Curves of equiharmonic solutions, and problems at resonance

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Abstract

We consider the semilinear Dirichlet problem

$$\Delta u + kg(u) = \mu_1 \varphi_1 + \dots + \mu_n \varphi_n + e(x)$$
 for $x \in \Omega$, $u = 0$ on $\partial \Omega$,

where φ_k is the k-th eigenfunction of the Laplacian on Ω and $e(x) \perp \varphi_k$, $k=1,\ldots,n$. Write the solution in the form $u(x)=\sum_{i=1}^n \xi_i \varphi_i + U(x)$, with $U\perp \varphi_k$, $k=1,\ldots,n$. Starting with k=0, when the problem is linear, we continue the solution in k by keeping $\xi=(\xi_1,\ldots,\xi_n)$ fixed, but allowing for $\mu=(\mu_1,\ldots,\mu_n)$ to vary. Studying the map $\xi\to\mu$ provides us with the existence and multiplicity results for the above problem. We apply our results to problems at resonance, at both the principal and higher eigenvalues. Our approach is suitable for numerical calculations, which we implement, illustrating our results.

Key words: Curves of equiharmonic solutions, problems at resonance.

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1 Introduction

We study existence and multiplicity of solutions for a semilinear problem

(1.1)
$$\Delta u + kg(u) = f(x) \text{ for } x \in \Omega,$$
$$u = 0 \text{ on } \partial\Omega$$

on a smooth bounded domain $\Omega \subset \mathbb{R}^m$. Here the functions $f(x) \in L^2(\Omega)$ and $g(u) \in C^1(\mathbb{R})$ are given, k is a parameter. We approach this problem

by continuation in k. When k=0 the problem is linear. It has a unique solution, as can be seen by using Fourier series of the form $u(x) = \sum_{j=1}^{\infty} u_j \varphi_j$, where φ_j is the j-th eigenfunction of the Dirichlet Laplacian on Ω , with $\int_{\Omega} \varphi_j^2 dx = 1$, and λ_j is the corresponding eigenvalue. We now continue the solution in k, looking for a solution pair (k, u), or u = u(x, k). At a generic point (k, u) the implicit function theorem applies, allowing the continuation in k. These are the regular points, where the corresponding linearized problem has only the trivial solution. So until a singular point is encountered, we have a solution curve u = u(x, k). At a singular point practically anything imaginable might happen. At some singular points the M.G. Crandall and P.H. Rabinowitz bifurcation theorem [5] applies, giving us a curve of solutions through a singular point. But even in this favorable situation there is a possibility that solution curve will "turn back" in k.

In [10] we have presented a way to continue solutions forward in k, which can take us through any singular point. We describe it next. If a solution u(x) is given by its Fourier series $u(x) = \sum_{j=1}^{\infty} \xi_j \varphi_j$, we call $U_n = (\xi_1, \xi_2, \dots, \xi_n)$ the *n-signature* of solution, or just *signature* for short. We also represent f(x) by its Fourier series, and rewrite the problem (1.1) as

(1.2)
$$\Delta u + kg(u) = \mu_1^0 \varphi_1 + \dots + \mu_n^0 \varphi_n + e(x) \text{ for } x \in \Omega,$$
$$u = 0 \text{ on } \partial \Omega$$

with $\mu_j^0 = \int_{\Omega} f \varphi_j dx$, and e(x) is the projection of f(x) onto the orthogonal complement to $\varphi_1, \ldots, \varphi_n$. Let us now constrain ourselves to hold the signature U_n fixed (when continuing in k), and in return allow for μ_1, \ldots, μ_n to vary. I.e., we are looking for $(u, \mu_1, \ldots, \mu_n)$ as a function of k, with U_n fixed, solving

(1.3)
$$\Delta u + kg(u) = \mu_1 \varphi_1 + \dots + \mu_n \varphi_n + e(x)$$
 for $x \in \Omega$, $u = 0$ on $\partial \Omega$,
$$\int_{\Omega} u \varphi_i \, dx = \xi_i, \quad i = 1, \dots, n.$$

It turned out that we can continue forward in k this way, so long as

$$(1.4) k \max_{u \in R} g'(u) < \lambda_{n+1}.$$

In the present paper we present a much simplified proof of this result, and generalize it for the case of (i, n) signatures (defined below). Then, we present two new applications.

So suppose the condition (1.4) holds, and we wish to solve the problem (1.2) at some $k = k_0$. We travel in k, from k = 0 to $k = k_0$, on a curve of

fixed signature $U_n = (\xi_1, \xi_2, \dots, \xi_n)$, obtaining a solution (u, μ_1, \dots, μ_n) of (1.3). The right hand side of (1.3) has the first n harmonics different (in general) from the ones we want in (1.2). We now vary U_n . The question is: can we choose U_n to obtain the desired $\mu_1 = \mu_1^0, \dots, \mu_n = \mu_n^0$, and if so, in how many ways? This corresponds to the existence and multiplicity questions for the original problem (1.1). In [10] we obtained this way a unified approach to the well known results of E.M. Landesman and A.C. Lazer [12], A. Ambrosetti and G. Prodi [2], M. S. Berger and E. Podolak [4], H. Amann and P. Hess [1] and D.G. de Figueiredo and W.-M. Ni [7]. We also provided some new results on "jumping nonlinearities", and on symmetry breaking.

