

Families of Solution Curves for Some Non-autonomous Problems

Philip Korman¹

Received: 10 March 2015 / Accepted: 22 November 2015
© Springer Science+Business Media Dordrecht 2015

Abstract The paper studies families of positive solution curves for non-autonomous two-point problems

$$u'' + \lambda f(u) - \mu g(x) = 0, \quad -1 < x < 1, \quad u(-1) = u(1) = 0,$$

depending on two positive parameters λ and μ . We regard λ as a primary parameter, giving us the solution curves, while the secondary parameter μ allows for evolution of these curves. We give conditions under which the solution curves do not intersect, and the maximum value of solutions provides a global parameter. Our primary application is to constant yield harvesting for diffusive logistic equation. We implement numerical computations of the solution curves, using continuation in a global parameter, a technique that we developed in (Korman in Nonlinear Anal. 93:226, 2013).

Keywords Families of solution curves · Fishing models · Numerical computations

Mathematics Subject Classification 34B15 · 92D25

1 Introduction

We study positive solutions of non-autonomous two-point problems

$$u'' + \lambda f(u) - \mu g(x) = 0, \quad -1 < x < 1, \quad u(-1) = u(1) = 0, \quad (1.1)$$

depending on two positive parameters λ and μ . We assume that $f(u) \in C^2(\bar{R}_+)$, and $g(x) \in C^1(-1, 1) \cap C[-1, 1]$ satisfies

$$g(-x) = g(x), \quad \text{for } x \in (0, 1), \quad (1.2)$$

✉ P. Korman
kormanp@ucmail.uc.edu

¹ Department of Mathematical Sciences, University of Cincinnati, Cincinnati, OH 45221-0025, United States

$$g(0) > 0, \quad \text{and} \quad xg'(x) \geq 0, \quad \text{for } x \in (-1, 1). \quad (1.3)$$

In case $g(x)$ is a constant, one can use the time map method, see K.C. Hung and S.H. Wang [7, 8] who have studied similar multiparameter problems, or the book by S.P. Hastings and J.B. McLeod [6]. We show that under the conditions (1.2) and (1.3) one can still get detailed results on the solution curves $u = u(x, \lambda)$, where we regard λ as a primary parameter, and on the evolution of these curves when the secondary parameter μ changes. We say that the solution curves $u = u(x, \lambda)$ are the λ -curves. We also consider the μ -curves, by regarding λ as the secondary parameter.

By B. Gidas, W.-M. Ni and L. Nirenberg [4], any positive solution of (1.1) is an even function, and moreover $u'(x) < 0$ for $x \in (0, 1)$. It follows that $u(0)$ is the maximum value of the solution $u(x)$. Our first result says that $u(0)$ is a *global parameter*, i.e., its value uniquely determines the solution pair $(\lambda, u(x))$ (μ is assumed to be fixed). It follows that a planar curve $(\lambda, u(0))$ gives a faithful representation of the solution set of (1.1), so that $(\lambda, u(0))$ describes the *global solution curve*. Then we show positivity of any non-trivial solution of the linearized problem for (1.1). This allows us to compute the direction of turn for convex and concave $f(u)$.

Turning to the secondary parameter μ , we show that solution curves at different μ 's do not intersect, which allows us to discuss the evolution of solution curves in μ .

We apply our results to a logistic model with fishing. S. Oruganti, J. Shi, and R. Shivaji [16] considered a class of general elliptic equations on an arbitrary domain, which includes

$$u'' + \lambda u(1 - u) - \mu g(x) = 0, \quad -1 < x < 1, \quad u(-1) = u(1) = 0.$$

They proved that for λ sufficiently close to the principal eigenvalue λ_1 , the μ -curves are as in Fig. 2 below. We show that such curves are rather special, with the solution curves as in Fig. 3 below being more common. Our approach is to study the λ -curves first, leading to the understanding of the μ -curves. We obtain an exhaustive result in case $g(x)$ is a constant. The parameter $\mu > 0$ quantifies the amount of fishing in the logistic model. We also consider the case $\mu < 0$, corresponding to “stocking” of fish. Previous work on the logistic equation with harvesting also includes D.G. Costa et al. [3], and P. Girão and H. Tehrani [5].

Using the fact that $u(0)$ is a global parameter, we implement numerical computations of the solution curves, illustrating our results. We use continuation in a global parameter, a technique that we developed in [11].

2 Families of Solution Curves

The following result is included in B. Gidas, W.-M. Ni and L. Nirenberg [4], see also P. Korman [9] for an elementary proof.

Lemma 2.1 *Under the conditions (1.2) and (1.3), any positive solution of (1.1) is an even function, with $u'(x) < 0$ for all $x \in (0, 1]$, so that $x = 0$ is a point of global maximum.*

We begin by considering the secondary parameter μ to be fixed. To stress that, we call $h(x) = \mu g(x)$, and consider positive solutions of

$$u'' + \lambda f(u) - h(x) = 0, \quad -1 < x < 1, \quad u(-1) = u(1) = 0. \quad (2.1)$$

Lemma 2.2 Assume that $f(u) \in C(\bar{R}_+)$ satisfies $f(u) > 0$ for $u > 0$, and $h(x)$ satisfies the conditions (1.2) and (1.3). Then $u(0)$, the maximum value of any positive solution, uniquely identifies the solution pair $(\lambda, u(x))$.

