi^3} \neq (\dots \neq \epsilon \neq \dots)$ $= \overrightarrow{\nabla} \cdot \left[\frac{(x-x')}{\pi^3} \overrightarrow{f} \right] \hat{x} - \left(\frac{x-x'}{\pi^3} \right) \hat{x} \cdot \overrightarrow{f} \cdot \overrightarrow{f} + (\cdots, y \cdot \vec{z})$ $\int d\mathbf{r}' \left(-\vec{\mathbf{f}}', \vec{\mathbf{f}} \right) \stackrel{\hat{\mathbf{f}}}{\underset{n^2}{\rightarrow}} = \left(\oint d\vec{\mathbf{a}}' \cdot \begin{pmatrix} \mathbf{x} - \mathbf{x}' \\ n^3 \end{pmatrix} \vec{\mathbf{f}}' \right) \stackrel{\hat{\mathbf{f}}}{\underset{\mathbf{x}}{\rightarrow}} + \cdots$ Ampere's law $\therefore \quad \left| \overrightarrow{\nabla} \times \overrightarrow{B} = \mu_0 \overrightarrow{J} \right|$ Integrate over arbitrary open surface S

and use Stoke's theorem to find



total current parsing through S $\oint \vec{B} \cdot d\vec{\ell} = \mu_0 \int \vec{J} \cdot d\vec{a} = \mu_0 I_{enc}$ $G = \int \vec{B} \cdot d\vec{\ell} = \mu_0 \int \vec{J} \cdot d\vec{a} = \mu_0 I_{enc}$ for any C c any S such that $\partial S = C$ (Remember RHR for Stakes theorem: $\hat{n} \propto d\tilde{a} \Rightarrow gives sign of Ienc$, \hat{f}_{C} · Just as with the integral form of Guoss' law, $9_s \vec{E} \cdot d\vec{a} = \frac{1}{\epsilon_0} Q_{enc}$, the integral form of Ampere's law is useful when the problem has alot of symmetry: - infinite straight lines Ex 5.7 - infinite planes Ex5.8 - infinite solenoids Ex5.9 - circular solenoids ("toroids") Ex 5.10 Ex 5.9: * construct * construct construct

$$\mu_{o}\vec{J} = \vec{\nabla} \times \vec{B} = \vec{\nabla} \times (\vec{\nabla} \times \vec{A})$$
$$= \vec{\nabla}(\vec{\nabla} \cdot \vec{A}) - \nabla^{2}\vec{A}$$

But: can alway choose
$$\vec{A}$$
 so that
 $\vec{\nabla} \cdot \vec{A} = 0$ "Coulomb gauge"

Proof: If
$$\nabla \cdot \vec{A} \neq 0$$
, define $\vec{A}' = \vec{A} + \vec{\nabla} \lambda$
such that $\nabla^2 \lambda = -\vec{\nabla} \cdot \vec{A}$. (This is
just Poisson's eqn for λ with "source" $\vec{\nabla} \cdot \vec{A}$,
which we know has a solotion.) Then
 $\vec{\nabla} \cdot \vec{A}' = \vec{\nabla} \cdot \vec{A} + \vec{\nabla} \cdot \vec{\nabla} \lambda = \vec{\nabla} \cdot \vec{A} + \nabla^2 \lambda = \vec{\nabla} \cdot \vec{A} - \vec{\nabla} \cdot \vec{A} = 0.$)

- In Coulomb gauge, Amperés law becomes

$$\nabla^2 \vec{A} = -\mu_0 \vec{J}$$

Which is just a vector version of
Poisson's equ, whose solution (component
by component) via Coulomb's law t is

$$\vec{A}(\vec{r}) = \frac{M_0}{4\pi} \int dz' \frac{\vec{J}(\vec{r}')}{rc} \qquad \begin{pmatrix} assuming \\ \vec{J} \rightarrow 0 & e^{\infty} \end{pmatrix}$$

 $(* \text{ compare: } \nabla^2 V = -\frac{1}{\epsilon_0} p \Leftrightarrow V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int dz' \frac{p(\vec{r}')}{rc} \end{pmatrix}$
Not as useful as V in static situations...

But is useful for developing

Take
$$f = \chi'_i$$
 (one of the Cartesian coordinates)
Then $\overline{\nabla}' f = \chi'_i$ so get

$$o = \int dz J_i \dots M_o(\hat{r}) = 0 \dots J$$

oIf write this for caned loop C than

$$\int dz' \ \overline{f}(\overline{v}') \cdots \rightarrow \oint d\ell' \ \overline{I}(\overline{v}') \cdots = I \ \oint d\overline{e}' \cdots$$

so absence of magnetic monople
becomes
 $0 = \int dz' \ \overline{f}(\overline{v}') = I \ \oint d\overline{e}' \rightarrow \oint d\overline{e}' = 0.$

$$\vec{M}_{1}(\vec{r}) \stackrel{!}{=} \int dz' r' P_{1}(\sigma \theta') \vec{J}(\vec{r}') \\ = \int dz' r' \cos \theta' \vec{J}(\vec{r}') \\ = \int dz' r' (\vec{r}' \cdot \vec{r}) \vec{J}(\vec{r}') \\ = \int dz' (\vec{r} \cdot \vec{r}') \vec{J}(\vec{r}')$$

Considu it Cartesian component:

 $(M_i)_i = \hat{r} \cdot \int dc' \vec{r}' J_i(\vec{r}') \quad (\hat{r} = \frac{\vec{r}}{r} = \frac{\xi_{x_i} \hat{x_i}}{r})$ $= \frac{1}{r} \sum_{i=1}^{2} X_{i} \int dz' X_{j}' J_{i}(\vec{r}')$

Now use math lemma proved above with $f = \chi'_i \chi'_j \Rightarrow$ $0 = \left(de' \overline{J}(\vec{r}') \cdot \overline{\nabla}(\pi_i' \pi_j') \right)$ $= \left(d\tau' \,\overline{\mathcal{T}}(\vec{r}') \cdot \left[\pi_i' \,\hat{\chi}_j' + \chi_j' \,\hat{\pi}_i' \right] \right)$ $= \int dz' \left[x_i' J_j(\vec{r}') + x_j' J_i(\vec{r}') \right]$ Use this to rewrite $\int d\mathbf{r}' \times_j J_i(\vec{r}') = \frac{1}{2} \int d\mathbf{r}' \left[\times_j J_i(\vec{r}') - \chi_i J_j(\vec{r}') \right]$ and plug into (M,): to get $(M_{1})_{i} = \frac{1}{2r} \sum_{j=1}^{3} x_{j} \int dz' (x_{i}' J_{j}'(\vec{r}') - x_{j}' J_{i}'(\vec{r}')]$ = - (Z X Eijk Sde'(r'×J(r'))k $= -\frac{1}{2r} \left[\vec{r} \times \int dz' (\vec{r}' \times \vec{J}(\vec{r}')) \right]_{k}$

$$\vec{M}_{l} = -\frac{1}{2} \hat{\Gamma} \times \int Az' (\vec{r}' \times \vec{J}(\vec{r}'))$$

· It is conventional to define:

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$$\widetilde{\mathcal{M}}(\widetilde{r}') \doteq \frac{1}{2} \widetilde{r}' \times \widetilde{J}(\widetilde{r}')$$

$$\widetilde{m} \doteq \frac{1}{2} \int dz' (\widetilde{r}' \times \widetilde{J}(\widetilde{r}'))$$

$$\widetilde{m} \operatorname{agnetic moment}^{i}$$

$$(\widetilde{m}_{1} = -\widetilde{r} \times \widetilde{m})$$

$$\widetilde{u} \operatorname{analog} \circ J \quad \overrightarrow{p}, \ \operatorname{electric} \ \operatorname{dipole moment})$$

$$\widetilde{M}_{1} = -\frac{1}{2} \widehat{r} \times (\operatorname{I} \oint \widetilde{r}' \times d\widetilde{z}') = \frac{1}{2} \widehat{r} \times (\oint d\widetilde{z}' \times \widetilde{r}')$$

$$\widetilde{m} = \frac{1}{2} \oint_{c} \widetilde{r}' \times d\widetilde{z}' \doteq \operatorname{I} \int d\widetilde{a}$$

$$\lim_{c} \operatorname{Sin ang surface} s.t. \quad \Im S = C$$

$$(\operatorname{Problem 1.61 of Griffithe})$$

o "Pure" dipole = infinitesinal loop ∫sdà->0 & I→0

$$Tf \quad th = m \hat{z}, then$$

$$\vec{A}_{dy}(\vec{r}) = \frac{\mu_0}{4\pi} \quad \frac{m \sin \theta}{r^2} \hat{\psi}$$

$$\vec{B}_{dij}(\vec{r}) = \vec{\nabla} \times \vec{A}_{dip} = \frac{\mu_0 m}{4\pi r^3} (2\cos\theta \hat{r} + \sin\theta \hat{\theta})$$

$$= \frac{\mu_0}{4\pi} \frac{1}{r^2} [3(m \cdot \hat{r})\hat{r} - m]$$

$$\vec{\nabla} = \frac{1}{4\pi r} \int_{r^2}^{2} [3(m \cdot \hat{r})\hat{r} - m]$$

$$\vec{\nabla} = \frac{1}{4\pi \epsilon_0} \int_{r^2}^{2} (\cos\theta \hat{r} + \sin\theta \hat{\theta})$$

$$\vec{E}_{dip}(\vec{r}) = \frac{1}{4\pi \epsilon_0} \int_{r^2}^{r \cos \theta} \frac{1}{r^2} (2\cos\theta \hat{r} + \sin\theta \hat{\theta})$$

$$= \frac{1}{4\pi \epsilon_0} \frac{1}{r^3} [3(\vec{p} \cdot \hat{r})\hat{r} - \vec{p}].$$

<u>Boundary conditions on BeA</u>
 Discontinuity at a surface canent density K

$$\nabla \cdot \vec{B} = 0 \implies O \vec{B} \cdot d\vec{n} = 0$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} \Rightarrow \oint \vec{B} \cdot d\vec{I} = \mu_0 \text{ Ienc}$$

$$\lim_{\substack{K \to 0 \\ C \to 0}} \Rightarrow \tilde{B}_{above}^{I} - \tilde{B}_{belns}^{I} = \mu_0 \vec{K}$$

$$T \circ gether \Rightarrow \vec{B}_{cbove} - \vec{B}_{belns} = M_0 (\vec{K} \times \hat{n})$$

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Enboure - Ébelow =
$$\frac{1}{e_0}$$
 \hat{n}
an Vabore - $\frac{3}{24}$ Vbelow = $-\frac{1}{e_0}$ \hat{r} .)