Our main new application in the present paper is to unbounded perturbations at resonance, which we describe next. For the problem

$$\Delta u + \lambda_1 u + g(u) = e(x)$$
 on Ω , $u = 0$ on $\partial \Omega$,

with a bounded g(u), satisfying $ug(u) \geq 0$ for all $u \in R$, and $e(x) \in L^{\infty}(\Omega)$ satisfying $\int_{\Omega} e(x)\varphi_1(x) dx = 0$, D.G. de Figueiredo and W.-M. Ni [7] have proved the existence of solutions. R. Iannacci, M.N. Nkashama and J.R. Ward [8] generalized this result to unbounded g(u) satisfying $g'(u) \leq \gamma < \lambda_2 - \lambda_1$ (they can also treat the case $\gamma = \lambda_2 - \lambda_1$ under an additional condition). We consider a more general problem

$$\Delta u + \lambda_1 u + g(u) = \mu_1 \varphi_1 + e(x)$$
 on Ω , $u = 0$ on $\partial \Omega$,

with g(u) and e(x) satisfying the same conditions. Writing $u = \xi_1 \varphi_1 + U$, we show that there exists a continuous curve of solutions $(u, \mu_1)(\xi_1)$, and all solutions lie on this curve. Moreover $\mu_1(\xi_1) > 0$ (< 0) for $\xi_1 > 0$ (< 0) and large. By continuity, $\mu_1(\xi_1^0) = 0$ at some ξ_1^0 . We see that the existence result of R. Iannacci et al [8] corresponds to just one point on this solution curve.

Our second application is to resonance at higher eigenvalues, where we operate with multiple harmonics. We obtain an extension of D.G. de Figueiredo and W.-M. Ni's [7] result to any simple λ_k .

Our approach in the present paper is well suited for numerical computations. We describe the implementation of the numerical computations, and use them to give numerical examples for our results.

2 Preliminary results

Recall that on a smooth bounded domain $\Omega \subset \mathbb{R}^m$ the eigenvalue problem

$$\Delta u + \lambda u = 0$$
 on Ω , $u = 0$ on $\partial \Omega$

has an infinite sequence of eigenvalues $0 < \lambda_1 < \lambda_2 \le \lambda_3 \le \ldots \to \infty$, where we repeat each eigenvalue according to its multiplicity, and the corresponding eigenfunctions we denote φ_k . These eigenfunctions φ_k form an orthogonal basis of $L^2(\Omega)$, i.e., any $f(x) \in L^2(\Omega)$ can be written as $f(x) = \sum_{k=1}^{\infty} a_k \varphi_k$, with the series convergent in $L^2(\Omega)$, see e.g., L. Evans [6]. We normalize $||\varphi_k||_{L^2(\Omega)} = 1$, for all k.

Lemma 2.1 Assume that $u(x) \in L^2(\Omega)$, and $u(x) = \sum_{k=n+1}^{\infty} \xi_k \varphi_k$. Then

$$\int_{\Omega} |\nabla u|^2 \, dx \ge \lambda_{n+1} \int_{\Omega} u^2 \, dx.$$

Proof: Since u(x) is orthogonal to $\varphi_1, \ldots, \varphi_n$, the proof follows by the variational characterization of λ_{n+1} .

In the following linear problem the function a(x) is given, while μ_1, \ldots, μ_n , and w(x) are unknown.

Lemma 2.2 Consider the problem

(2.1)
$$\Delta w + a(x)w = \mu_1 \varphi_1 + \dots + \mu_n \varphi_n, \text{ for } x \in \Omega,$$

$$w = 0 \text{ on } \partial \Omega,$$

$$\int_{\Omega} w \varphi_1 \, dx = \dots = \int_{\Omega} w \varphi_n \, dx = 0.$$

Assume that

(2.2)
$$a(x) < \lambda_{n+1}, \text{ for all } x \in \Omega.$$

Then the only solution of (2.1) is $\mu_1 = \ldots = \mu_n = 0$, and $w(x) \equiv 0$.

Proof: Multiply the equation in (2.1) by w(x), a solution of the problem (2.1), and integrate. Using Lemma 2.1 and the assumption (2.2), we have

$$\lambda_{n+1} \int_{\Omega} w^2 dx \le \int_{\Omega} |\nabla w|^2 dx = \int_{\Omega} a(x) w^2 dx < \lambda_{n+1} \int_{\Omega} w^2 dx.$$

It follows that $w(x) \equiv 0$, and then

$$0 = \mu_1 \varphi_1 + \dots + \mu_n \varphi_n \text{ for } x \in \Omega,$$

 \Diamond

which implies that $\mu_1 = \ldots = \mu_n = 0$.

Corollary 1 If one considers the problem (2.1) with $\mu_1 = \ldots = \mu_n = 0$, then $w(x) \equiv 0$ is the only solution of that problem.

Corollary 2 With $f(x) \in L^2(\Omega)$, consider the problem

$$\Delta w + a(x)w = f(x) \quad \text{for } x \in \Omega,$$

$$w = 0 \quad \text{on } \partial\Omega,$$

$$\int_{\Omega} w\varphi_1 \, dx = \dots = \int_{\Omega} w\varphi_n \, dx = 0.$$

Then there is a constant c, so that the following a priori estimate holds

$$||w||_{H^2(\Omega)} \le c||f||_{L^2(\Omega)}$$
.

Proof: An elliptic estimate gives

$$||w||_{H^2(\Omega)} \le c \left(||w||_{L^2(\Omega)} + ||f||_{L^2(\Omega)} \right).$$

Since the corresponding homogeneous problem has only the trivial solution, the extra term on the right is removed in a standard way.

We shall also need a variation of the above lemma.

Lemma 2.3 Consider the problem $(2 \le i \le n)$

(2.3)
$$\Delta w + a(x)w = \mu_i \varphi_i + \mu_{i+1} \varphi_{i+1} + \dots + \mu_n \varphi_n \text{ for } x \in \Omega,$$

$$w = 0 \text{ on } \partial\Omega,$$

$$\int_{\Omega} w \varphi_i \, dx = \int_{\Omega} w \varphi_{i+1} \, dx = \dots = \int_{\Omega} w \varphi_n \, dx = 0.$$

Assume that

(2.4)
$$\lambda_{i-1} < a(x) < \lambda_{n+1}, \text{ for all } x \in \Omega.$$

Then the only solution of (2.3) is $\mu_i = \ldots = \mu_n = 0$, and $w(x) \equiv 0$.