Proof Observe from (2.1) that $f(u(0)) > 0$ for any positive solution $u(x)$. Let $(\lambda_1, v(x))$ be another solution of (2.1), with $v(0) = u(0)$, $v'(0) = u'(0) = 0$, and $\lambda_1 > \lambda$. From Eq. (2.1), $v''(0) < u''(0)$, and hence $v(x) < u(x)$ for small $x > 0$. Let $\xi \leq 1$ be their first point of intersection, i.e., $u(\xi) = v(\xi)$. Clearly

$$|v'(\xi)| \leq |u'(\xi)|. \quad (2.2)$$

Multiplying Eq. (2.1) by u' , and integrating over $(0, \xi)$, we get

$$\frac{1}{2}u'^2(\xi) + \lambda[F(u(\xi)) - F(u(0))] - \int_0^\xi h(x)u'(x) dx = 0,$$

where $F(u) = \int_0^u f(t) dt$. Integrating by parts, we conclude

$$\frac{1}{2}u'^2(\xi) = \lambda[F(u(0)) - F(u(\xi))] + h(\xi)u(\xi) - h(0)u(0) - \int_0^\xi h'(x)u(x) dx.$$

Similarly,

$$\frac{1}{2}v'^2(\xi) = \lambda_1[F(u(0)) - F(u(\xi))] + h(\xi)u(\xi) - h(0)u(0) - \int_0^\xi h'(x)v(x) dx,$$

and then, subtracting,

$$\frac{1}{2}[u'^2(\xi) - v'^2(\xi)] = (\lambda - \lambda_1)[F(u(0)) - F(u(\xi))] + \int_0^\xi h'(x)(v(x) - u(x)) dx.$$

Since $v(x) < u(x)$ on $(0, \xi)$, the second term on the right is non-positive, while the first term on the right is negative, since $F(u)$ is an increasing function. It follows that $|u'(\xi)| < |v'(\xi)|$, which contradicts (2.2). \square

Lemma 2.3 Assume that $f(u) \in C(\bar{R}_+)$, and $h(x)$ satisfies the conditions (1.2) and (1.3). Then the curves of positive solutions of (1.1) in $(\lambda, u(0))$ plane, computed at different μ 's, do not intersect.

Proof Assume, on the contrary, that $v(x)$ is a solution of

$$v'' + \lambda f(v) - \mu_1 g(x) = 0, \quad -1 < x < 1, \quad v(-1) = v(1) = 0, \quad (2.3)$$

with $\mu_1 > \mu$, but $u(0) = v(0)$, where $u(x)$ is a solution of (1.1). Then $u''(0) < v''(0)$, and hence $u(x) < v(x)$ for small $x > 0$. Let $\xi \leq 1$ be their first point of intersection, i.e., $u(\xi) = v(\xi)$. Clearly

$$|u'(\xi)| \leq |v'(\xi)|. \quad (2.4)$$

Multiplying Eq. (1.1) by u' , and integrating over $(0, \xi)$, we get

$$\frac{1}{2}u'^2(\xi) + \lambda[F(u(\xi)) - F(u(0))] = \mu \int_0^\xi g(x)u'(x) dx.$$

Similarly, using (2.3), we get

$$\frac{1}{2}v'^2(\xi) + \lambda[F(u(\xi)) - F(u(0))] = \mu_1 \int_0^\xi g(x)v'(x) dx.$$

Subtracting, we obtain

$$\begin{aligned} \frac{1}{2}[u'^2(\xi) - v'^2(\xi)] &= \mu \int_0^\xi g(x)u'(x) dx - \mu_1 \int_0^\xi g(x)v'(x) dx \\ &> \mu_1 \left[\int_0^\xi g(x)u'(x) dx - \int_0^\xi g(x)v'(x) dx \right] \\ &= \mu_1 \int_0^\xi g'(x)(v(x) - u(x)) dx > 0. \end{aligned}$$

Hence, $|u'(\xi)| > |v'(\xi)|$, which contradicts (2.4). \square

Corollary 1 Assume that λ is fixed in (1.1), and μ is the primary parameter. Assume that $f(u) \in C(\bar{R}_+)$ satisfies $f(u) > 0$ for $u > 0$, and $g(x)$ satisfies the conditions (1.2) and (1.3). Then the maximum value of solution $u(0)$ is a global parameter, i.e., it uniquely identifies the solution pair $(\mu, u(x))$.

Proof If at some λ_0 we had another solution pair $(\mu_1, u_1(x))$ with $u(0) = u_1(0)$, then the λ -curves at μ and μ_1 would intersect at $(\lambda_0, u(0))$, contradicting Lemma 2.2. \square

The linearized problem for (1.1) is

$$w'' + \lambda f'(u)w = 0, \quad -1 < x < 1, \quad w(-1) = w(1) = 0. \quad (2.5)$$

We call the solution of (1.1) singular if (2.5) has non-trivial solutions. Since the solution set of (2.5) is one-dimensional (parameterized by $w'(-1)$), it follows that $w(-x) = w(x)$, and $w'(0) = 0$.

Lemma 2.4 Assume that $f(u) \in C^1(\bar{R}_+)$, and $g(x)$ satisfies the conditions (1.2) and (1.3), and let $u(x)$ be a positive solution of (1.1). Then any non-trivial solution of (2.5) is of one sign, i.e., we may assume that $w(x) > 0$ for all $x \in (-1, 1)$.

Proof Assuming the contrary, we can find a point $\xi \in (0, 1)$ such that $w(\xi) = w(1) = 0$, and $w(x) > 0$ on $(\xi, 1)$. Differentiate Eq. (1.1)

$$u''' + \lambda f'(u)u' - \mu g'(x) = 0.$$

Combining this with (2.5),

$$(u'w' - u''w)' + \mu g'(x) = 0. \quad (2.6)$$

Integrating over $(\xi, 1)$,

$$u'(1)w'(1) - u'(\xi)w'(\xi) + \mu \int_\xi^1 g'(x) dx = 0.$$

All three terms on the left are non-negative, and the second one is positive, which results in a contradiction. \square

Lemma 2.5 Assume that $f(u) \in C(\bar{R}_+)$, and $g(x)$ satisfies the conditions (1.2) and (1.3). Let $u(x)$ be a positive and singular solution of (1.1), with $u'(1) < 0$, and $w(x) > 0$ a solution of (2.5). Then

$$\int_0^1 f(u)w \, dx > 0.$$

Proof By (2.6), the function $u'w' - u''w$ is non-increasing on $(0, 1)$, and hence

$$u'w' - u''w \geq u'(1)w'(1).$$

Integrating over $(0, 1)$, and expressing u'' from (1.1), gives

$$2 \int_0^1 w(\lambda f(u) - \mu g(x)) \, dx \geq u'(1)w'(1) > 0,$$

which implies the lemma. \square

Theorem 2.1 Assume that $f(u) \in C^1(\bar{R}_+)$, and $g(x)$ satisfies the conditions (1.2) and (1.3). Then positive solutions of the problem (1.1) can be continued globally either in λ or in μ , on smooth solution curves, so long as $u'(1) < 0$.

Proof At any non-singular solution of (1.1), the implicit function theorem applies (see e.g., L. Nirenberg [13], or P. Korman [10] for more details), while at the singular solutions the Crandall-Rabinowitz [2] bifurcation theorem applies, with Lemma 2.5 verifying its crucial “transversality condition”, see e.g., P. Korman [10] (or [12, 15]) for more details. In either case we can always continue the solution curves. \square

Theorem 2.2

- (i) Assume that $f(u) \in C^2[0, \infty)$ is concave. Then only turns to the right are possible in the $(\lambda, u(0))$ plane, when solutions are continued in λ , and only turns to the left are possible in the $(\mu, u(0))$ plane, when solutions are continued in μ .
- (ii) Assume that $f(u) \in C^2[0, \infty)$ is convex. Then only turns to the left are possible in the $(\lambda, u(0))$ plane, when solutions are continued in λ , and only turns to the right are possible in the $(\mu, u(0))$ plane, when solutions are continued in μ .

Proof Assume that when continuing in λ , we encounter a critical point (λ_0, u_0) , i.e., the problem (2.5) has a non-trivial solution $w(x) > 0$. By Lemma 2.5, the Crandall-Rabinowitz [2] bifurcation theorem applies. This theorem implies that the solution set near (λ_0, u_0) is given by a curve $(\lambda(s), u(s))$ for $s \in (-\delta, \delta)$, with $\lambda(s) = \lambda_0 + \frac{1}{2}\lambda''(0)s^2 + o(s^2)$, and

$$\lambda''(0) = -\lambda_0 \frac{\int_{-1}^1 f''(u)w^3 \, dx}{\int_{-1}^1 f(u)w \, dx},$$

see e.g., [10]. When $f(u)$ is concave (convex), $\lambda''(0)$ is positive (negative), and a turn to the right (left) occurs on the solution curve.

If a critical point (μ_0, u_0) is encountered when continuing in μ , the Crandall-Rabinowitz [2] bifurcation theorem implies that the solution set near (μ_0, u_0) is given by $(\mu(s), u(s))$ for $s \in (-\delta, \delta)$, with $\mu(s) = \mu_0 + \frac{1}{2}\mu''(0)s^2 + o(s^2)$, and

$$\mu''(0) = \lambda \frac{\int_{-1}^1 f''(u)w^3 dx}{\int_{-1}^1 g(x)w dx},$$

see e.g., [14]. When $f(u)$ is concave (convex), $\mu''(0)$ is negative (positive), and a turn to the left (right) occurs on the solution curve. \square

3 Numerical Computation of the Solution Curves

In this section we present computations of the global curves of positive solutions for the problem (1.1), which are based on our paper [11]. We assume that the conditions of Lemma 2.2 hold, so that $\alpha \equiv u(0)$ is a global parameter. We think of the parameter μ as secondary, and we begin with the problem (2.1) (i.e., we set $\mu g(x) = h(x)$). Since any positive solution $u(x)$ is an even function, we shall compute it on the half-interval $(0, 1)$, by solving

$$u'' + \lambda f(u) - h(x) = 0 \quad \text{for } 0 < x < 1, \quad u'(0) = u(1) = 0. \quad (3.1)$$

A standard approach to numerical computations involves continuation in λ by using the predictor-corrector methods, see e.g., E.L. Allgower and K. Georg [1]. These methods are well developed, but not easy to implement, because the solution curve $u = u(x, \lambda)$ may consist of several parts, each having multiple turns. Here λ is a local parameter, but not a global one.