Proof: Since the harmonics from *i*-th to *n*-th are missing in the solution, we may represent $w = w_1 + w_2$, with $w_1 \in Span\{\varphi_1, \ldots, \varphi_{i-1}\}$, and $w_2 \in Span\{\varphi_{n+1}, \varphi_{n+2}, \ldots\}$. Multiply the equation (2.3) by w_1 , and integrate

$$- \int_{\Omega} |\nabla w_1|^2 dx + \int_{\Omega} a(x)w_1^2 dx + \int_{\Omega} a(x)w_1w_2 dx = 0.$$

Similarly

$$-\int_{\Omega} |\nabla w_2|^2 dx + \int_{\Omega} a(x)w_2^2 dx + \int_{\Omega} a(x)w_1w_2 dx = 0.$$

Subtracting

(2.5)
$$\int_{\Omega} |\nabla w_2|^2 dx - \int_{\Omega} |\nabla w_1|^2 dx = \int_{\Omega} a(x) w_2^2 dx - \int_{\Omega} a(x) w_1^2 dx.$$

By the variational characterization of eigenvalues, the quantity on the left in (2.5) is greater or equal to

$$\lambda_{n+1} \int_{\Omega} w_2^2 dx - \lambda_{i-1} \int_{\Omega} w_1^2 dx,$$

while the one of the on the right is strictly less than the above number, by our condition (2.4). We have a contradiction, unless $w_1 = w_2 \equiv 0$. Then $\mu_i = \ldots = \mu_n = 0$.

Corollary 3 If one considers the problem (2.3) with $\mu_i = \ldots = \mu_n = 0$, then $w(x) \equiv 0$ is the only solution of that problem. Consequently, for the problem

$$\Delta w + a(x)w = f(x) \quad \text{for } x \in \Omega,$$

$$w = 0 \quad \text{on } \partial\Omega,$$

$$\int_{\Omega} w\varphi_i \, dx = \dots = \int_{\Omega} w\varphi_n \, dx = 0.$$

there is a constant c, so that the following a priori estimate holds

$$||w||_{H^2(\Omega)} \le c||f||_{L^2(\Omega)}.$$

3 Continuation of solutions

Any $f(x) \in L^2(\Omega)$ can be decomposed as $f(x) = \mu_1 \varphi_1 + \ldots + \mu_n \varphi_n + e(x)$, with $e(x) = \sum_{j=n+1}^{\infty} e_j \varphi_j$ orthogonal to $\varphi_1, \ldots, \varphi_n$. We consider a boundary value problem

(3.1)
$$\Delta u + kg(u) = \mu_1 \varphi_1 + \ldots + \mu_n \varphi_n + e(x) \text{ for } x \in \Omega,$$
$$u = 0 \text{ on } \partial \Omega.$$

Here $k \geq 0$ is a constant, and $g(u) \in C^1(R)$ is assumed to satisfy

$$(3.2) g(u) = \gamma u + b(u),$$

with a real constant γ , and b(u) bounded for all $u \in R$, and also

(3.3)
$$g'(u) = \gamma + b'(u) \le M, \text{ for all } u \in R,$$

where M > 0 a constant.

If $u(x) \in H^2(\Omega) \cap H_0^1(\Omega)$ is a solution of (3.1), we decompose it as

$$(3.4) u(x) = \sum_{i=1}^{n} \xi_i \varphi_i + U(x),$$

where U(x) is orthogonal to $\varphi_1, \ldots, \varphi_n$ in $L^2(\Omega)$.

For the problem (3.1) we pose an inverse problem: keeping e(x) fixed, find $\mu = (\mu_1, \dots, \mu_n)$ so that the problem (3.1) has a solution of any prescribed n-signature $\xi = (\xi_1, \dots, \xi_n)$.

Theorem 3.1 For the problem (3.1) assume that the conditions (3.2), (3.3) hold, and

$$kM < \lambda_{n+1}$$
.

Then given any $\xi = (\xi_1, \ldots, \xi_n)$, one can find a unique $\mu = (\mu_1, \ldots, \mu_n)$ for which the problem (3.1) has a solution $u(x) \in H^2(\Omega) \cap H^1_0(\Omega)$ of n-signature ξ . This solution is unique. Moreover, we have a continuous curve of solutions $(u(k), \mu(k))$, such that u(k) has a fixed n-signature ξ , for all $0 \le k \le 1$.

Proof: Let $e(x) = \sum_{j=n+1}^{\infty} e_j \varphi_j$. When k = 0, the unique solution of (3.1) of signature ξ is $u(x) = \sum_{j=1}^{n} \xi_j \varphi_j - \sum_{j=n+1}^{\infty} \frac{e_j}{\lambda_j} \varphi_j$, corresponding to $\mu_j = -\lambda_j \xi_j$, $j = 1, \ldots, n$. We shall use the implicit function theorem to continue this solution in k. With $u(x) = \sum_{i=1}^{n} \xi_i \varphi_i + U(x)$, we multiply the equation (3.1) by φ_i , and integrate

(3.5)
$$\mu_i = -\lambda_i \xi_i + k \int_{\Omega} g\left(\Sigma_{i=1}^n \xi_i \varphi_i + U\right) \varphi_i \, dx, \quad i = 1, \dots, n.$$

Using these expressions in (3.1), we have

$$(3.6) \Delta U + kg \left(\sum_{i=1}^{n} \xi_{i} \varphi_{i} + U \right) - k \sum_{i=1}^{n} \int_{\Omega} g \left(\sum_{i=1}^{n} \xi_{i} \varphi_{i} + U \right) \varphi_{i} dx \varphi_{i} = e(x),$$

$$U = 0 \text{ on } \partial \Omega.$$

The equations (3.5) and (3.6) constitute the classical Lyapunov-Schmidt decomposition of our problem (3.1). Define H_0^2 to be the subspace of $H^2(\Omega) \cap H_0^1(\Omega)$, consisting of functions with zero *n*-signature:

$$H_0^2 = \left\{ u \in H^2(\Omega) \cap H_0^1(\Omega) \mid \int_{\Omega} u\varphi_i \, dx = 0, \ i = 1, \dots, n \right\}.$$