Since $\alpha = u(0)$ is a global parameter, we shall compute the solution curve $(\lambda, u(0))$ of (3.1) in the form $\lambda = \lambda(\alpha)$, with $\alpha = u(0)$. If we solve the initial value problem

$$u'' + \lambda f(u) - h(x) = 0, \quad u(0) = \alpha, \quad u'(0) = 0, \quad (3.2)$$

then we need to find λ , so that $u(1) = 0$, in order to obtain the solution of (3.1), with $u(0) = \alpha$. Rewrite Eq. (3.2) in the integral form

$$u(x) = \alpha - \lambda \int_0^x (x-t)f(u(t)) dt + \int_0^x (x-t)h(t) dt,$$

and then the equation for λ is

$$F(\lambda) \equiv u(1) = \alpha - \lambda \int_0^1 (1-t)f(u(t)) dt + \int_0^1 (1-t)h(t) dt = 0. \quad (3.3)$$

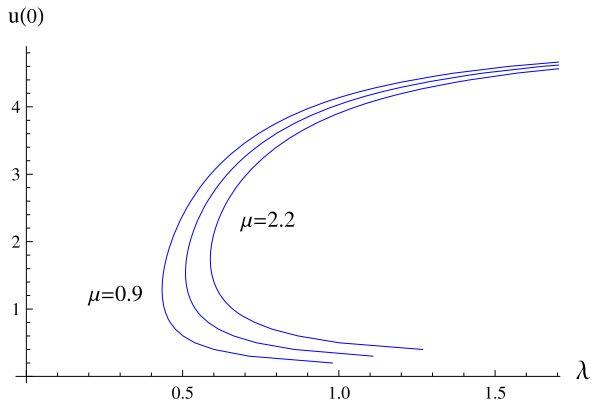
We solve this equation by using Newton's method

$$\lambda_{n+1} = \lambda_n - \frac{F(\lambda_n)}{F'(\lambda_n)}.$$

We have

$$\begin{aligned} F(\lambda_n) &= \alpha - \lambda_n \int_0^1 (1-t)f(u(t, \lambda_n)) dt + \int_0^1 (1-t)h(t) dt, \\ F'(\lambda_n) &= - \int_0^1 (1-t)f(u(t, \lambda_n)) dt - \lambda_n \int_0^1 (1-t)f'(u(t, \lambda_n))u_\lambda dt, \end{aligned}$$

Fig. 1 The curve of positive solutions for the problem (3.6) at $\mu = 0.9$, $\mu = 1.5$ and $\mu = 2.2$



where $u(x, \lambda_n)$ and u_λ are respectively the solutions of

$$u'' + \lambda_n f(u) - h(x) = 0, \quad u(0) = \alpha, \quad u'(0) = 0, \quad (3.4)$$

$$u_\lambda'' + \lambda_n f'(u(x, \lambda_n)) u_\lambda + f(u(x, \lambda_n)) = 0, \quad u_\lambda(0) = 0, \quad u_\lambda'(0) = 0. \quad (3.5)$$

(As we vary λ , we keep $u(0) = \alpha$ fixed, that is why $u_\lambda(0) = 0$.) This method is very easy to implement. It requires repeated solutions of the initial value problems (3.4) and (3.5) (using the NDSolve command in *Mathematica*).

Example Using *Mathematica* software, we have computed the solution curves in $(\lambda, u(0))$ plane for the problem

$$u'' + \lambda u(10 - 2u) - \mu(1 + 0.2x^2) = 0, \quad -1 < x < 1, \quad u(-1) = u(1) = 0, \quad (3.6)$$

at $\mu = 0.9$, $\mu = 1.5$ and $\mu = 2.2$. Results are presented in Fig. 1. (The curve in the middle corresponds to $\mu = 1.5$.)

We now discuss numerical continuation of solutions in the secondary parameter. We consider again

$$u'' + \lambda f(u) - \mu g(x) = 0, \quad -1 < x < 1, \quad u(-1) = u(1) = 0, \quad (3.7)$$

and assume λ to be fixed, and we continue the solutions in μ . By Corollary 1, $\alpha = u(0)$ is a global parameter, and we shall compute the solution curve $(\mu, u(0))$ of (3.1) in the form $\mu = \mu(\alpha)$. As before, to find $\mu = \mu(\alpha)$, we need to solve

$$F(\mu) \equiv u(1) = \alpha - \lambda \int_0^1 (1-t) f(u(t)) dt + \mu \int_0^1 (1-t) g(t) dt = 0.$$

We solve this equation by using Newton's method

$$\mu_{n+1} = \mu_n - \frac{F(\mu_n)}{F'(\mu_n)},$$

with

$$F(\mu_n) = \alpha - \lambda \int_0^1 (1-t) f(u(t, \mu_n)) dt + \mu_n \int_0^1 (1-t) g(t) dt,$$

Fig. 2 The curve of positive solutions for the problem (3.8)

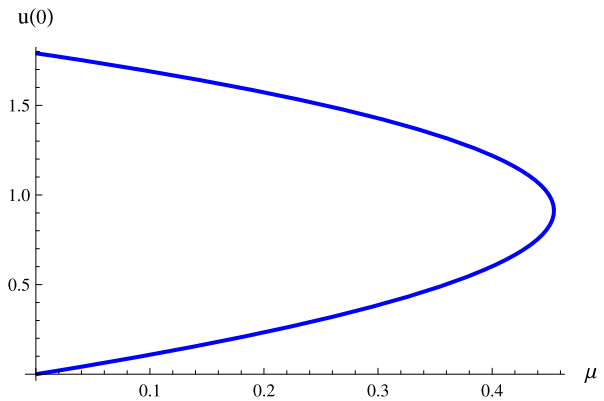
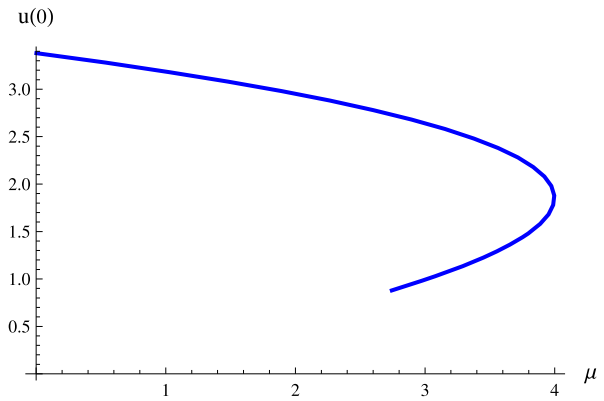


Fig. 3 The curve of positive solutions for the problem (3.9)



$$F'(\mu_n) = -\lambda \int_0^1 (1-t) f'(u(t, \mu_n)) u_\mu dt + \int_0^1 (1-t) g(t) dt,$$

where $u(x, \mu_n)$ and u_μ are respectively the solutions of

$$\begin{aligned} u'' + \lambda f(u) - \mu_n g(x) &= 0, & u(0) &= \alpha, & u'(0) &= 0, \\ u''_\mu + \lambda f'(u(x, \mu_n)) u_\mu - g(x) &= 0, & u_\mu(0) &= 0, & u'_\mu(0) &= 0. \end{aligned}$$

(As we vary μ , we keep $u(0) = \alpha$ fixed, that is why $u_\mu(0) = 0$.)

Example We have continued in μ the positive solutions of

$$u'' + u(4-u) - \mu(1+x^2) = 0, \quad -1 < x < 1, \quad u(-1) = u(1) = 0. \quad (3.8)$$

The curve of positive solutions is given in Fig. 2.

Example We have continued in μ the positive solutions of

$$u'' + 2.4u(4-u) - \mu(1+x^2) = 0, \quad -1 < x < 1, \quad u(-1) = u(1) = 0. \quad (3.9)$$

The curve of positive solutions is given in Fig. 3. At $\mu \approx 2.28634$, the solutions become sign changing, negative near $x = \pm 1$.

4 Diffusive Logistic Equation with Harvesting

Recall that the eigenvalues of

$$u'' + \lambda u = 0, \quad -1 < x < 1, \quad u(-1) = u(1) = 0$$

are $\lambda_n = \frac{n^2\pi^2}{4}$, and in particular $\lambda_1 = \frac{\pi^2}{4}$, $\lambda_2 = \pi^2$.

We consider positive solutions of

$$u'' + \lambda u(1 - u) - \mu = 0, \quad -1 < x < 1, \quad u(-1) = u(1) = 0, \quad (4.1)$$

with positive parameters λ and μ . It is easy to see that no positive solutions exist if $\lambda \leq \lambda_1 = \frac{\pi^2}{4}$, and by maximum principle any positive solution satisfies $0 < u(x) < 1$. The following result gives a complete description of the set of positive solutions.

Theorem 4.1 *For any fixed μ the set of positive solutions of (4.1) is a parabola-like curve opening to the right in $(\lambda, u(0))$ plane (the λ -curves). The upper branch continues for all λ after the turn, while the solutions on the lower branch become sign-changing after some $\lambda = \bar{\lambda}$ ($u_x(\pm 1, \bar{\lambda}) = 0$, see Fig. 1). For any fixed λ the set of positive solutions of (4.1) is a parabola-like curve opening to the left in $(\mu, u(0))$ plane (the μ -curves). Different λ -curves (and different μ -curves) do not intersect. The λ -curves and the μ -curves share the turning points. Namely, if at $\mu = \mu_0$, the λ -curve turns at the point (λ_0, α) , then at $\lambda = \lambda_0$, the μ -curve turns at the point (μ_0, α) .*

If $\lambda \in (\lambda_1, \lambda_2]$, then the μ -curve joins the point $(0, \mu_1)$, with some $\mu_1 > 0$, to $(0, 0)$, with exactly one turn to the left at some μ_0 (as in Fig. 2). If $\lambda > \lambda_2$, then the μ -curve joins the point $(0, \mu_1)$, with some $\mu_1 > 0$, to some point $(\bar{\mu} > 0, \alpha > 0)$, with exactly one turn to the left at some $\mu_0 > \bar{\mu}$ (as in Fig. 3). Solutions on the lower branch become sign-changing for $\mu < \bar{\mu}$.

We remark that in case $\lambda \in (\lambda_1, \lambda_2]$, a more general result was given in J. Shi [16], by a more involved method.