We recast the problem (3.6) in the operator form as

$$F(U, k) = e(x),$$

where $F(U,k): H_0^2 \times R \to L^2(\Omega)$ is given by the left hand side of (3.6). Compute the Frechet derivative

$$F_U(U,k)w = \Delta w + kg' \left(\sum_{i=1}^n \xi_i \varphi_i + U \right) w - \mu_1^* \varphi_1 - \ldots - \mu_n^* \varphi_n ,$$

where $\mu_i^* = k \int_{\Omega} g' \left(\sum_{i=1}^n \xi_i \varphi_i + U \right) w \varphi_i dx$. By Lemma 2.2 the map $F_U(U, k)$ is injective. Since this map is Fredholm of index zero, it is also surjective. The implicit function theorem applies, giving us locally a curve of solutions U = U(k). Then we compute $\mu = \mu(k)$ from (3.5).

To show that this curve can be continued for all k, we only need to show that this curve $(u(k), \mu(k))$ cannot go to infinity at some k, i.e., we need an a priori estimate. Since the n-signature of the solution is fixed, we only need to estimate U. We claim that there is a constant c > 0, so that

$$(3.7) ||U||_{H^2(\Omega)} \le c.$$

We rewrite the equation in (3.6) as

$$\Delta U + k\gamma U = -kb \left(\sum_{i=1}^n \xi_i \varphi_i + U \right) + k \sum_{i=1}^n \int_{\Omega} b \left(\sum_{i=1}^n \xi_i \varphi_i + U \right) \varphi_i \, dx \varphi_i + e(x) \,.$$

By the Corollary 2 to Lemma 2.2, the estimate (3.7) follows, since b(u) is bounded.

Finally, if the problem (3.1) had a different solution $(\bar{u}(k), \bar{\mu}(k))$ with the same signature ξ , we would continue it back in k, obtaining at k = 0 a different solution of the linear problem of signature ξ (since solution curves do not intersect by the implicit function theorem), which is impossible. \diamondsuit

The Theorem 3.1 implies that the value of $\xi = (\xi_1, \dots, \xi_n)$ uniquely identifies the solution pair $(\mu, u(x))$, where $\mu = (\mu_1, \dots, \mu_n)$. Hence, the solution set of (3.1) can be faithfully described by the map: $\xi \in \mathbb{R}^n \to \mu \in \mathbb{R}^n$, which we call the *solution manifold*. In case n = 1, we have the *solution curve* $\mu = \mu(\xi)$, which faithfully depicts the solution set. We show next that the solution manifold is connected.

Theorem 3.2 In the conditions of Theorem 3.1, the solution $(u, \mu_1, \ldots, \mu_n)$ of (3.1) is a continuous function of $\xi = (\xi_1, \ldots, \xi_n)$. Moreover, we can continue solutions of any signature $\bar{\xi}$ to solution of arbitrary signature $\hat{\xi}$ by following any continuous curve in R^n joining $\bar{\xi}$ and $\hat{\xi}$.

Proof: We use the implicit function theorem to show that any solution of (3.1) can be continued in ξ . The proof is essentially the same as for continuation in k above. After performing the same Lyapunov-Schmidt decomposition, we recast the problem (3.6) in the operator form

$$F(U,\xi) = e(x),$$

where $F: H_0^2 \times \mathbb{R}^n \to L^2$ is defined by the left hand side of (3.6). The Frechet derivative $F_U(U,\xi)w$ is the same as before, and by the implicit function theorem we have locally $U=U(\xi)$. Then we compute $\mu=\mu(\xi)$ from (3.5). We use the same a priori bound (3.7) to continue the curve for all $\xi \in \mathbb{R}^n$. (The bound (3.7) is uniform in ξ .)

Given a Fourier series $u(x) = \sum_{j=1}^{\infty} \xi_j \varphi_j$, we call the vector (ξ_i, \dots, ξ_n) to be the (i, n)-signature of u(x). Using Lemma 2.3 instead of Lemma 2.2, we have the following variation of the above result.

Theorem 3.3 For the problem (3.1) assume that the conditions (3.2), (3.3) hold, and

$$\lambda_{i-1} < k\gamma + kg'(u) < \lambda_{n+1}, \text{ for all } u \in R.$$

Then given any $\xi = (\xi_i, ..., \xi_n)$, one can find a unique $\mu = (\mu_i, ..., \mu_n)$ for which the problem

(3.8)
$$\Delta u + kg(u) = \mu_i \varphi_i + \dots + \mu_n \varphi_n + e(x), \text{ for } x \in \Omega,$$
$$u = 0 \text{ on } \partial \Omega$$

has a solution $u(x) \in H^2(\Omega) \cap H^1_0(\Omega)$ of the (i,n)-signature ξ . This solution is unique. Moreover, we have a continuous curve of solutions $(u(k), \mu(k))$, such that u(k) has a fixed (i,n)-signature ξ , for all $0 \le k \le 1$. In addition, we can continue solutions of any (i,n)-signature $\bar{\xi}$ to solution of arbitrary (i,n)-signature $\hat{\xi}$ by following any continuous curve in R^{n-i+1} joining $\bar{\xi}$ and $\hat{\xi}$.

4 Unbounded perturbations at resonance

We use an idea from [8] to get the following a priori estimate.

Lemma 4.1 Let u(x) be a solution of the problem

(4.1)
$$\Delta u + \lambda_1 u + a(x)u = \mu_1 \varphi_1 + e(x) \text{ on } \Omega, u = 0 \text{ on } \partial\Omega,$$

with $e(x) \in \varphi_1^{\perp}$, and $a(x) \in C(\Omega)$. Assume there is a constant γ , so that

$$0 \le a(x) \le \gamma < \lambda_2 - \lambda_1$$
, for all $x \in \Omega$.