The proof will depend on several lemmas, which we state for a more general problem

$$u'' + \lambda f(u) - \mu = 0, \quad -1 < x < 1, \quad u(-1) = u(1) = 0. \quad (4.2)$$

Lemma 4.1 *Assume that $f(u) \in C^1(\bar{R}_+)$ satisfies $f(0) = 0$, and $f(u(x)) > 0$ for any positive solution of (4.2), for all $x \in (-1, 1)$. Assume that $u(x, \lambda)$ arrives at the point λ_0 where the positivity of solutions is lost (i.e., $u_x(\pm 1, \lambda_0) = 0$) with the maximum value $u(0, \lambda)$ decreasing along the solution curve. Then the positivity is lost forward in λ at λ_0 . (I.e., $u(x, \lambda) > 0$ for all $x \in (-1, 1)$ if $\lambda < \lambda_0$, and $u(x, \lambda)$ is sign-changing for $\lambda > \lambda_0$.)*

Proof Since for positive solutions $u_x(x, \lambda_0) < 0$ for $x \in (0, 1)$, the only way for solutions to become sign-changing is to have $u_x(\pm 1, \lambda_0) = 0$. Assume, on the contrary, that positivity is lost backward in λ . Then by our assumption

$$u_\lambda(0, \lambda_0) \geq 0. \quad (4.3)$$

Differentiating Eq. (4.2) in λ , we have

$$u''_\lambda + \lambda f'(u)u_\lambda = -f(u), \quad -1 < x < 1, \quad u_\lambda(-1) = u_\lambda(1) = 0. \quad (4.4)$$

Differentiating Eq. (4.2) in x , gives

$$u_x'' + \lambda f'(u)u_x = 0. \quad (4.5)$$

Combining Eqs. (4.4) and (4.5),

$$(u_\lambda' u' - u_\lambda u'')' = -f(u)u_x > 0, \quad \text{for } x \in (0, 1).$$

It follows that the function $q(x) \equiv u_\lambda' u' - u_\lambda u''$ is increasing, with $q(0) \geq 0$ by (4.3), and $q(1) = 0$, a contradiction. \square

Lemma 4.2 Assume that $f(u) \in C^1(\bar{R}_+)$ satisfies $f(0) = 0$, and $f(u(x)) > 0$ for any positive solution of (4.2), for all $x \in (-1, 1)$. Assume that $u(x, \mu)$ arrives at the point μ_0 where the positivity is lost (i.e., $u_x(\pm 1, \mu_0) = 0$) with the maximum value $u(0, \mu)$ decreasing along the solution curve. Then the positivity is lost backward in μ at μ_0 . (I.e., $u(x, \mu) > 0$ for all $x \in (-1, 1)$ if $\mu > \mu_0$, and $u(x, \mu)$ is sign-changing for $\mu < \mu_0$.)

Proof Assume, on the contrary, that positivity is lost forward in μ . Then by our assumption

$$u_\mu(0, \mu_0) \leq 0. \quad (4.6)$$

Differentiating Eq. (4.2) in μ , we have

$$u_\mu'' + \lambda f'(u)u_\mu = 1, \quad -1 < x < 1, \quad u_\mu(-1) = u_\mu(1) = 0. \quad (4.7)$$

Combining Eqs. (4.5) and (4.7),

$$(u_\mu' u' - u_\mu u'')' = u_x < 0, \quad \text{for } x \in (0, 1).$$

It follows that the function $r(x) \equiv u_\mu' u' - u_\mu u''$ is decreasing, with $r(0) \leq 0$ by (4.6), and $r(1) = 0$, a contradiction. \square

Lemma 4.3 Assume that $f(u) \in C^1[0, \infty)$, $f(0) = 0$, and $f'(u)$ is a decreasing function for $u > 0$. Then for any $\lambda > 0$ there is at most one solution pair $(\mu, u(x))$, with $u'(\pm 1) = 0$.

Proof Assume, on the contrary, that there are two solution pairs $(\mu_1, u(x))$ and $(\mu_2, v(x))$, with $\mu_2 > \mu_1$, satisfying

$$u'' + \lambda f(u) - \mu_1 = 0, \quad -1 < x < 1, \quad u(\pm 1) = u'(\pm 1) = 0, \quad (4.8)$$

$$v'' + \lambda f(v) - \mu_2 = 0, \quad -1 < x < 1, \quad v(\pm 1) = v'(\pm 1) = 0. \quad (4.9)$$

Since $v''(1) = \mu_2 > \mu_1 = u''(1)$, we have $v(x) > u(x)$ for x close to 1. Two cases are possible.

(i) $v(x) > u(x)$ for $x \in (0, 1)$. Differentiating Eqs. (4.8) and (4.9), we get

$$u_x'' + \lambda f'(u)u_x = 0, \quad u_x < 0 \quad \text{on } (0, 1), \quad u_x(0) = u_x(1) = 0,$$

$$v_x'' + \lambda f'(v)v_x = 0, \quad v_x < 0 \quad \text{on } (0, 1), \quad v_x(0) = v_x(1) = 0.$$

Since $f'(u) > f'(v)$, we have a contradiction by Sturm's comparison theorem.

(ii) There is $\xi \in (0, 1)$ such that $v(x) > u(x)$ for $x \in (\xi, 1)$, while $v(\xi) = u(\xi)$ and $u'(\xi) \leq v'(\xi) < 0$. Multiply Eq. (4.8) by u' , and integrate over $(\xi, 1)$ (with $F(u) = \int_0^u f(t) dt$)

$$-\frac{1}{2}u'^2(\xi) - \lambda F(u(\xi)) + \mu_1 u(\xi) = 0.$$

Similarly, from (4.9)

$$-\frac{1}{2}v'^2(\xi) - \lambda F(u(\xi)) + \mu_2 u(\xi) = 0.$$

Subtracting

$$(\mu_2 - \mu_1)u(\xi) = \frac{1}{2}(v'^2(\xi) - u'^2(\xi)).$$

The quantity on the left is positive, while the one on the right is non-positive, a contradiction. \square

Lemma 4.4 For any $\alpha \in (0, \frac{3}{4})$ there exists a unique pair $(\bar{\lambda}, \bar{\mu})$, with $\bar{\lambda} > \lambda_2$ and $\bar{\mu} > 0$, and a positive solution of (4.1) with $u(0) = \alpha$ and $u'(\pm 1) = 0$. Moreover, if $\bar{\mu} \rightarrow 0$, then $\bar{\lambda} \downarrow \lambda_2 = \pi^2$.

Proof Multiplying Eq. (4.1) by u' , we see that the solution with $u'(\pm 1) = 0$ satisfies

$$\frac{1}{2}u'^2 + \bar{\lambda}\left(\frac{1}{2}u^2 - \frac{1}{3}u^3\right) - \bar{\mu}u = 0. \quad (4.10)$$

Evaluating this at $x = 0$

$$\bar{\lambda}\left(\frac{1}{2}\alpha - \frac{1}{3}\alpha^2\right) = \bar{\mu}. \quad (4.11)$$

We also express from (4.10)

$$\frac{du}{dx} = -\sqrt{2\bar{\mu}u - \bar{\lambda}\left(u^2 - \frac{2}{3}u^3\right)}, \quad \text{for } x \in (0, 1).$$

We express $\bar{\mu}$ from (4.11), separate the variables and integrate, getting

$$\int_0^\alpha \frac{du}{\sqrt{(\alpha - \frac{2}{3}\alpha^2)u - (u^2 - \frac{2}{3}u^3)}} = \sqrt{\bar{\lambda}}.$$

Setting here $u = \alpha v$, we express

$$\bar{\lambda} = \left(\int_0^1 \frac{dv}{\sqrt{(1 - \frac{2}{3}\alpha)v - (v^2 - \frac{2}{3}\alpha v^3)}} \right)^2. \quad (4.12)$$

The formulas (4.12) and (4.11) let us compute $\bar{\lambda}$, and then $\bar{\mu}$, for any $\alpha \in (0, \frac{3}{4})$. (For $\alpha \in (0, \frac{3}{4})$, the quantity inside the square root in (4.12), which is $v(1 - v)[1 - \frac{2}{3}\alpha(1 + v)]$, is positive for all $v \in (0, 1)$.)

If $\bar{\mu} \rightarrow 0$, then from (4.11), $\alpha \rightarrow 0$ (recall that $\lambda > \lambda_1$), and then from (4.12)

$$\bar{\lambda} \downarrow \left(\int_0^1 \frac{dv}{\sqrt{v-v^2}} \right)^2 = \pi^2,$$

completing the proof. \square

Proof of Theorem 4.1 It is easier to understand the λ -curves, so we assume first that μ is fixed. It is well known that for λ large enough the problem (4.1) has a positive stable (“large”) solution, with $u(0, \lambda)$ increasing in λ (see e.g., [14]). Let us continue this solution for decreasing λ . This curve does not continue to λ 's $\leq \lambda_1$, and it cannot become sign-changing while continued to the left, by Lemma 4.1, hence a turn to the right must occur. After the turn, standard arguments imply that solutions develop zero slope at ± 1 , and become sign-changing for $\lambda > \bar{\lambda}_\mu$, see e.g., [10]. By Theorem 2.2, exactly one turn occurs on each λ -curve, and by Lemma 4.4, $\inf_\mu \bar{\lambda}_\mu = \lambda_2 = \pi^2$.

Turning to the μ -curves, for any fixed $\tilde{\lambda} > \lambda_1$ we can find a positive solution on the curve $\mu = 0$ (the curve that bifurcates from the trivial solution at $\lambda = \lambda_1$). We now slide down from this point in the $(\lambda, u(0))$ plane, by varying μ . As we increase μ (keeping $\tilde{\lambda}$ fixed), we slide to different λ -curves. At some μ we reach a λ -curve which has its turn at $\lambda = \tilde{\lambda}$. After that point, μ begins to decrease on the λ -curves. If $\tilde{\lambda} \in (\lambda_1, \lambda_2)$, we slide all the way to $\mu = 0$, by Lemma 4.4. Hence, the μ -curve at $\tilde{\lambda}$ is as in Fig. 2. In case $\tilde{\lambda} > \lambda_2$, by Lemma 4.4, we do not slide all the way to $\mu = 0$, and hence the μ -curve at $\tilde{\lambda}$ is as in Fig. 3. By Lemma 4.3, this curve exhausts the set of all positive solutions of (4.1) (any other solution would lie on a solution curve with no place to go, when continued in μ). \square

Remark Our results also imply that the μ -curves described in Theorem 4.1 continue without turns for all $\mu < 0$. (Observe that Lemma 2.4 holds for autonomous problems, regardless of the sign of μ , see e.g., [10].) Negative μ 's correspond to “stocking” of fish, instead of “fishing”. In Fig. 4 we present the solution curve of the problem

$$u'' + 6u(1-u) - \mu = 0, \quad -1 < x < 1, \quad u(-1) = u(1) = 0. \quad (4.13)$$

Observe that $u(0) > 1$ for $\mu < \mu_0$, for some $\mu_0 < 0$.