Write the solution of (4.1) in the form $u(x) = \xi_1 \varphi_1 + U$, with $U \in \varphi_1^{\perp}$, and assume that

$$(4.2) \xi_1 \mu_1 \le 0.$$

Then there exists a constant c_0 , so that

(4.3)
$$\int_{\Omega} |\nabla U|^2 dx \le c_0, \quad \text{uniformly in } \xi_1 \text{ satisfying } (4.2).$$

Proof: We have

$$(4.4) \Delta U + \lambda_1 U + a(x) (\xi_1 \varphi_1 + U) = \mu_1 \varphi_1 + e(x) \text{ on } \Omega, \quad U = 0 \text{ on } \partial \Omega.$$

Multiply this by $\xi_1 \varphi_1 - U$, and integrate

$$\int_{\Omega} (|\nabla U|^2 - \lambda_1 U^2) dx + \int_{\Omega} a(x) (\xi_1^2 \varphi_1^2 - U^2) dx - \xi_1 \mu_1 = -\int_{\Omega} eU dx.$$

Dropping two non-negative terms on the left, we have

$$(\lambda_2 - \lambda_1 - \gamma) \int_{\Omega} U^2 dx \le \int_{\Omega} \left(|\nabla U|^2 - \lambda_1 U^2 \right) dx - \int_{\Omega} a(x) U^2 dx \le - \int_{\Omega} eU dx.$$

From this we get an estimate on $\int_{\Omega} U^2 dx$, and then on $\int_{\Omega} |\nabla U|^2 dx$. \diamondsuit

Corollary 4 If, in addition, $\mu_1 = 0$ and $e(x) \equiv 0$, then $U \equiv 0$.

We now consider the problem

(4.5)
$$\Delta u + \lambda_1 u + g(u) = \mu_1 \varphi_1 + e(x) \text{ on } \Omega, \ u = 0 \text{ on } \partial \Omega,$$

with $e(x) \in \varphi_1^{\perp}$. We wish to find a solution pair (u, μ_1) . We have the following extension of the result of R. Iannacci et al [8].

Theorem 4.1 Assume that $g(u) \in C^1(R)$ satisfies

$$(4.6) ug(u) > 0 for all u \in R,$$

$$(4.7) g'(u) \le \gamma < \lambda_2 - \lambda_1 for all u \in R.$$

Then there is a continuous curve of solutions of (4.5): $(u(\xi_1), \mu_1(\xi_1))$, $u \in H^2(\Omega) \cap H^1_0(\Omega)$, with $-\infty < \xi_1 < \infty$, and $\int_{\Omega} u(\xi_1) \varphi_1 dx = \xi_1$. This curve exhausts the solution set of (4.5). The continuous function $\mu_1(\xi_1)$ is positive for $\xi_1 > 0$ and large, and $\mu_1(\xi_1) < 0$ for $\xi_1 < 0$ and $|\xi_1|$ large. In particular, $\mu_1(\xi_1^0) = 0$ at some ξ_1^0 , i.e., we have a solution of

$$\Delta u + \lambda_1 u + g(u) = e(x)$$
 on Ω , $u = 0$ on $\partial \Omega$.

Proof: By the Theorem 3.1 there exists a curve of solutions of (4.5) $(u(\xi_1), \mu_1(\xi_1))$, which exhausts the solution set of (4.5). The condition (4.6) implies that g(0) = 0, and then integrating (4.7), we conclude that

(4.8)
$$0 \le \frac{g(u)}{u} \le \gamma < \lambda_2 - \lambda_1, \quad \text{for all } u \in R.$$

Writing $u(x) = \xi_1 \varphi_1 + U$, with $U \in \varphi_1^{\perp}$, we see that U satisfies

$$\Delta U + \lambda_1 U + g(\xi_1 \varphi_1 + U) = \mu_1 \varphi_1 + e(x)$$
 on Ω , $U = 0$ on $\partial \Omega$.

We rewrite this equation in the form (4.1), by letting $a(x) = \frac{g(\xi_1 \varphi_1 + U)}{\xi_1 \varphi_1 + U}$. By (4.8), the Lemma 4.1 applies, giving us the estimate (4.3).

We claim next that $|\mu_1(\xi_1)|$ is bounded uniformly in ξ_1 , provided that $\xi_1\mu_1 \leq 0$. Indeed, let us assume first that $\xi_1 \geq 0$ and $\mu_1 \leq 0$. Then

$$\mu_1 = \int_{\Omega} g(u)\varphi_1 dx = \int_{\Omega} \frac{g(u)}{u} \xi_1 \varphi_1^2 dx + \int_{\Omega} \frac{g(u)}{u} U \varphi_1 dx \ge \int_{\Omega} \frac{g(u)}{u} U \varphi_1 dx,$$

$$|\mu_1| = -\mu_1 \le -\int_{\Omega} \frac{g(u)}{u} U\varphi_1 dx \le \gamma \int_{\Omega} |U\varphi_1| dx \le c_1,$$

for some $c_1 > 0$, in view of (4.8) and the estimate (4.3). The case when $\xi_1 \leq 0$ and $\mu_1 \geq 0$ is similar.

We now rewrite (4.5) in the form

(4.9)
$$\Delta u + a(x)u = f(x) \text{ on } \Omega, \quad u = 0 \text{ on } \partial\Omega$$

with $a(x) = \lambda_1 + \frac{g(u)}{u}$, and $f(x) = \mu_1 \varphi_1 + e(x)$. By above, we have a uniform in ξ_1 bound on $||f||_{L^2(\Omega)}$, and by the Corollary 4 we have uniqueness for (4.9). It follows that

$$||u||_{H^2(\Omega)} \le c||f||_{L^2(\Omega)} \le c_2$$
,

for some $c_2 > 0$.

Assume, contrary to what we wish to prove, that there is a sequence $\{\xi_1^n\} \to \infty$, such that $\mu_1(\xi_1^n) \le 0$. We have

$$u = \xi_1^n \varphi_1 + U,$$

with both u and U bounded in $L^2(\Omega)$, uniformly in ξ_1^n , which results in a contradiction for n large. We prove similarly that $\mu_1(\xi_1) < 0$ for $\xi_1 < 0$ and $|\xi_1|$ large. \diamondsuit

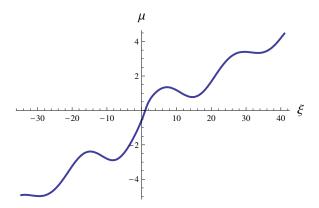


Figure 1: An example for the Theorem 4.1

Example We have solved numerically the problem

$$u'' + u + 0.2 \frac{u^3}{u^2 + 3u + 3} + \sin \frac{1}{2}u = \mu \sin x + 5(x - \pi/2), \quad 0 < x < \pi,$$
$$u(0) = u(\pi) = 0.$$

The Theorem 4.1 applies. Write the solution as $u(x) = \xi \sin x + U(x)$, with $\int_0^{\pi} U(x) \sin x \, dx = 0$. Then the solution curve $\mu = \mu(\xi)$ is given in Figure 1. The picture suggests that the problem has at least one solution for all μ .

We have the following extension of the results of D.G. de Figueiredo and W.-M. Ni [7] and R. Iannacci et al [8], which does not require that $\mu = 0$.

Theorem 4.2 In addition to the conditions of the Theorem 4.1, assume that for some constants $c_0 > 0$ and $p > \frac{3}{2}$

(4.10)
$$ug(u) > c_0 |u|^p$$
, for all $u > 0$ $(u < 0)$.

Then for the problem (4.5) we have $\lim_{\xi_1 \to \infty} \mu(\xi_1) = \infty$ ($\lim_{\xi_1 \to -\infty} \mu(\xi_1) = -\infty$).

Proof: Assume that (4.10) holds for u > 0. By the Theorem 4.1, $\mu(\xi_1) > 0$ for ξ_1 large. Assume, on the contrary, that $\mu(\xi_1)$ is bounded along some sequence of ξ_1 's, which tends to ∞ . Writing $u = \xi_1 \varphi_1 + U$, we conclude from the line following (4.4) that

(4.11)
$$\int_{\Omega} U^2 dx \le c_1 \xi_1 + c_2$$
, for some constants $c_1 > 0$ and $c_2 > 0$.

We have

$$\mu_1 = \int_{\Omega} g(\xi_1 \varphi_1 + U) \varphi_1 dx = \int_{\Omega} \left(g(\xi_1 \varphi_1 + U) - g(\xi_1 \varphi_1) \right) \varphi_1 dx + \int_{\Omega} g(\xi_1 \varphi_1) \varphi_1 dx.$$

Using the mean value theorem, the estimate (4.11), and the condition (4.10), we estimate

$$\mu_1 > c_3 \xi_1^{p-1} - c_4 \xi_1^{1/2} - c_5$$

with some positive constants c_3 , c_4 and c_5 . It follows that $\mu(\xi_1)$ gets large along our sequence, a contradiction. \diamondsuit

Bounded perturbations at resonance are much easier to handle. For example, we have the following result.

Theorem 4.3 Assume that $g(u) \in C^1(R)$ is a bounded function, which satisfies the condition (4.6), and in addition,

$$\lim_{u \to +\infty} g(u) = 0.$$

There is a continuous curve of solutions of (4.5): $(u(\xi_1), \mu_1(\xi_1)), u \in H^2(\Omega) \cap H^1_0(\Omega)$, with $-\infty < \xi_1 < \infty$, and $\int_{\Omega} u(\xi_1) \varphi_1 dx = \xi_1$. This curve exhausts the solution set of (4.5). Moreover, there are constants $\mu_- < 0 < \mu_+$ so that the problem (4.5) has at least two solutions for $\mu \in (\mu_-, \mu_+) \setminus 0$, it has at least one solution for $\mu = \mu_-$, $\mu = 0$ and $\mu = \mu_+$, and no solutions for μ lying outside of (μ_-, μ_+) .

Proof: Follow the proof of the Theorem 4.1. Since g(u) is bounded, we have a uniform in ξ_1 bound on $||U||_{C^1}$, see [7]. Since $\mu_1 = \int_{\Omega} g(\xi_1 \varphi_1 + U)\varphi_1 dx$, we conclude that for ξ_1 positive (negative) and large, μ_1 is positive (negative) and it tends to zero as $\xi_1 \to \infty$ ($\xi_1 \to -\infty$).

Example We have solved numerically the problem

$$u'' + u + \frac{u}{2u^2 + u + 1} = \mu \sin x + \sin 2x, \quad 0 < x < \pi, \quad u(0) = u(\pi) = 0.$$

The Theorem 4.3 applies. Write the solution as $u(x) = \xi \sin x + U(x)$, with $\int_0^{\pi} U(x) \sin x \, dx = 0$. Then the solution curve $\mu = \mu(\xi)$ is given in Figure 2. The picture shows that, say, for $\mu = -0.4$, the problem has exactly two solutions, while for $\mu = 1$ there are no solutions.

We also have a result of Landesman-Lazer type, which also provides some additional information on the solution curve.

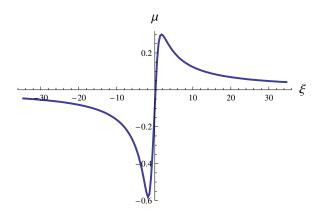


Figure 2: An example for the Theorem 4.3

Theorem 4.4 Assume that the function $g(u) \in C^1(R)$ is bounded, it satisfies (4.7), and in addition, g(u) has finite limits at $\pm \infty$, and

$$g(-\infty) < g(u) < g(\infty)$$
, for all $u \in R$.

Then there is a continuous curve of solutions of (4.5): $(u(\xi_1), \mu_1(\xi_1)), u \in H^2(\Omega) \cap H^1_0(\Omega)$, with $-\infty < \xi_1 < \infty$, and $\int_{\Omega} u(\xi_1)\varphi_1 dx = \xi_1$. This curve exhausts the solution set of (4.5), and $\lim_{\xi_1 \to \pm \infty} \mu_1(\xi_1) = g(\pm \infty) \int_{\Omega} \varphi_1 dx$. I.e., the problem (4.5) has a solution if and only if

$$g(-\infty) \int_{\Omega} \varphi_1 dx < \mu < g(\infty) \int_{\Omega} \varphi_1 dx$$
.