For the non-autonomous version of the fishing problem

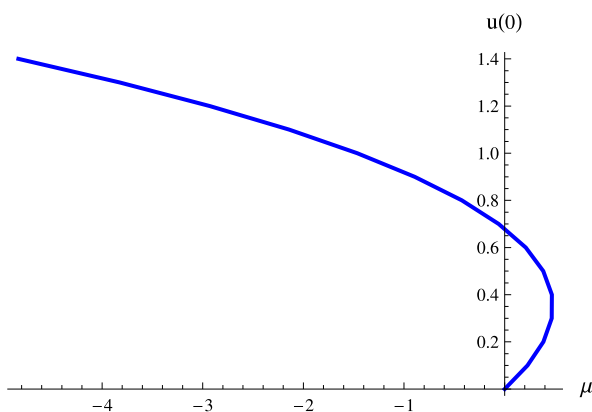
$$u'' + \lambda u(1-u) - \mu g(x) = 0, \quad -1 < x < 1, \quad u(-1) = u(1) = 0 \quad (4.14)$$

we were not able to extend any of the above lemmas. Still it appears easier to understand the λ -curves first. Here we cannot rule out the possibility of the λ -curves losing their positivity backward, and thus never making a turn to the right.

We prove next that a turn to the right does occur for solution curves of (4.14) that are close to the curve bifurcating from zero at $\lambda = \lambda_1$. Let $\bar{\lambda}_\mu$ be the value of λ , at which positivity is lost for a given μ (so that $u_x(\pm 1, \bar{\lambda}_\mu) = 0$). We claim that $\inf_{\mu > 0} \bar{\lambda}_\mu > \lambda_1$. Indeed, assuming otherwise, we can find a sequence $\{\mu_n\} \rightarrow 0$, with $\bar{\lambda}_{\mu_n} \rightarrow \lambda_1$. By a standard argument, $\frac{u(x, \bar{\lambda}_{\mu_n})}{u(0, \bar{\lambda}_{\mu_n})} \rightarrow w(x) > 0$, where

$$w'' + \lambda_1 w = 0, \quad w(\pm 1) = w'(\pm 1) = 0,$$

Fig. 4 The solution curve for the problem (4.13)



which is not possible. It follows that for a fixed $\lambda \in (\lambda_1, \inf_{\mu>0} \bar{\lambda}_\mu]$, the μ -curve for (4.14) is as in Fig. 2. (Notice that this also implies that the λ -curves for small μ do turn.) A similar result for general PDE's was proved in S. Oruganti, J. Shi, and R. Shivaji [14]. In case $\lambda > \inf_{\mu>0} \bar{\lambda}_\mu$, the μ -curves are different, although we cannot prove in general that they are as in Fig. 3. (For example, we cannot rule out the possibility that the μ -curves consist of several pieces.)

References

1. Allgower, E.L., Georg, K.: Numerical Continuation Methods. An Introduction. Springer Series in Computational Mathematics, vol. 13. Springer, Berlin (1990)
2. Crandall, M.G., Rabinowitz, P.H.: Bifurcation, perturbation of simple eigenvalues and linearized stability. Arch. Ration. Mech. Anal. **52**, 161–180 (1973)
3. Costa, D.G., Drábek, P., Tehrani, H.: Positive solutions to semilinear elliptic equations with logistic type nonlinearities and constant yield harvesting in R^n . Commun. Partial Differ. Equ. **33**, 1597–1610 (2008)
4. Gidas, B., Ni, W.-M., Nirenberg, L.: Symmetry and related properties via the maximum principle. Commun. Math. Phys. **68**, 209–243 (1979)
5. Girão, P., Tehrani, H.: Positive solutions to logistic type equations with harvesting. J. Differ. Equ. **247**(2), 574–595 (2009)
6. Hastings, S.P., McLeod, J.B.: Classical Methods in Ordinary Differential Equations. With Applications to Boundary Value Problems. Graduate Studies in Mathematics, vol. 129. Am. Math. Soc., Providence (2012)
7. Hung, K.C., Wang, S.H.: Classification and evolution of bifurcation curves for a multiparameter p-Laplacian Dirichlet problem. Nonlinear Anal. **74**(11), 3589–3598 (2011)
8. Hung, K.C., Wang, S.H.: Bifurcation diagrams of a p-Laplacian Dirichlet problem with Allee effect and an application to a diffusive logistic equation with predation. J. Math. Anal. Appl. **375**(1), 294–309 (2011)
9. Korman, P.: Symmetry of positive solutions for elliptic problems in one dimension. Appl. Anal. **58**(3–4), 351–365 (1995)
10. Korman, P.: Global Solution Curves for Semilinear Elliptic Equations. World Scientific, Hackensack (2012)
11. Korman, P.: Exact multiplicity and numerical computation of solutions for two classes of non-autonomous problems with concave-convex nonlinearities. Nonlinear Anal. **93**, 226–235 (2013)
12. Korman, P., Li, Y., Ouyang, T.: Exact multiplicity results for boundary-value problems with nonlinearities generalising cubic. Proc. R. Soc. Edinb., Sect. A **126A**, 599–616 (1996)
13. Nirenberg, L.: Topics in Nonlinear Functional Analysis. Courant Institute Lecture Notes. Am. Math. Soc., Providence (1974)

14. Oruganti, S., Shi, J., Shivaji, R.: Diffusive logistic equation with constant yield harvesting. I. Steady states. *Transl. Am. Math. Soc.* **354**(9), 3601–3619 (2002)
15. Ouyang, T., Shi, J.: Exact multiplicity of positive solutions for a class of semilinear problems, II. *J. Differ. Equ.* **158**(1), 94–151 (1999)
16. Shi, J.: A radially symmetric anti-maximum principle and applications to fishery management models. *Electron. J. Differ. Equ.* **27** (2004), 13 pp. (electronic)