Proof: Follow the proof of the Theorem 4.1. Since g(u) is bounded, we have a uniform bound on U, when we do the continuation in ξ_1 . Hence $\mu_1 \to g(\pm \infty) \int_{\Omega} \varphi_1 dx$, as $\xi_1 \to \pm \infty$, and by continuity of $\mu_1(\xi_1)$, the problem (4.5) is solvable for all μ_1 's lying between these limits. \diamondsuit

Example We have solved numerically the problem

$$u'' + u + \frac{u}{\sqrt{u^2 + 1}} = \mu \sin x + 5\sin 2x - \sin 10x, \quad 0 < x < \pi, \quad u(0) = u(\pi) = 0.$$

The Theorem 4.4 applies. Write the solution as $u(x) = \xi \sin x + U(x)$, with $\int_0^{\pi} U(x) \sin x \, dx = 0$. Then the solution curve $\mu = \mu(\xi)$ is given in Figure 3. It confirms that $\lim_{\xi_1 \to \pm \infty} \mu_1(\xi_1) = \pm \frac{4}{\pi} \left(\frac{4}{\pi} = \int_0^{\pi} \frac{2}{\pi} \sin x \, dx \right)$.

One can append the following uniqueness condition (4.12) to all of the above results. For example, we have the following result.

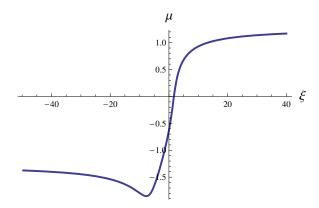


Figure 3: An example for the Theorem 4.4

Theorem 4.5 Assume that the conditions of the Theorem 4.1 hold, and in addition

$$(4.12) g'(u) > 0, for all u \in R.$$

Then

(4.13)
$$\mu'_1(\xi_1) > 0$$
, for all $\xi_1 \in R$.

Proof: Clearly, $\mu'_1(\xi_1) > 0$ at least for some values of ξ_1 . If (4.13) is not true, then $\mu'_1(\xi_1^0) = 0$ at some ξ_1^0 . Differentiate the equation (4.5) in ξ_1 , set $\xi_1 = \xi_1^0$, and denote $w = u_{\xi_1}|_{\xi_1 = \xi_1^0}$, obtaining

$$\Delta w + (\lambda_1 + g'(u)) w = 0$$
 for $x \in \Omega$,
 $w = 0$ on $\partial \Omega$.

Clearly, w is not zero, since it has a non-zero projection on φ_1 $(U_{\xi_1} \in \varphi_1^{\perp})$. On the other hand, $w \equiv 0$, since by the assumption (4.7) we have $\lambda_1 < \lambda_1 + g'(u) < \lambda_2$.

Corollary 5 In addition to the conditions of this theorem, assume that the condition (4.10) holds, for all $u \in R$. Then for any $f(x) \in L^2(\Omega)$, the problem

$$\Delta u + \lambda_1 u + g(u) = f(x)$$
, for $x \in \Omega$, $u = 0$ on $\partial \Omega$

has a unique solution $u(x) \in H^2(\Omega) \cap H^1_0(\Omega)$.

5 Resonance at higher eigenvalues

We consider the problem

(5.1)
$$\Delta u + \lambda_k u + g(u) = f(x) \text{ on } \Omega, \quad u = 0 \text{ on } \partial \Omega,$$

where λ_k is assumed to be a *simple* eigenvalue of $-\Delta$. We have the following extension of the result of D.G. de Figueiredo and W.-M. Ni [7] to the case of resonance at a non-principal eigenvalue.

Theorem 5.1 Assume that $g(u) \in C^1(R)$ is bounded, it satisfies (4.6), and

(5.2)
$$g'(u) \le c_0$$
, for all $u \in R$, and some $c_0 > 0$,

$$\lim_{u \to \infty} \inf g(u) > 0, \quad \lim_{u \to -\infty} \sup g(u) < 0.$$

Assume that $f(x) \in L^2(\Omega)$ satisfies

(5.4)
$$\int_{\Omega} f(x)\varphi_k(x) dx = 0.$$

Then the problem (5.1) has a solution $u(x) \in H^2(\Omega) \cap H_0^1(\Omega)$.

Proof: By (5.2) we may assume that $\lambda_k + g'(u) \leq \lambda_{n+1}$ for some n > k. Expand $f(x) = \mu_1^0 \varphi_1 + \mu_2^0 \varphi_2 + \dots + \mu_n^0 \varphi_n + e(x)$, with $e(x) \in Span\{\varphi_1, \dots, \varphi_n\}^{\perp}$, and $u(x) = \xi_1 \varphi_1 + \xi_2 \varphi_2 + \dots + \xi_n \varphi_n + U(x)$, with $U(x) \in Span\{\varphi_1, \dots, \varphi_n\}^{\perp}$. By (5.4), $\mu_k^0 = 0$. By the Theorem 3.1 for any $\xi = (\xi_1, \dots, \xi_n)$, one can find a unique $\mu = (\mu_1, \dots, \mu_n)$ for which the problem (3.1) has a solution of n-signature ξ , and we need to find a $\xi^0 = (\xi_1^0, \dots, \xi_n^0)$, for which $\mu(\xi^0) = (\mu_1^0, \dots, \mu_{k-1}^0, 0, \mu_{k+1}^0, \dots, \mu_n^0)$.

Multiplying the equation (5.1) by φ_i , and integrating we get

$$(\lambda_k - \lambda_i)\xi_i + \int_{\Omega} g\left(\sum_{i=1}^n \xi_i \varphi_i + U\right) \varphi_i \, dx = \mu_i^0, \quad i = 1, \dots, k-1, k+1, \dots n$$

$$\int_{\Omega} g\left(\sum_{i=1}^{n} \xi_{i} \varphi_{i} + U\right) \varphi_{k} dx = 0.$$

We need to solve this system of equations for (ξ_1, \ldots, ξ_n) . For that we set up a map $T: (\eta_1, \ldots, \eta_n) \to (\xi_1, \ldots, \xi_n)$, by calculating ξ_i from

$$(\lambda_k - \lambda_i)\xi_i = \mu_i^0 - \int_{\Omega} g\left(\sum_{i=1}^n \eta_i \varphi_i + U\right) \varphi_i dx, \quad i = 1, \dots, k-1, k+1, \dots n$$

followed by

$$\xi_k = \eta_k - \int_{\Omega} g \left(\xi_1 \varphi_1 + \dots + \xi_{k-1} \varphi_{k-1} + \eta_k \varphi_k + \xi_{k+1} \varphi_{k+1} + \dots + \xi_n \varphi_n + U \right) \varphi_k dx.$$

Fixed points of this map provide solutions to our system of equations. By the Theorem 3.2, the map T is continuous. Since g(u) is bounded, $(\xi_1, \ldots, \xi_{k-1}, \xi_{k+1}, \ldots, \xi_n)$ belongs to a bounded set. By (4.6) and (5.3), $\xi_k < \eta_k$ for $\eta_k > 0$ and large, while $\xi_k > \eta_k$ for $\eta_k < 0$ and $|\eta_k|$ large. Hence, the map T maps a sufficiently large ball around the origin in R^n into itself, and Brouwer's fixed point theorem applies, giving us a fixed point of T. \diamondsuit

6 Numerical computation of solutions

We describe numerical computation of solutions for the problem

(6.1)
$$u'' + u + g(u) = \mu \sin x + e(x), \quad 0 < x < \pi, \quad u(0) = u(\pi) = 0,$$

whose linear part is at resonance. We assume that $\int_0^{\pi} e(x) \sin x \, dx = 0$. Writing $u(x) = \xi \sin x + U(x)$, with $\int_0^{\pi} U(x) \sin x \, dx = 0$, we shall compute the solution curve of (6.1): $(u(\xi), \mu(\xi))$. (I.e., we write ξ , μ instead of ξ_1 , μ_1 .) We shall use Newton's method to perform continuation in ξ .

Our first task is to implement the "linear solver", i.e., the numerical solution of the following problem: given any $\xi \in R$, and any functions a(x) and f(x), find u(x) and μ solving

(6.2)
$$u'' + a(x)u = \mu \sin x + f(x), \quad 0 < x < \pi,$$
$$u(0) = u(\pi) = 0,$$
$$\int_0^{\pi} u(x) \sin x \, dx = \xi.$$

The general solution of the equation (6.2) is of course

$$u(x) = Y(x) + c_1 u_1(x) + c_2 u_2(x)$$
,

where Y(x) is any particular solution, and u_1, u_2 are two solutions of the corresponding homogeneous equation

(6.3)
$$u'' + a(x)u = 0, \quad 0 < x < \pi.$$

We shall use $Y = \mu Y_1 + Y_2$, where Y_1 solves

$$u'' + a(x)u = \sin x$$
, $u(0) = 0$, $u'(0) = 1$,

and Y_2 solves

$$u'' + a(x)u = f(x), u(0) = 0, u'(0) = 1.$$

Let $u_1(x)$ be the solution of (6.3) with u(0) = 0, u'(0) = 1, and let $u_2(x)$ be any solution of (6.3) with $u_2(0) \neq 0$. The condition u(0) = 0 implies that $c_2 = 0$, i.e., there is no need to compute $u_2(x)$, and we have

(6.4)
$$u(x) = \mu Y_1(x) + Y_2(x) + c_1 u_1(x).$$

We used the NDSolve command in *Mathematica* to calculate u_1 , Y_1 and Y_2 . *Mathematica* not only solves differential equations numerically, but it returns the solution as an interpolated function of x, practically indistinguishable from an explicitly defined function. The condition $u(\pi) = 0$ and the last line in (6.2) imply that

$$\mu Y_1(\pi) + c_1 u_1(\pi) = -Y_2(\pi) ,$$

$$\mu \int_0^{\pi} Y_1(x) \sin x \, dx + c_1 \int_0^{\pi} u_1(x) \sin x \, dx = \xi - \int_0^{\pi} Y_2(x) \sin x \, dx ,$$

Solving this system for μ and c_1 , and using them in (6.4), we obtain the solution of (6.2).

Turning to the problem (6.1), we begin with an initial ξ_0 , and using a step size $\Delta \xi$, on a mesh $\xi_i = \xi_0 + i\Delta \xi$, i = 1, 2, ..., nsteps, we compute the solution of (6.1), satisfying $\int_0^\pi u(x) \sin x \, dx = \xi_i$, by using Newton's method. Namely, assuming that the iterate $u_n(x)$ is already computed, we linearize the equation (6.1) at it, i.e., we solve the problem (6.2) with $a(x) = 1 + g'(u_n(x))$, $f(x) = -g(u_n(x)) + g'(u_n(x))u_n(x) + e(x)$, and $\xi = \xi_i$. After several iterations, we compute $(u(\xi_i), \mu(\xi_i))$. We found that two iterations of Newton's method, coupled with $\Delta \xi$ not too large (e.g., $\Delta \xi = 0.5$), were sufficient for accurate computation of the solution curves. To start Newton's iterations, we used u(x) computed at the preceding step, i.e., $u(\xi_{i-1})$.

We have verified our numerical results by an independent calculation. Once a solution of (6.1) was computed at some ξ_i , we took its initial data u(0) = 0 and u'(0), and computed numerically the solution of the equation in (6.1) with this initial data, let us call it v(x) (using the NDSolve command). We always had $v(\pi) = 0$ and $\int_0^{\pi} v(x) \sin x \, dx = \xi_i$.

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